# Storage and Indexing



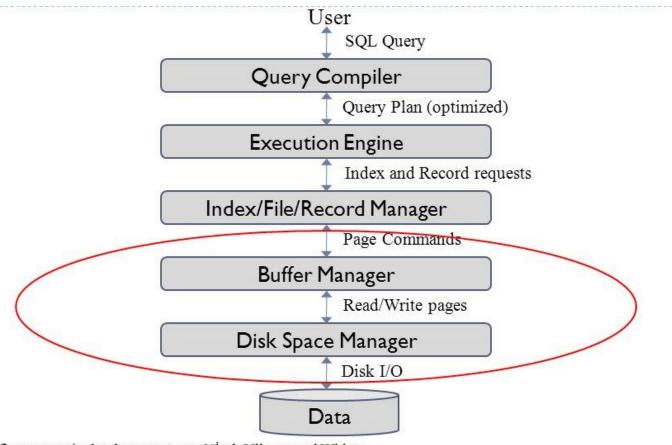
#### **Motivation**

- DBMS stores vast quantities of data
- Data is stored on external storage devices and fetched into main memory as needed for processing
- Page is unit of information read from or written to disk. (in DBMS, a page may have size 8KB or more).
- Data on external storage devices :
  - Disks: Can retrieve random page at fixed cost (I/O operations).
     But reading several consecutive pages is much cheaper (i.e. faster) than reading them in random order
  - Tapes: Can only read pages in sequence.
     Cheaper than disks; used for archival storage.
- Cost of page I/O dominates cost of typical database operations





#### Architecture of a DBMS

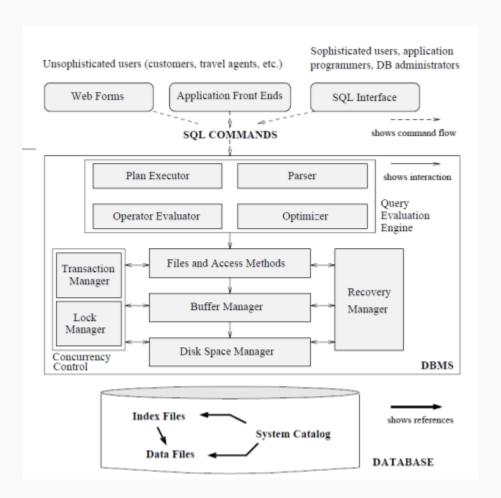


A first course in database systems, 3rd ed, Ullman and Widom



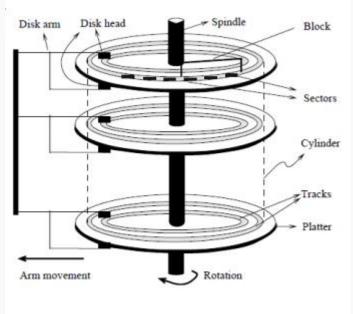
#### introduction

- □ **DBMS** abstracts data as a collection of **records** stored in a **file**.
- ☐ A file is a set of **pages**, each contain certain **set of records**.
- ☐ The **files layer** is responsible or data organization for fast data retrieval.
- ☐ File organization: a way of organizing records in a file.
- ☐ Each file organization makes certain operations efficient, but other operations expensive



