

3.5] Steady state Response of LTI system with FS Representation



$$x(t) = \sum_{n=-\infty}^{\infty} X_n e^{jn\omega_0 t}, \quad H(\omega) = |H(\omega)| e^{j\theta_H(\omega)}$$

↳ input (complex form of FS)
↳ Frequency response [$\omega = n\omega_0$]

By applying the concept of superposition, we get:-

$$y(t) = \sum_{n=-\infty}^{\infty} X_n |H(n\omega_0)| e^{j(n\omega_0 t + \theta_H(n\omega_0))}$$

$$x(t) = \sum_{n=1}^{\infty} C_n \cos(n\omega_0 t + \theta_n)$$

↳ Sinusoidal form
of FS
(input)

$$H(\omega) = |H(\omega)| e^{j\theta_H(\omega)}$$

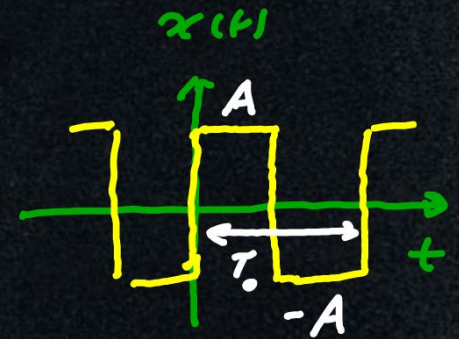
where $\omega = n\omega_0$

By applying the concept of superposition, we get :-

$$y(t) = \sum_{n=1}^{\infty} C_n |H(n\omega_0)| \cos(n\omega_0 t + \theta_n + \theta_H(n\omega_0))$$

EX:- $H(\omega) = \frac{10}{10 + j\omega}$

Find the SS response of $x(t)$



$a_0 = 0, a_n = 0, b_n = 0$ for n even

$b_n = \frac{4A}{\pi n}$ for n odd

$x(t) = \sum_{n=1,3,\dots}^{\infty} b_n \sin(n\omega_0 t)$

$y(t) = \sum_{n=1,3,\dots}^{\infty} |H(n\omega_0)| b_n \sin(n\omega_0 t + \theta_H(n\omega_0))$

$H(\omega) = \frac{10}{\sqrt{100 + \omega^2}} e^{-j \tan^{-1}(\frac{\omega}{10})}$

$$y(t) = \sum_{n=1,3,\dots}^{\infty} \left[\frac{40A}{\sqrt{100+(n\omega_0)^2}} \frac{1}{\pi n} \sin(n\omega_0 t - \tan^{-1}(\frac{n\omega_0}{10})) \right]$$

Write the SS response for $\omega_0 = 10$

$$y(t) = \sum_{n=1,3,\dots}^{\infty} \frac{(4A/\pi)}{\sqrt{1+n^2}} \frac{1}{n} \sin(10nt - \tan^{-1}(n))$$

Exercise: Determine the response of the same system to the input

$$x(t) = 10 \cos(10t + \pi/2) + 20 \sin(30t - \pi/3) + 15 \cos(50t + \pi/4)$$

3.6] RMS calculation Using FS

$$x(t) = a_0 + \sum_{n=1}^{\infty} a_n \cos(n\omega_0 t) + \sum_{n=1}^{\infty} b_n \sin(n\omega_0 t)$$

$$X_{RMS}^2 = \frac{1}{T_0} \int_{T_0} x^2(t) dt = \frac{1}{T_0} \int_{T_0} x(t) x(t) dt$$

$$X_{RMS}^2 = \frac{1}{T_0} \left[\int_{T_0} x(t) \left[a_0 + \sum_{n=1}^{\infty} a_n \cos(n\omega_0 t) + \sum_{n=1}^{\infty} b_n \sin(n\omega_0 t) \right] dt \right]$$

$$X_{RMS}^2 = \frac{1}{T_0} \left[\underbrace{a_0 \int_{T_0} x(t) dt}_{a_0 T_0} + \sum_{n=1}^{\infty} \underbrace{a_n \int_{T_0} x(t) \cos(n\omega_0 t) dt}_{a_n T_0 / 2} + \sum_{n=1}^{\infty} \underbrace{b_n \int_{T_0} x(t) \sin(n\omega_0 t) dt}_{b_n T_0 / 2} \right]$$

$$X_{RMS}^2 = a_0^2 + \frac{1}{2} \sum_{n=1}^{\infty} (a_n^2 + b_n^2) = a_0^2 + \frac{1}{2} \sum_{n=1}^{\infty} C_n^2$$

