

3.5

Change of Basis

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Def. Let V be a vector space and $E = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ be an ordered basis for V .

If \vec{w} is any element in V , then $\vec{w} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$ where c_1, c_2, \dots, c_n are scalars.

→ Thus, we can associate a unique vector of scalars

$$\vec{c} = (c_1, c_2, \dots, c_n) \in \mathbb{R}^n \text{ for each } \vec{w} \in V.$$

→ The vector \vec{c} is called the coordinate vector of \vec{w} with respect to the ordered basis E , and is denoted by $\vec{c} = [w]_E$, and the c_i 's are called the coordinates of \vec{w} relative to E .

* We can also compute the coordinate vector as

$$\text{follows: } \vec{c} = [w]_E = \vec{E}^{-1} w = [\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n]^{-1} \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{bmatrix} = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$$

where \vec{E}^{-1} is the transition matrix from the basis $\{\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n\}$ to the basis $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\} = E$.

Ex Let $\vec{u}_1 = (3, 2)$ and $\vec{u}_2 = (1, 1)$. Find the coordinates of

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$\vec{x} = (7, 4)$ w.r.t \vec{u}_1 and \vec{u}_2 .

$$\vec{c} = [x]_{\vec{u}} = \vec{U}^{-1} \vec{x} = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 7 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 7 \\ 4 \end{bmatrix} = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$$

This means $x = \begin{pmatrix} 7 \\ 4 \end{pmatrix} = (3) \begin{pmatrix} 3 \\ 2 \end{pmatrix} + (-2) \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\vec{x} = 3 \vec{u}_1 - 2 \vec{u}_2 \quad \checkmark$$

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Remarks:

① The transition matrix from $\{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n\}$ to $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$
 is $S = \bar{V}^{-1}U$ where
 $U = (u_1 \ u_2 \ \dots \ u_n)$ and $V = (v_1 \ v_2 \ \dots \ v_n)$

② $= \quad = \quad = \quad = \quad \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ to $\{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n\}$
 is $S = U^{-1}\bar{V}$. That is, the transition matrix is nonsingular.

Ex • The transition matrix from the basis $\{(1,1)^T, (-1,1)^T\}$ to
 the basis $\{e_1, e_2\}$ is

$$S = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

$\circ = \quad = \quad = \quad = \quad = \quad \{e_1, e_2\}$ to $\{(1,1)^T, (-1,1)^T\}$ is

$$\bar{S} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

$\circ = \quad = \quad = \quad = \quad = \quad \{(3,2)^T, (4,3)^T\}$ to $\{(1,1)^T, (-1,1)^T\}$ is

$$\bar{S} = \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 3 & 4 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 3 & 4 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} \frac{5}{2} & \frac{7}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

Ex Let $\vec{b}_1 = (1, -1)$ and $\vec{b}_2 = (-2, 3)$. Find the coordinates of

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$$c = [x]_B = \bar{B}^{-1}X = \begin{bmatrix} 1 & -2 \\ -1 & 3 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 7 \\ 3 \end{bmatrix}$$

That is $\vec{x} = 7\vec{b}_1 + 3\vec{b}_2$

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix} = 7 \begin{pmatrix} 1 \\ -1 \end{pmatrix} + 3 \begin{pmatrix} -2 \\ 3 \end{pmatrix}$$

Ex Find the transition matrix to the change of basis from $V = \left\{ \begin{pmatrix} 5 \\ 2 \end{pmatrix}, \begin{pmatrix} 7 \\ 3 \end{pmatrix} \right\}$ to $U = \left\{ \begin{pmatrix} 3 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$

$$S = U^{-1}V = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 5 & 7 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 4 \\ -4 & -5 \end{bmatrix}$$

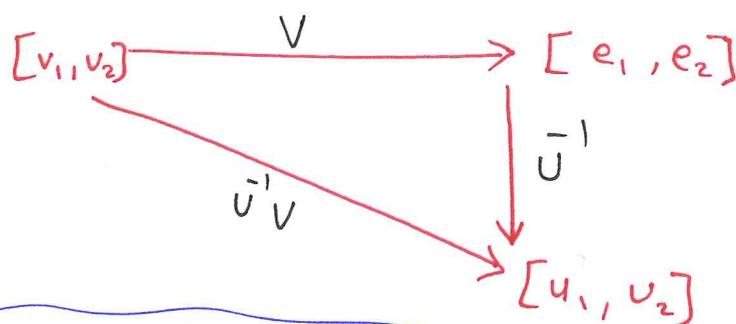
Note that the change of basis from $\{\vec{v}_1, \vec{v}_2\}$ to $\{\vec{u}_1, \vec{u}_2\}$ can be viewed as two step process:

① Change from $\{\vec{v}_1, \vec{v}_2\}$ to $\{\vec{e}_1, \vec{e}_2\}$ and

in this case the transition matrix is V

② Change from $\{\vec{e}_1, \vec{e}_2\}$ to $\{\vec{u}_1, \vec{u}_2\}$

in this case the transition matrix is U^{-1}



Ex Let $E = [v_1, v_2, v_3] = [(1, 1, 1)^T, (2, 3, 2)^T, (1, 5, 4)^T]$ and $F = [u_1, u_2, u_3] = [(1, 1, 0)^T, (1, 2, 0)^T, (1, 2, 1)^T]$.