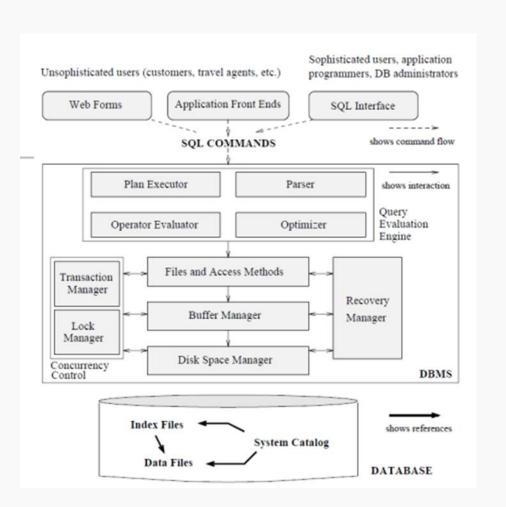


- ☐ **Hard disks** are the primary storage devices for DBMS
- ☐ The **taps** are used for archiving.
- ☐ The unit of information read from or written from disk is a page.
- □ A page is **typically 4KB** or **8KB**
- ☐ The cost of page I/O is the **most expensive** operation.
- □ Disks have **fixed cost per page**.
- ☐ Each record in a file has a unique identifier called rid.
- ☐ Using the **rid**, we can identify the **page address**





- ☐ The **buffer manager** is responsible for loading a page into memory.
- □When the files layer wants to access a certain page, it asks the **buffer manager** to load it into memory (if it is not already there)
- ☐ Space on disk is managed by **disk space** manager.





- File organization:
  - Method of arranging a file of records on external storage.
  - Record id (rid) is sufficient to physically locate record
  - Indexes are data structures that allow us to find the record ids of records with given values in index search key fields
- Architecture: Buffer manager stages pages from external storage to main memory buffer pool.



# Multiple File Organizations

Many alternatives exist, each good in some situations and not so good in others

#### Heap Files:

- is the simplest file organization: records are stored randomly across the pages.
- Suitable when typical access is a full scan of all records
- Unordered collection of records
- Add/Remove records: Easy (Cost?)

#### Sorted Files:

- Best for retrieval in search key order, or a range of records is needed
- Arrange and store collection of records in sorted manner.
- Add/Remove records: Easy or not (Cost?)
- Clustered Files & Indexes: Group data into block to enable fast lookup and efficient modifications. (More on this soon ...)
  An index is a data structure that allows fast retrieval of data records.

We can create several indexes for same data file, each with

-s-different search key.

# **Bigger Questions**

- What is the "best" file organization?
  - Depends on access patterns ...
  - How? What are they?
- Can we be quantitative about tradeoffs?
  - Better → How much?

# Goals for Today

- Big picture overheads for data access
  - Then estimate cost in a principled way
- Foundation for query optimization
  - Can't choose the fastest scheme without an estimate of speed!



# Cost Model & Analysis



# Cost Model for Analysis

- B: The number of data blocks
- R: Number of records per block
- D: (Average) time to read/write disk block
- Average case analysis for uniform random workloads
- We will ignore
  - Sequential vs Random I/O
  - Pre-fetching
  - Any in-memory costs

Good enough to show the overall trends!



# More Assumptions

- Single record insert and delete
- Equality selection exactly one match
- For Heap Files:
  - Insert always appends to end of file.
- For Sorted Files:
  - Files compacted after deletions.
  - Sorted according to search key



# Heap Files & Sorted Files

## Heap File



#### Sorted File



- **B:** The number of data blocks = 5
- R: Number of records per block = 2
- **D:** (Average) time to read/write disk block = 5ms



	Heap File	Sorted File
Scan all records		
Equality Search		
Range Search		
Insert		
Delete		

- **B:** The number of data blocks
- R: Number of records per block
- **D:** Average time to read/write disk block



	Heap File	Sorted File
Scan all records		
Equality Search		
Range Search		
Insert		
Delete		

- **B:** The number of data blocks
- R: Number of records per block
- **D:** Average time to read/write disk block



## Scan All Records

## Heap File



#### Sorted File



- **B:** The number of data blocks
- R: Number of records per block
- **D:** Average time to read/write disk block

Pages touched: ?

Time to read the record: ?



