

3.3 Linear Independence

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Def A minimal spanning set is a spanning set with no unnecessary elements. That is, all elements in the set are needed in order to span the vector space.

Exp Let S be the subset of \mathbb{R}^3 spanned by the vectors

$$\vec{x}_1 = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}^T, \quad \vec{x}_2 = \begin{pmatrix} -2 \\ 3 \\ 1 \end{pmatrix}^T, \quad \vec{x}_3 = \begin{pmatrix} -1 \\ 3 \\ 8 \end{pmatrix}^T$$

→ In fact every vector in S can be represented in terms of x_1 and x_2 since $\vec{x}_3 \in \text{span}(\vec{x}_1, \vec{x}_2)$. That is $\vec{x}_3 = 3\vec{x}_1 + 2\vec{x}_2$ *

• This means that any linear combination of $\vec{x}_1, \vec{x}_2, \vec{x}_3$ can be reduced to a linear combination of x_1 and x_2 since

$$\begin{aligned} \alpha_1 \vec{x}_1 + \alpha_2 \vec{x}_2 + \alpha_3 \vec{x}_3 &= \alpha_1 \vec{x}_1 + \alpha_2 \vec{x}_2 + \alpha_3 (3\vec{x}_1 + 2\vec{x}_2) \\ &= (\alpha_1 + 3\alpha_3) \vec{x}_1 + (\alpha_2 + 2\alpha_3) \vec{x}_2 \end{aligned}$$

• Thus, $S = \text{span}(\vec{x}_1, \vec{x}_2, \vec{x}_3) = \text{span}(\vec{x}_1, \vec{x}_2)$

→ From* $\Rightarrow 3\vec{x}_1 + 2\vec{x}_2 - 1\vec{x}_3 = \vec{0}$.

\Rightarrow Since the three coefficients are non zero

$$\bullet \vec{x}_1 = \frac{-2}{3} \vec{x}_2 + \frac{1}{3} \vec{x}_3 \Rightarrow \text{span}(\vec{x}_1, \vec{x}_2, \vec{x}_3) = \text{span}(\vec{x}_2, \vec{x}_3)$$

$$\bullet \vec{x}_2 = \frac{-2}{3} \vec{x}_1 + \frac{1}{2} \vec{x}_3 \Rightarrow \text{span}(\vec{x}_1, \vec{x}_2, \vec{x}_3) = \text{span}(\vec{x}_1, \vec{x}_3)$$

$$\text{STUDENTS-HUB.com} \quad \vec{x}_3 = 3\vec{x}_1 + 2\vec{x}_2 \Rightarrow \text{span}(\vec{x}_1, \vec{x}_2, \vec{x}_3) = \text{span}(\vec{x}_1, \vec{x}_2)$$

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$$S = \text{span}(\vec{x}_1, \vec{x}_2, \vec{x}_3) = \text{span}(\vec{x}_2, \vec{x}_3) = \text{span}(\vec{x}_1, \vec{x}_3) = \text{span}(\vec{x}_1, \vec{x}_2)$$

→ $\left. \begin{array}{l} \vec{x}_1 \text{ is not multiple of } \vec{x}_2 \\ \vec{x}_2 \text{ " " " " } \vec{x}_3 \\ \vec{x}_3 \text{ " " " " } \vec{x}_1 \end{array} \right\} \Rightarrow \begin{array}{l} \bullet \text{span}(\vec{x}_1), \text{span}(\vec{x}_2) \\ \text{are proper subspaces of} \\ \text{span}(\vec{x}_1, \vec{x}_2) \end{array}$

• ...

Th^{**}

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[1] If $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ span a vector space V and one of these vectors can be written as linear combination of the other $n-1$ vectors, then those $n-1$ vectors span V .