$$X_{RMS} = \sqrt{a_0^2 + \frac{1}{2} \sum_{n=1}^{\infty} C_n^2}$$

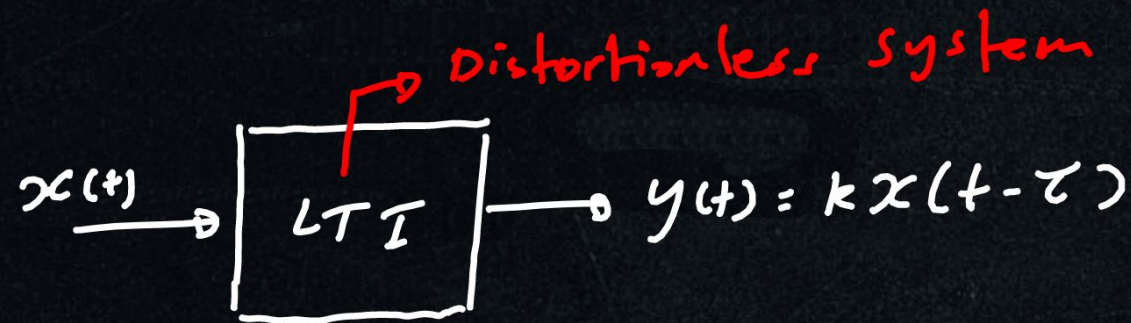
$$X_{RMS} = \sqrt{a_0^2 + \sum_{n=1}^{\infty} C_{RMS,n}^2}$$

where $C_{RMS,k} = \frac{C_k}{\sqrt{2}}$

↳ It is the RMS value of k^{th} sinusoidal harmonic $\left[\frac{C_k}{\sqrt{2}} \cos(k\omega_0 t + \theta_k) \right]$

$$X_{RMS}^2 = a_0^2 + C_{RMS,1}^2 + C_{RMS,2}^2 + \dots$$

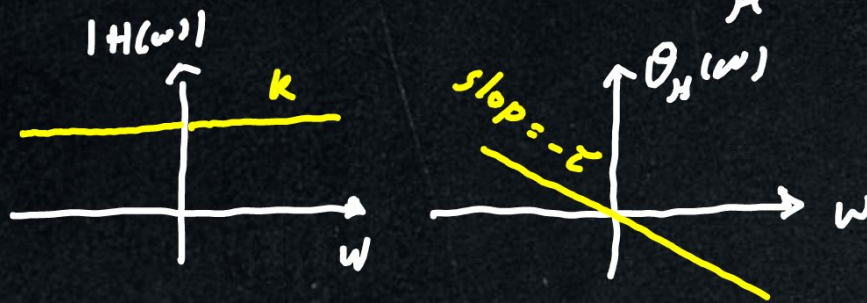
3.7] System and Signal Distortion



$x(t)$ is undistorted if k & τ are constants.

\Rightarrow The frequency response of distortionless system is given by $H(\omega) = k e^{-j\omega\tau}$

