

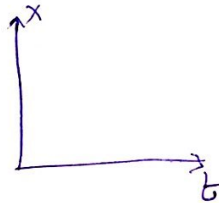
Motion in a straight lines

- Displacement = $\Delta x = x_2 - x_1$ **vector quantity**
- Magnitude = $|\Delta x|$
- has 2 features: $\begin{cases} \text{direction} \\ \text{Magnitude} \end{cases}$

- Distance Traveled: measured along the actual path

- Average velocity & Average speed
- $\downarrow$
 (vector) velocity = $\frac{\Delta x}{\Delta t}$ $\begin{matrix} \text{pos} \rightarrow V+ \\ \text{neg} \rightarrow V- \\ \Delta t \rightarrow \text{always} + \end{matrix}$
- $\rightarrow$ speed = $\frac{\text{distance}}{\text{time}}$ (scalars)
 $\rightarrow$ no algebraic sign = $\frac{d_1 + d_2}{t_1 + t_2}$

Velocity in a graph = The slope of the line that connects 2 points (x_1, t_1) and (x_2, t_2)



V.I.N

our bodies react to accelerations but not to velocities

- Instantaneous velocity and speed

$V_{\text{Inst}} = \frac{dx}{dt}$ The slope of $x(t)$ curve at that point

sign of $\vec{v}$ and $\vec{a}$ the same $\rightarrow$ acceleration

- vector • Average Acceleration

acc = $\frac{\Delta v}{\Delta t}$ = slope

acc Inst = $\frac{dv}{dt}$ = slope at that point

$\Delta x \rightarrow v \rightarrow \text{acc} \xrightarrow{\text{steepness}}$
 $\text{acc} \rightarrow v \rightarrow \Delta x \xrightarrow{\text{distance}}$

Physics of Motion

- Kinematics: describes change in motion
- Dynamics: explains the effect

Motion

$\downarrow$ Translation $\downarrow$ Vibration $\downarrow$ Rotation

Ahmed Etaini

Acceleration

$$V +$$

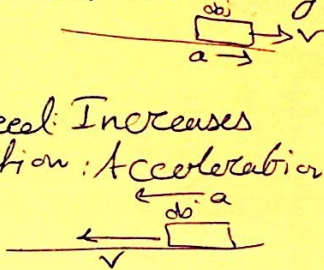
Motion: Accelerating

Motion: Accelerating

 γ_-

Notion: Acceleration

Notion: Acceleration



Deceleration

$$V +$$

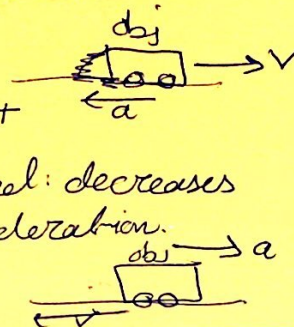
Deceleration

Deceleration

V-

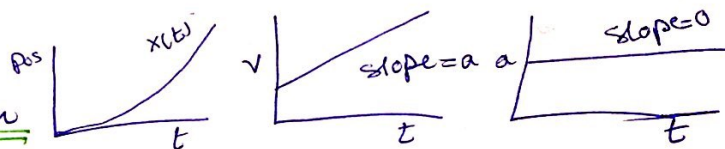
Deceleration

Deceleration



* The Human body has an awareness of acceleration
But not the velocity

Constant acceleration



$$\bar{a} = \frac{v_2 - v_1}{t_2 - 0}$$

$$v_2 - v_1 = at_2$$

$$V_2 = V_1 + at_2$$

1 we us
This if we
don't have
 $\Delta x(x - x_0)$

$$\bar{V} = \frac{V_1 + V_2}{2}$$

$$= \frac{v_1 + v_1 + at}{2}$$

$$\overline{V} = V_1 + a\left(\frac{t}{2}\right)$$

Const acc

$$\overline{V} = \frac{V_1 + V_2}{2}$$

$$\Delta V = \frac{V - t}{\Delta t} \sim \sim \sim$$

$$\Delta x = v t = \left(\frac{v_1 + v_2}{2} \right) \left(\frac{v_2 - v_1}{a} \right)$$

$$\Delta x = \frac{V_1^2 - V_2^2}{2a}$$

$$V_2^2 = V_1^2 + 2a\Delta x$$

$$\Delta x = \bar{v}t$$

$$= \frac{1}{2}(v_1 + v_2 + at)t$$

$$\Delta x = v_1 t + \frac{1}{2} a t^2$$

$$\frac{V_1 + V_2}{2}$$

variable account

Acceleration

Acceleration $\xrightarrow{\int a(t)} \text{velocity}$
 $\frac{dv}{dt} = a(t) \quad \cdot \quad v(t)$

$\xrightarrow{v(t)}$ position $x(t)$

4. $\sim \sim \sim$
 $\sim \sim \sim t$

Aaa Etaiwi