	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search		
Range Search		
Insert		
Delete		

- **B:** The number of data blocks
- R: Number of records per block
- D: Average time to read/write disk block



	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search		
Range Search		
Insert		
Delete		

- **B:** The number of data blocks
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- D: Average time to read/write disk block



# Find Key 8

#### Heap File

2,5 1,6 4,7 3,10 8,9

#### Pages touched on average?

- P(i): Probability of key on page i is 1/B
- T(i): Number of pages touched if key on page i is i
- Therefore the expected number of pages touched

$$\sum_{i=1}^{B} T(i) \mathbf{P}(i) = \sum_{i=1}^{B} i \frac{1}{B} = \frac{B(B+1)}{2B} \approx \frac{B}{2}$$



# Find Key 8

## Heap File



Pages touched on average: B/2

- Breaking an assumption
  - What if there was more than one key?
  - Need to check all the pages → B



# Find Key 8

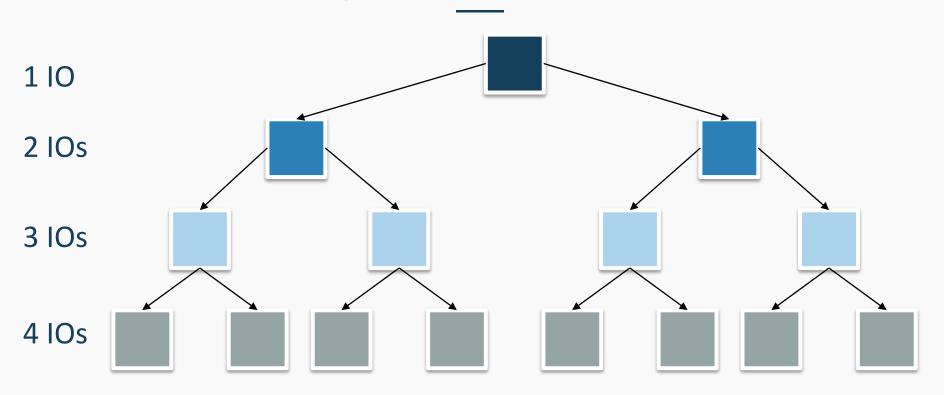
#### Sorted File



- Worst-case: Pages touched in binary search
  - $-\log_2 B$
- Average-case: Pages touched in binary search
  - $-\log_2 B$ ?



# Average Case Binary Search



Expected Number of Reads: 1(1/B) + 2(2/B) + 3(4/B) + 4(8/B)

$$\sum_{\substack{i=1\\ F. Ahmad\ Abusnaina}}^{\log_2 B} i\frac{2^{i-1}}{B} = \frac{1}{B}\sum_{\substack{i=1\\ Storage\ and\ Indexing}}^{\log_2 B} i2^{i-1} = \log_2 B - \frac{B-1}{B}$$

	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D
Range Search		
Insert		
Delete		

- **B:** The number of data blocks
- R: Number of records per block
- D: Average time to read/write disk block



	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D
Range Search		
Insert		
Delete		

- **B:** The number of data blocks
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# Find Keys Between 7 and 9

Heap File



Always touch all blocks. Why?



# Find Keys Between 7 and 9

## Heap File



Always touch all blocks. Why?

#### Sorted File



- Find beginning of range
- Scan right



	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D
Range Search	B*D	((log <sub>2</sub> B)+pages)*D
Insert		
Delete		

- **B:** The number of data blocks
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- **D:** Average time to read/write disk block



	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D
Range Search	B*D	((log <sub>2</sub> B)+pages)*D
Insert		
Delete		

- **B:** The number of data blocks
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## Insert 4.5

## Heap File



Stick at the end of the file. Cost? = 2\*D Why 2?

## Insert 4.5

#### Heap File



Read last page, append, write.

Cost = 2\*D

Sorted File



Find location for record: log<sub>2</sub>B



## Insert 4.5

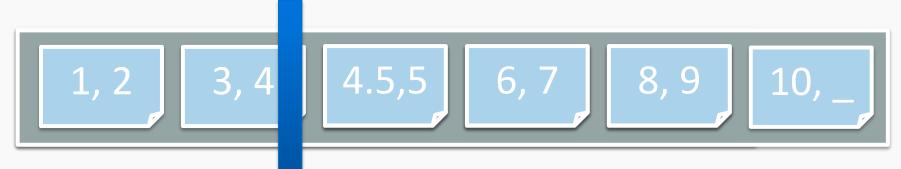
## Heap File



Read last page, append, write.