Proof • Let $\vec{v} \in V$ be any element

$$\vec{v} = \alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \dots + \alpha_{n-1} \vec{v}_{n-1} + \alpha_n \vec{v}_n \quad \dots (1)$$

• Assume \vec{v}_n is the vector that can be written as

$$\vec{v}_n = \beta_1 \vec{v}_1 + \beta_2 \vec{v}_2 + \dots + \beta_{n-1} \vec{v}_{n-1}$$

• Hence (1) becomes

$$\vec{v} = \alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \dots + \alpha_{n-1} \vec{v}_{n-1} + \alpha_n (\beta_1 \vec{v}_1 + \beta_2 \vec{v}_2 + \dots + \beta_{n-1} \vec{v}_{n-1})$$

$$= (\alpha_1 + \alpha_n \beta_1) \vec{v}_1 + (\alpha_2 + \alpha_n \beta_2) \vec{v}_2 + \dots + (\alpha_{n-1} + \alpha_n \beta_{n-1}) \vec{v}_{n-1}$$

• Thus, \vec{v} can be written as a linear combination of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_{n-1}$. Hence, these vectors span V .

[2] Given n vectors: $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$.

linearly
Dependent
Definition

It is possible to write one of these vectors as a linear combination of the other $n-1$ vectors if

\exists scalars c_1, c_2, \dots, c_n not all zero s.t

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$$

Proof \Rightarrow Suppose $\vec{v}_n = \alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \dots + \alpha_{n-1} \vec{v}_{n-1} \Rightarrow$

$$\alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \dots + \alpha_{n-1} \vec{v}_{n-1} - \vec{v}_n = \vec{0}$$

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Let $c_i = \alpha_i, i=1, \dots, n-1$ and $c_n = -1 \Rightarrow$

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$$

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\leftarrow If $c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$ and at least one of

$c_i \neq 0$, say c_n , then

$$\vec{v}_n = -\frac{c_1}{c_n} \vec{v}_1 - \frac{c_2}{c_n} \vec{v}_2 - \dots - \frac{c_{n-1}}{c_n} \vec{v}_{n-1}$$

Def

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The vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ in a vector space V are **linearly independent** if $c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$ implies that $c_1 = c_2 = \dots = c_n = 0$.

Note that From Th*

- If $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a minimal spanning set, then $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent.
- If $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent and span V , then $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a minimal spanning set.

* A minimal spanning set is called a **basis** (next section).

Exp 1 The vectors $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ 2 \end{pmatrix}$ are linearly independent

$$\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix} \neq 0$$

since if $c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ then $\begin{matrix} c_1 + c_2 = 0 \\ c_1 + 2c_2 = 0 \end{matrix}$

$$\left[\begin{array}{cc|c} 1 & 1 & 0 \\ 1 & 2 & 0 \end{array} \right]_{R_2 - R_1} \Rightarrow \left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \end{array} \right] \Rightarrow \boxed{c_2 = 0} \Rightarrow \boxed{c_1 = 0}$$

is the only solution.

2 The vectors $\begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix}$ and $\begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}$ are linearly independent

since if $c_1 \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} + c_2 \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ then $\begin{matrix} \boxed{c_1 = 0} \\ c_1 + c_2(2) = 0 \\ \boxed{c_2 = 0} \end{matrix}$

Def

The vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ in a vector space V are **linearly dependent** if \exists scalars c_1, c_2, \dots, c_n not all zero

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$$\text{s.t. } c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n = \vec{0}$$

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Exp 1 The vectors $\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 2 \end{pmatrix}$ are linearly dependent

- since $(2) \begin{pmatrix} 1 \\ 1 \end{pmatrix} + (-1) \begin{pmatrix} 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ and $\boxed{c_1 = 2}, \boxed{c_2 = -1}$
- That is the system $\left[\begin{array}{cc|c} 1 & 2 & 0 \\ 1 & 2 & 0 \end{array} \right]$ has non trivial solution
- That is $\begin{vmatrix} 1 & 2 \\ 1 & 2 \end{vmatrix} = 0$