$$\Rightarrow |H(\omega)| = k, \quad \theta_H(\omega) = -\omega\tau$$



Types of distortion

Amplitude
distortion

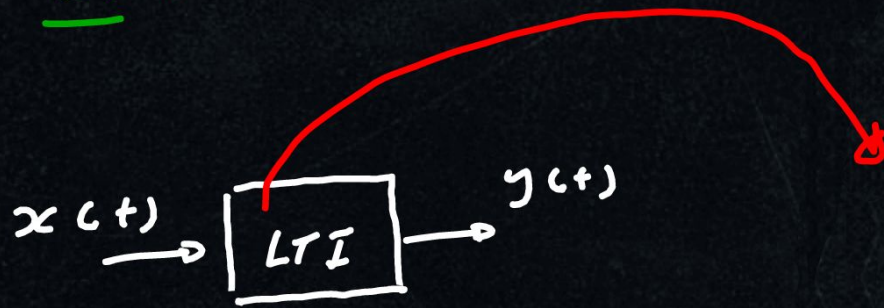
$$|H(\omega)| \neq \text{constant}$$

phase distortion

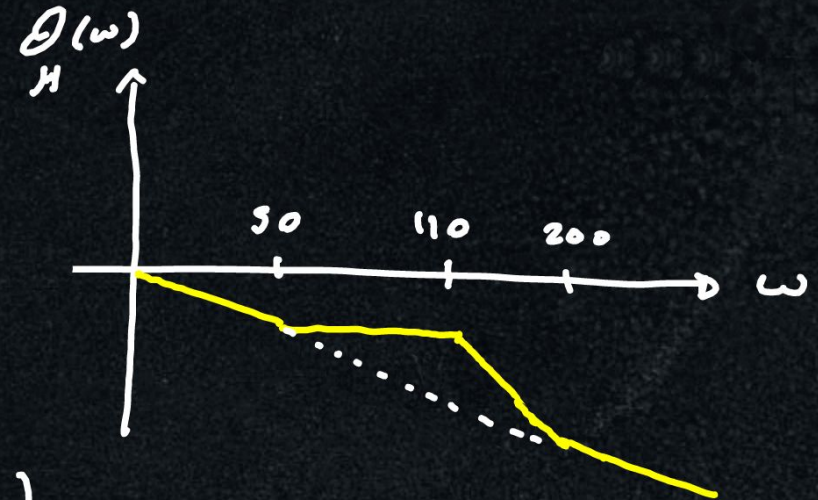
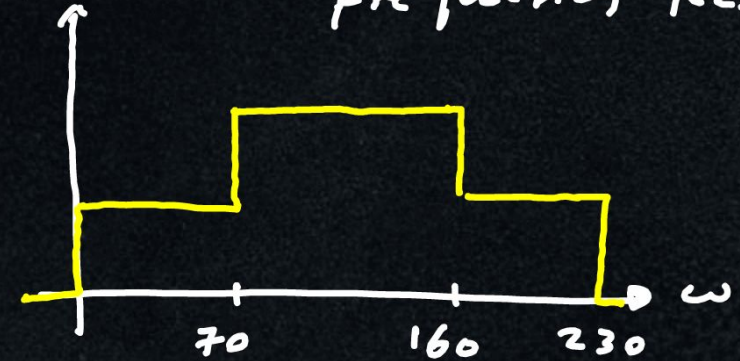
$$\theta_H(\omega) \neq -k\omega$$

It does not follow
a constant slope linear
characteristic

EX :-



$|H(\omega)|$ Frequency Response



1) $x(t) = 10 \cos(10t + \pi/6) + 20 \sin(30t - \pi/3)$

↳ Not distorted

2) $x(t) = 10 \cos(10t + \pi/6) + 20 \sin(60t - \pi/3)$

↳ distorted (phase distortion)

3) $x(t) = 10 \cos(60t + \pi/6) + 20 \sin(90t - \pi/3)$

↳ distorted (Amplitude & phase distortion)

4) $x(t) = 10 \cos(40t + \pi/6) + 20 \sin(215t - \pi/3)$

↳ Not distorted

3.8) Total Harmonic Distortion (THD) and Distortion Factor (DF)

$$THD = \frac{\sqrt{C_{RMS,2}^2 + C_{RMS,3}^2 + C_{RMS,3}^2 + \dots}}{C_{RMS,1}} = \frac{\sqrt{X_{RMS}^2 - C_{RMS,1}^2}}{C_{RMS,1}}$$

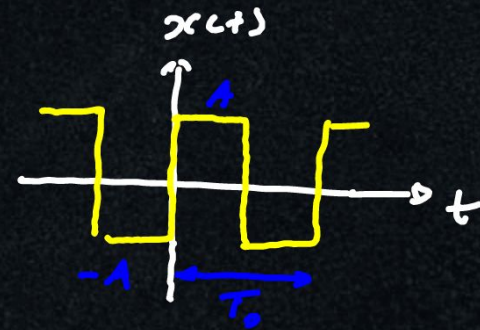
$$DF = \frac{C_{RMS,1}}{X_{RMS}}$$

$C_{RMS,1}$ \rightarrow RMS of the fundamental
 X_{RMS} \rightarrow RMS of the signal

Note: $THD = \sqrt{\left(\frac{1}{DF}\right)^2 - 1} \Rightarrow DF = \sqrt{\frac{1}{1 + (THD)^2}}$

Ex :- Calculate the RMS, THD, and DF of the square wave signal

$$x(t) = \sum_{n=1,3,\dots} C_n \cos(n\omega_1 t + \theta_n)$$



where $C_n = \frac{4A}{n\pi}$, $\theta_n = -\frac{\pi}{2}$

$$X_{RMS} = \sqrt{\frac{1}{T_0} \int_0^{T_0} x^2(t) dt} = \sqrt{\frac{1}{T_0} \int_0^{T_0} A^2 dt} = \boxed{A}$$

$$C_{1,RMS} = \frac{4A}{\sqrt{2}\pi}$$

$$THD = \frac{\sqrt{X_{RMS}^2 - C_{1,RMS}^2}}{C_{1,RMS}} = \sqrt{\frac{\pi^2}{8} - 1} = \boxed{48.3} \%$$

$$DF = \frac{C_{1,RMS}}{X_{RMS}} = \frac{4}{\sqrt{2}\pi} = \boxed{0.9}$$