Cost = 2\*D

#### Sorted File



- Find location for record: log<sub>2</sub>B
- Insert and shift rest of file Cost? 2\*B/2 Why?



	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D
Range Search	B*D	((log <sub>2</sub> B)+pages)*D
Insert	2*D	((log <sub>2</sub> B)+B)*D
Delete		

- **B:** The number of data blocks
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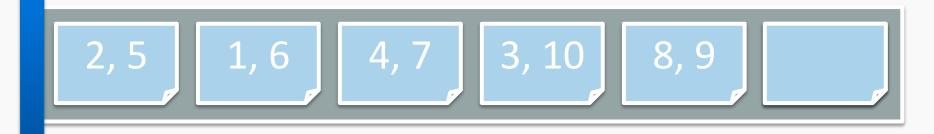
	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D
Range Search	B*D	((log <sub>2</sub> B)+pages)*D
Insert	2*D	((log <sub>2</sub> B)+B)*D
Delete		

- **B:** The number of data blocks
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# Delete 4.5

## Heap File



Average case to find the record: B/2 reads

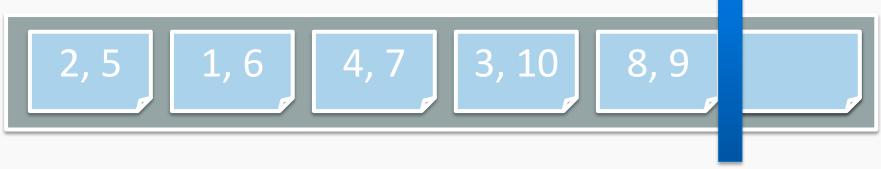
Delete record from page

Cost? = (B/2+1)\*D Why +1?

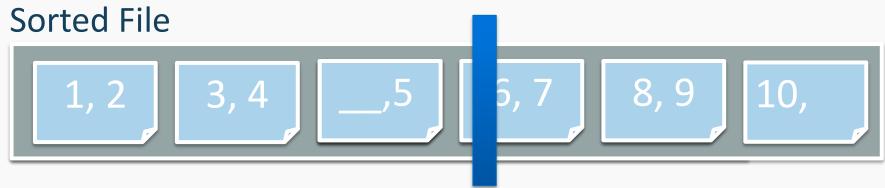


# Delete 4.5

#### Heap File



Average case runtime: (B/2+1) \* D

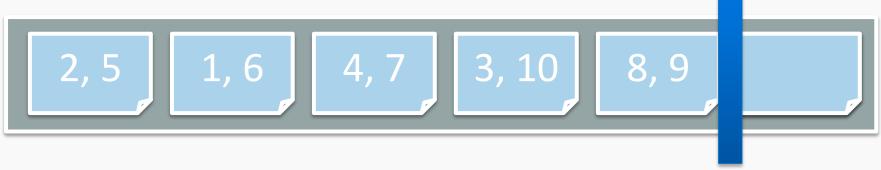


- Find location for record: log<sub>2</sub>B
- Delete record in page → Gap



### Delete 4.5

### Heap File



Average case runtime: (B/2+1) \* D

### Sorted File



- Find location for record: log<sub>2</sub>B
- Shift rest of file left by 1 record: 2 \* (B/2)



	Heap File	Sorted File		
Scan all records	B*D	B*D		
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D		
Range Search	B*D	((log <sub>2</sub> B)+pages)*D		
Insert	2*D	((log <sub>2</sub> B)+B)*D		
Delete	(0.5*B+1)*D	((log <sub>2</sub> B)+B)*D		

- **B:** The number of data blocks
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- **D:** Average time to read/write disk block