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 [2] The vectors $\vec{e}_1, \vec{e}_2, \vec{e}_3, \vec{x} = (1, 2, 3)$ are linearly dependent

Since $c_1 \vec{e}_1 + c_2 \vec{e}_2 + c_3 \vec{e}_3 + c_4 \vec{x} = \vec{0}$ implies that

$$c_1 = 1, c_2 = 2, c_3 = 3, c_4 = -1$$

[3] $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 2 & 3 \\ 0 & 2 \end{bmatrix}$ are linearly dependent

since if $c_1 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + c_2 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c_3 \begin{bmatrix} 2 & 3 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ then

$$\begin{aligned} c_1 + 2c_3 &= 0 \\ c_1 + 2c_3 &= 0 \\ c_2 + 3c_3 &= 0 \end{aligned} \Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 2 & 0 \\ 1 & 0 & 2 & 0 \\ 0 & 1 & 3 & 0 \end{array} \right] R_2 - R_1$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 3 & 0 \end{array} \right] \Leftrightarrow \left[\begin{array}{ccc|c} 1 & 0 & 2 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \text{ has non trivial solution } c_1 = 2, c_2 = 3, c_3 = -1$$

Note that $\begin{vmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \end{vmatrix} = 0$

Th Let x_1, x_2, \dots, x_n be n vectors in \mathbb{R}^n . Let $X = [x_1, x_2, \dots, x_n]$.

The vectors x_1, x_2, \dots, x_n are linearly dependent iff X is singular.

Proof • Note that $c_1 x_1 + c_2 x_2 + \dots + c_n x_n = 0$ is equivalent to

$$Xc = 0$$

• This system has non trivial solution iff X is singular.

• Thus, x_1, x_2, \dots, x_n are linearly dependent iff X is singular.

Ex The vectors $\begin{pmatrix} 4 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ -5 \\ 3 \end{pmatrix}$ are linearly dependent

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since $\begin{vmatrix} 4 & 2 & 2 \\ 2 & 3 & -5 \\ 3 & 1 & 3 \end{vmatrix} = 0 \Leftrightarrow$ The solution set = $\{(-2\alpha, 3\alpha, \alpha) : \alpha \in \mathbb{R}\}$

[2] The vectors $x_1 = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}, x_2 = \begin{pmatrix} -2 \\ 3 \\ 1 \end{pmatrix}, x_3 = \begin{pmatrix} 1 \\ 0 \\ 7 \end{pmatrix}$ are linearly dep.

since $\left[\begin{array}{ccc|c} 1 & -2 & 1 & 0 \\ -1 & 3 & 0 & 0 \\ 2 & 1 & 7 & 0 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & -2 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$ This system has non trivial solutions. c_3 is free.

Th Let $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ be vectors in a vector space V .

(65)

The vector $\vec{v} \in \text{Span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)$ can be written uniquely as a linear combination of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ iff $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent.

Proof If $\vec{v} \in \text{Span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)$, then

$$\vec{v} = \alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \dots + \alpha_n \vec{v}_n \quad \text{---- (1)}$$

➔ (By Contradiction) Assume $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent but \vec{v} can be written not uniquely as linear combination of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$. Hence,

$$\vec{v} = \beta_1 \vec{v}_1 + \beta_2 \vec{v}_2 + \dots + \beta_n \vec{v}_n \quad \text{---- (2)}$$

$$\bullet (1) - (2) \Rightarrow \vec{0} = (\alpha_1 - \beta_1) \vec{v}_1 + (\alpha_2 - \beta_2) \vec{v}_2 + \dots + (\alpha_n - \beta_n) \vec{v}_n$$

$$\bullet \text{ since } \vec{v}_1, \vec{v}_2, \dots, \vec{v}_n \text{ are linearly independent} \Rightarrow$$

$$\alpha_1 - \beta_1 = \alpha_2 - \beta_2 = \dots = \alpha_n - \beta_n = 0$$

$$\bullet \text{ Hence, } \alpha_i = \beta_i \text{ for all } i=1, 2, \dots, n \quad \times$$

• This means if $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent, then (1) is the unique representation of the vector \vec{v} .