① Find the transition matrix from E to F

$$S = F^{-1}E = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 2 & 1 \\ 1 & 3 & 5 \\ 1 & 2 & 4 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 1 & 3 & 5 \\ 1 & 2 & 4 \end{bmatrix}$$

~~STUDENTS-HUB.COM~~ $\vec{x} = 3\vec{v}_1 + 2\vec{v}_2 - \vec{v}_3$ and $\vec{y} = \vec{v}_1 - 3\vec{v}_2 + 2\vec{v}_3$ and Uploaded By: anonymous

Find the coordinates of \vec{x} and \vec{y} w.r.t the ordered basis F .

$$[x]_F = Sx = \begin{bmatrix} 1 & 1 & -3 \\ -1 & 1 & 0 \\ 1 & 2 & 4 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 8 \\ -5 \\ 3 \end{bmatrix} \quad \text{This means: } \vec{x} = 3\vec{u}_1 + 2\vec{u}_2 - \vec{u}_3 = 8\vec{u}_1 - 5\vec{u}_2 + 3\vec{u}_3$$

$$[y]_F = Sy = \begin{bmatrix} 1 & 1 & -3 \\ -1 & 1 & 0 \\ 1 & 2 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ -3 \\ 2 \end{bmatrix} = \begin{bmatrix} -8 \\ 2 \\ 3 \end{bmatrix} \quad \vec{y} = \vec{u}_1 - 3\vec{u}_2 + 2\vec{u}_3 = -8\vec{u}_1 + 2\vec{u}_2 + 3\vec{u}_3$$

Expt ① Find the transition matrix representing the change of coordinates on P_3 from the ordered basis $[1, x, x^2]$ to the ordered basis $[1, 2x, 4x^2 - 2]$

\Rightarrow Since $[1, x, x^2]$ is the standard basis for P_3 , it is easier to find the transition matrix from

$[1, 2x, 4x^2 - 2]$ to $[1, x, x^2]$:

$$\begin{aligned} 1 &= 1 + 0x + 0x^2 \\ 2x &= 0 + 2x + 0x^2 \\ 4x^2 - 2 &= -2 + 0x + 4x^2 \end{aligned}$$

\Rightarrow Hence, the transition matrix $S = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$

$\Rightarrow S^{-1}$ is the transition matrix from $[1, x, x^2]$ to $[1, 2x, 4x^2 - 2]$:

$$S^{-1} = \begin{bmatrix} 1 & 0 & \frac{1}{2} \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix}$$

② If $p(x) = a + bx + cx^2$, then find the coordinates of $p(x)$ w.r.t the basis $[1, 2x, 4x^2 - 2] = F$

$$[p(x)]_F = S^{-1} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{bmatrix} 1 & 0 & \frac{1}{2} \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a + \frac{c}{2} \\ \frac{b}{2} \\ \frac{c}{4} \end{pmatrix}$$

$$= \left(a + \frac{c}{2}\right)(1) + \left(\frac{b}{2}\right)(2x) + \left(\frac{c}{4}\right)(4x^2 - 2)$$

Note ① If V is any n -dimensional vector space, then it is possible to change from one basis to another using a transition matrix $S_{n \times n}$. Moreover, $S_{n \times n}$ is nonsingular.

② Any nonsingular matrix can be thought as a transition matrix.

Ex Let $\vec{y} = (2, 1)$ and $\vec{z} = (1, 4)$.

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→ The vectors \vec{y} and \vec{z} are linearly independent

→ Hence, they form a basis for \mathbb{R}^2

⇒ Let $\vec{x} = (7, 7) \in \mathbb{R}^2 \Rightarrow \vec{x}$ can be written as a linear combination of \vec{y} and \vec{z} :

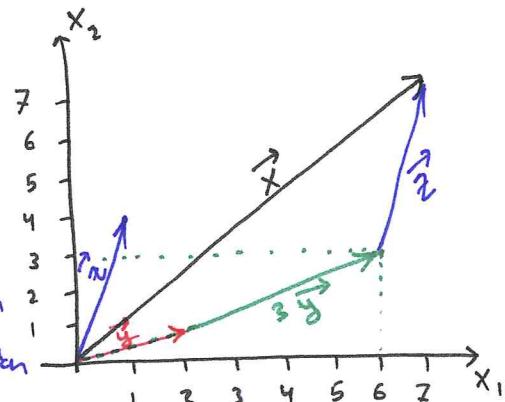
→ In fact: $\vec{x} = 3\vec{y} + \vec{z}$

→ This means that the coordinate vector of $\vec{x} = (7, 7)$ w.r.t the basis $[\vec{y}, \vec{z}]$ is $\vec{c} = (3, 1)$ ordered

$$\text{That is } [\vec{x}]_{[\vec{y}, \vec{z}]} = \begin{bmatrix} 2 & 1 \\ 1 & 4 \end{bmatrix}^{-1} \begin{bmatrix} 7 \\ 7 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 4 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 7 \\ 7 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

→ Geometrically:

→ The coordinate vector $\vec{c} = (3, 1)$ specifies how to get from the origin to the point $(7, 7)$ by moving first in the direction of \vec{y} and then in the direction of \vec{z} .



← If instead, we treat \vec{z} as the first basis and \vec{y} as the second basis then the coordinate vector becomes

$$c = \begin{bmatrix} 1 & 2 \\ 4 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 7 \\ 7 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 1 & -2 \\ -4 & 1 \end{bmatrix} \begin{bmatrix} 7 \\ 7 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$\text{That is } \vec{x} = \vec{z} + 3\vec{y}$$

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* Hence, ordered basis is important since the coordinate vector w.r.t the ordered basis $[\vec{y}, \vec{z}]$ is $(3, 1)^T$ and

the coordinate vector w.r.t the ordered basis $[\vec{z}, \vec{y}]$ is $(1, 3)^T$.