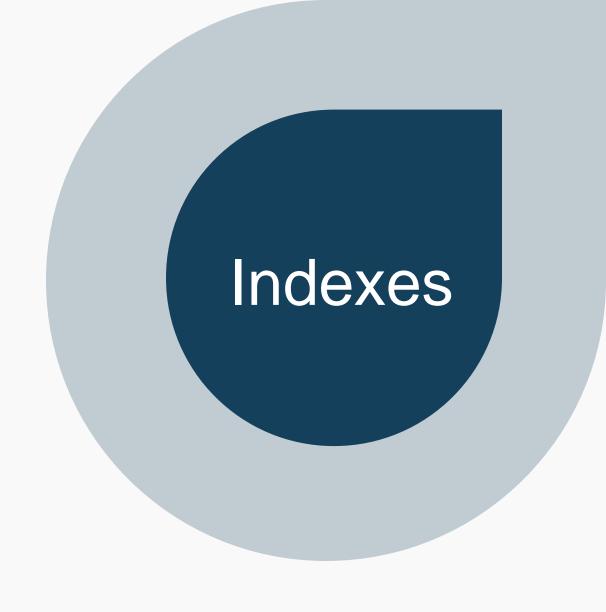
	Heap File	Sorted File		
Scan all records	B*D	B*D	Issues: • Find	
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	<ul><li>Range</li><li>Modification</li></ul>	
Range Search	B*D ((log <sub>2</sub> B)+pages)*D		Can we do	
Insert	2*D	((log <sub>2</sub> B)+B)*D	better?	
Delete	(0.5*B+1)*D	((log <sub>2</sub> B)+B)*D		

- **B:** The number of data blocks
- R: Number of records per block
- **D:** Average time to read/write disk block

Indexe

5







### **Indexes Overview**

- ✓ Indexing organizes data records on disk to optimize certain kinds of retrieval operations.
- ✓ An index is a data structure that enables fast lookup of data entries by search key.
  - Lookup (retrieval): may support many different operations
    - Equivalence (i.e. =), range (i.e. >, < , >=), ...
  - Data Entries: records stored in the index file, (k, {items})
    - A data entry with search key value k, denoted as k\*.
    - Could be actual records or record-ids (pointers).
    - We can efficiently search an index to find the desired data entries, and then use these to obtain data records.
  - Search Key: any subset of columns (i.e. fields) in the relation.





## Search Key: Any Subset of Columns?

- Search key does not require to be a key of the relation
  - Recall: key of a relation must be unique (e.g., SSN)
  - Search keys don't have to be unique
- Additional indexes can be created on a given collection of data records, each with a different search key,
- Why indexing used?
- to speed up search operations that are not efficiently supported by the file organization used to store the data records on disk.





### **Example**

- Consider the Employee Table.
- We can store the records in a file organized as an index on employee age;
- which it is an alternative to sorting the file by age (i.e Sorted file).
- Additionally, we can create an auxiliary index file based on salary, to speed up queries involving salary.

•



## **Example: creating different indexes**

<age, sal=""></age,>	rid
19,100	4
20,10	1
20,20	5
24,80	2
25,75	3

	<sal,age></sal,age>	rid
	10,20	1
	20,20	5
	75,25	3
	80,24	2
ηŞT <u>I</u>	100,19 JDENTS-HUB hmad Abusnain	4 .com

### **Employee Table**

Name	age	sal	
Ahmad	20	10	
Assad	24	80	
Murad	25	75	
Moh'd	19	100	
Qusai	20	20	

<age></age>	rid
19	4
20	1
20	5
24	2
25	3

<sal></sal>	rid
10	1
20	5
75	3
80	2
100	4



rid

1

2

3

4

<age, sal>

31,400

32,300

55,140

55,400

### Search Key: Any Subset of Columns?

- Search key needn't be a key of the relation
  - Recall: key of a relation must be unique (e.g., SSN)
  - Search keys don't have to be unique
- Composite Keys: more than one column
  - Think: Phone Book <Last Name, First>
  - Lexicographic order