➔ (By Contradiction) Assume \vec{v} is uniquely written as a linear combination of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ but $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly dependent.

• Hence, there exists c_1, c_2, \dots, c_n not all zero s.t.

$$\vec{0} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n \quad \text{---- (3)}$$

$$\bullet (1) + (3) \Rightarrow$$

$$\vec{v} = (c_1 + \alpha_1) \vec{v}_1 + (c_2 + \alpha_2) \vec{v}_2 + \dots + (c_n + \alpha_n) \vec{v}_n \quad \text{let } \beta_i = c_i + \alpha_i$$
$$= \beta_1 \vec{v}_1 + \beta_2 \vec{v}_2 + \dots + \beta_n \vec{v}_n$$

• Since c_i are not all zero \Rightarrow at least one $\beta_i \neq \alpha_i$ for some i
 $\Rightarrow \vec{v}$ can be written not uniquely as a linear combination of $\vec{v}_1, \dots, \vec{v}_n$ \times

Exp show that $p_1(x) = x^2 - 2x + 3$
 $p_2(x) = 2x^2 + x + 8$ are linearly dependent.
 $p_3(x) = x^2 + 8x + 7$
(The Vector space P_n)

Let $c_1 p_1(x) + c_2 p_2(x) + c_3 p_3(x) = 0 = 0x^2 + 0x + 0$

$c_1 [x^2 - 2x + 3] + c_2 [2x^2 + x + 8] + c_3 [x^2 + 8x + 7] = 0$

$(c_1 + 2c_2 + c_3)x^2 + (-2c_1 + c_2 + 8c_3)x + (3c_1 + 8c_2 + 7c_3) = 0$

$c_1 + 2c_2 + c_3 = 0$
 $-2c_1 + c_2 + 8c_3 = 0$
 $3c_1 + 8c_2 + 7c_3 = 0$

\Rightarrow The coefficient matrix is singular since

$\begin{vmatrix} 1 & 2 & 1 \\ -2 & 1 & 8 \\ 3 & 8 & 7 \end{vmatrix} = 0$

Hence, p_1, p_2, p_3 are linearly dependent. since nontrivial solution exists.

solution set = $\{(3\alpha, -2\alpha, \alpha) : \alpha \in \mathbb{R}\}$

How to determine whether f_1, f_2, \dots, f_n in $C^{(n-1)}[a, b]$ are linearly independent? (The Vector space $C^{(n-1)}[a, b]$)

* If $f_1(x), f_2(x), \dots, f_n(x)$ are linearly dependent, then \exists scalars c_1, c_2, \dots, c_n not all zero s.t

$\forall x \in [a, b] \Rightarrow c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0$ since f exists $^{(n-1)}$
 $c_1 f_1'(x) + c_2 f_2'(x) + \dots + c_n f_n'(x) = 0$
 \vdots
 $c_1 f_1^{(n-1)}(x) + c_2 f_2^{(n-1)}(x) + \dots + c_n f_n^{(n-1)}(x) = 0$

Hence, the system $\begin{bmatrix} f_1(x) & f_2(x) & \dots & f_n(x) \\ f_1'(x) & f_2'(x) & \dots & f_n'(x) \\ \vdots & \vdots & \ddots & \vdots \\ f_1^{(n-1)}(x) & f_2^{(n-1)}(x) & \dots & f_n^{(n-1)}(x) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$ will have non trivial solution

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Thus, If f_1, f_2, \dots, f_n are linearly dependent in $C^{(n-1)}[a, b]$,
* remark Then $\forall x \in [a, b]$, the coefficient matrix A is singular ($|A| = 0$).