_	<age,< th=""><th>Sa</th><th>lary</th><th><b>/&gt;:</b></th></age,<>	Sa	lary	<b>/&gt;:</b>
---	---	----	------	---------------

/	•	Age = 31	& Sala	rv = 400
•	_	, 18c 3±		, ,



• Age = 31

• Age > 31

Salary = 300

ne, First>						
SSN	Name	Age	Salary			
123	Ahmad	31	\$400			
443	Assad	32	\$300			
244	Moh'd	55	\$140			

55



Qusai

Means that the index is unable to exclude all entries that are not in the result set.

\$400



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## Data Entries: How are they stored?

- What is the representation of data in the index?
  - Actual data or pointer(s) to the data
- How is the data stored in the data file?
  - Clustered or unclustered with respect to the index
- Big Impact on Performance





### What to store as a data entry in an index?

- Three main alternatives:
  - 1. By Value:

A data entry **k\*** is an actual data record (with search key value **k**).

2. By Reference: <k, rid of matching data record>

A data entry **k\*** is a (k, *rid*) pair, where *rid* is the record id of a data record with search key value **k**.

- **3. By List of References:** <**k**, list of rids of *all* matching data records>
  A data entry **k\*** is a (k. rid-list) pair, where rid-list is a list of record ids of data records with search key value k.
- Can have multiple (different) indexes per file, for e.g.,
  - file stored by age
  - a hash index on salary and
  - B+ tree index on name.



### Alternatives for Storing Data Entries

Alternative 1: By Value – Actual data record (with key value k)

- Index as a file organization for records
  - Similar to heap files or sorted files
- No "pointer lookups" to get data records
  - Following record ids
- Could a single relation have multiple indexes of this form?



### Alternatives for Storing Data Entries

Alternative 2: By Reference, <k, rid of matching data record> and

Alternative 3: **By List of references**, <**k**, list of rids of matching data records>

#### **By Reference**

Nama	Name	Salary	By List of references		
Ivaille	Ivallie		_ J	LISC OI I	
Gonzalez	Amanda	\$400		Key	Record Id
Gonzalez	Joey	\$300	<b>←</b>	Gonzalez	{1, 2, 3}
		4440			
Gonzalez	Jose	\$140		Hong	4
Hong	Sup	\$400	4		
		Gonzalez Amanda Gonzalez Joey Gonzalez Jose	Gonzalez Amanda \$400 Gonzalez Joey \$300 Gonzalez Jose \$140	Gonzalez Amanda \$400 Gonzalez Joey \$300 Gonzalez Jose \$140	Gonzalez Amanda \$400 Key Gonzalez Joey \$300 Gonzalez Gonzalez Jose \$140 Hong

- Alternatives 2 or 3 needed to support multiple indexes per table!
- Alternative 3 more compact than alternative 2
- For very large rid lists, single data entry spans multiple blocks.





- In a clustered index:
  - index data entries are stored in (approximate) order by value of search keys in data records



- In a clustered index:
  - index data entries are stored in (approximate) order by value of search keys in data records

Clustered Unclustered

Key	Record Id		SSN	Last Name	First Name	Salary		Key	Record Id
Gonzalez	1		123	Gonzalez	Amanda	\$400	~/	Gonzalez	3
Gonzalez	2		443	Gonzalez	Joey	\$300		Gonzalez	1
Gonzalez	3		244	Gonzalez	Jose	\$140		Hong	4
Hong	4	<b></b>	134	Hong	Sue	\$400		Gonzalez	2

- In a clustered index:
  - index data entries are stored in (approximate) order by value of search keys in data records
  - A file can be clustered on at most one search key
- Cost of retrieving data records through index varies greatly based on whether index is clustered or not!

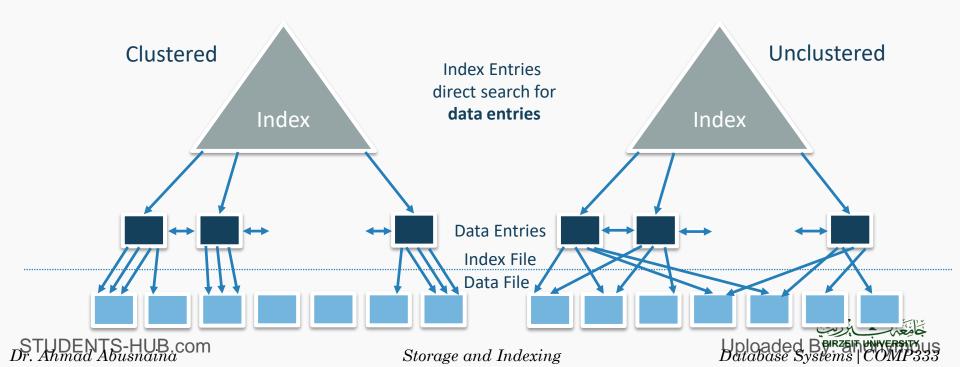
- Note: there is another definition of "clustering"
  - Data Mining/AI: grouping similar items in n-space





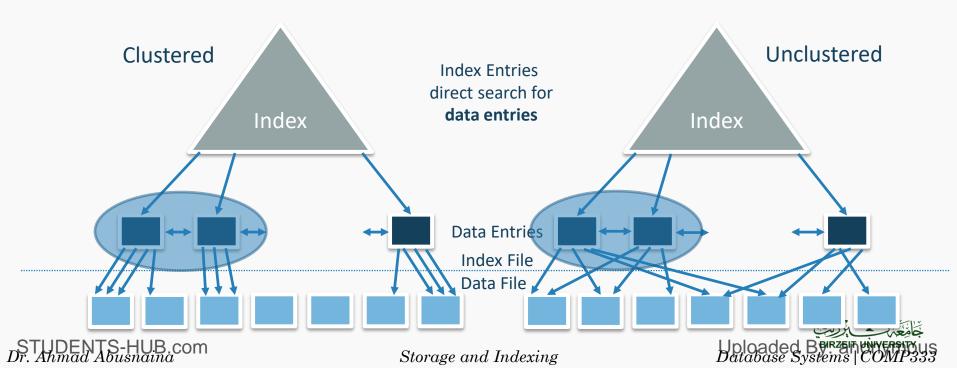
#### Alternative 2: Use references to data entries, data records in a Heap File

- To build a clustered index, first sort the heap file
  - Leave some free space on each block for future inserts
- Overflow blocks may be needed for inserts
  - Thus, order of data records is "close to", but not identical to, the sort order



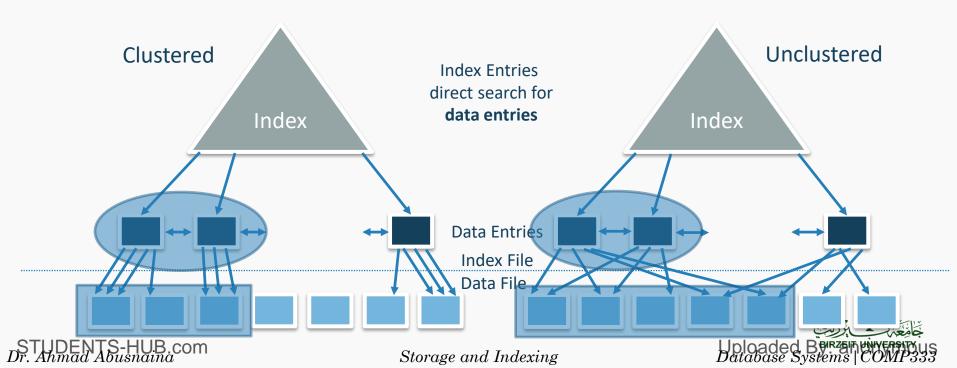
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- Clustered Index Pros
  - Efficient for range searches
  - Potentially locality benefits?
    - Sequential disk access, prefetching, etc.
  - Support certain types of compression