Def Let f_1, f_2, \dots, f_n be functions in $C^{(n-1)}[a, b]$. We define the **Wronskian** of f_1, f_2, \dots, f_n on $[a, b]$ by

$$W(f_1, f_2, \dots, f_n)(x) = \begin{vmatrix} f_1(x) & f_2(x) & \dots & f_n(x) \\ f_1'(x) & f_2'(x) & & f_n'(x) \\ \vdots & \vdots & & \vdots \\ f_1^{(n-1)}(x) & f_2^{(n-1)}(x) & & f_n^{(n-1)}(x) \end{vmatrix}$$

Note that **Remark*** means that:

If f_1, f_2, \dots, f_n are linearly dependent, then

$$W(f_1, f_2, \dots, f_n)(x) = 0 \text{ for every } x \in [a, b]$$

Th³ Let f_1, f_2, \dots, f_n be elements of $C^{(n-1)}[a, b]$.

If there exist a point $x_0 \in [a, b]$ s.t. $W(f_1, f_2, \dots, f_n)(x_0) \neq 0$,

then f_1, f_2, \dots, f_n are linearly independent.

Proof (by contradiction)

If f_1, f_2, \dots, f_n are linearly dependent, then the coefficient matrix is singular $\forall x \in [a, b]$. That is,

$$W(f_1, f_2, \dots, f_n)(x) = 0 \quad \forall x \in [a, b]. \quad \text{X since } \exists x_0 \in [a, b] \text{ s.t. } W(f_1, f_2, \dots, f_n)(x_0) \neq 0.$$

Ex Are e^x and e^{-x} linearly independent in $C(-\infty, \infty)$

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$$W(e, e^{-}) = \begin{vmatrix} e^x & e^{-x} \\ e^x & -e^{-x} \end{vmatrix} = -1 - 1 = -2 \neq 0$$

Hence, they are linearly independent.

Note If f_1, f_2, \dots, f_n are linearly independent in $C^{(n-1)}[a, b]$,
then f_1, f_2, \dots, f_n are linearly independent in $C[a, b]$

Exp Are $x^2, x|x|$ linearly independent in $C[-1,1]$ (68)

- Both functions are in $C^1[-1,1]$ since $x|x| = \begin{cases} x^2, & x \geq 0 \\ -x^2, & x < 0 \end{cases}$
- Hence, $w(x^2, x|x|) = \begin{vmatrix} x^2 & x|x| \\ 2x & 2|x| \end{vmatrix} = 0$ $\left\{ \begin{aligned} (x|x|)' &= \begin{cases} 2x, & x \geq 0 \\ -2x, & x < 0 \end{cases} \\ &= 2|x| \end{aligned} \right.$
- No information can be concluded since $w=0$

so, we let $c_1 x^2 + c_2 x|x| = 0 \quad \forall x \in [-1,1]$

$$\left. \begin{aligned} \text{when } x=1 &\Rightarrow c_1 + c_2 = 0 \\ x=-1 &\Rightarrow c_1 - c_2 = 0 \end{aligned} \right\} \Rightarrow c_1 = c_2 = 0 \text{ is the only solution.}$$

- Hence, x^2 and $x|x|$ are linearly independent.

Remark ^{**} ① If $w(f_1, f_2, \dots, f_n) = 0$, then f_1, f_2, \dots, f_n may be linearly independent or linearly dependent.

② If $w(f_1, f_2, \dots, f_n) \neq 0$, then f_1, f_2, \dots, f_n are linearly indep.

Exp Show that $x+2, x^2-1$ are linearly independent

$$w(x+2, x^2-1) = \begin{vmatrix} x+2 & x^2-1 \\ 1 & 2x \end{vmatrix} = 2x^2 + 4x - x^2 + 1 = x^2 + 4x + 1$$

- since $x+2$ and x^2-1 are continuous at $x=0$ and

$$w(x+2, x^2-1)(0) = (0)^2 + 4(0) + 1 = 1 \neq 0, \text{ it follows that}$$

$x+2, x^2-1$ are linearly independent by Th³