Enhance compression algorithms.
Graduation project or Master

- Clustered Cons
  - More expensive to maintain
    - Need to update index data structure
  - File usually only packed to 2/3 to accommodate inserts
  - Need more storage space





	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B) * D
Range Search	B*D	((log <sub>2</sub> B)+pages)*D
Insert	2*D	((log <sub>2</sub> B)+B)*D
Delete	(0.5*B+1)*D	((log <sub>2</sub> B)+B)*D

#### Can we do better with indexes?

- **B:** The number of data blocks
- R: Number of records per block
- **D:** Average time to read/write disk block



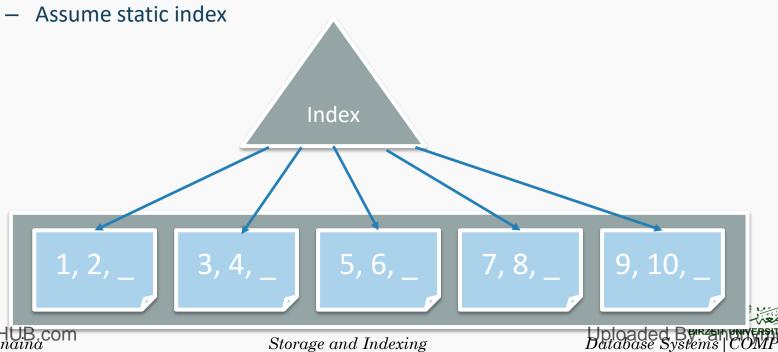
	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	
Insert	2*D	$((\log_2 B) + B)*D$	
Delete	(0.5*B+1)*D	$((\log_2 B) + B)*D$	

- **B:** The number of data blocks
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#### Assumptions:

- Store data by reference (Alternative 2)
- Clustered index with 2/3 full heap file pages
  - Clustered → Heap file is initially sorted
  - **Fan-out** (F): relatively large. Why?
    - Page of <key, pointer> pairs ~ O(R)



	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	
Insert	2*D	$((\log_2 B) + B)*D$	
Delete	(0.5*B+1)*D	$((\log_2 B) + B)*D$	

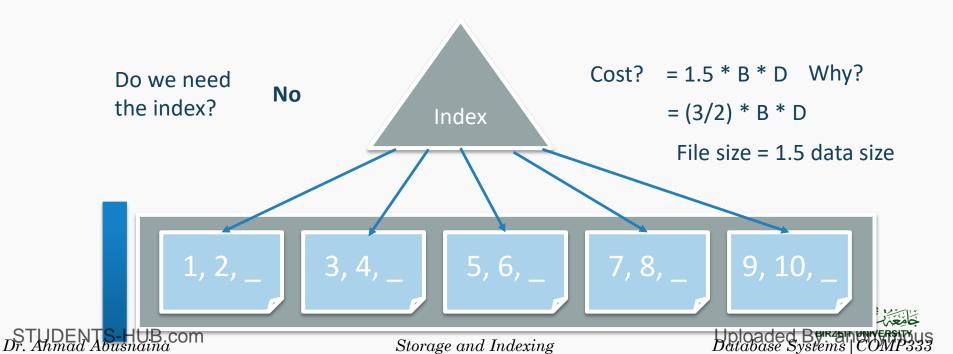
- **B:** The number of data blocks
- R: Number of records per block
- D: Average time to read/write disk block



### Scan all the Records

#### Assumptions:

- Store data by reference (Alternative 2)
- Clustered index with 2/3 full heap file pages
- Occupancy = 66.6%
  - Clustered → Heap file is initially sorted



	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	1.5*B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	
Insert	2*D	$((\log_2 B) + B)*D$	
Delete	(0.5*B+1)*D	$((\log_2 B) + B)*D$	

- **B:** The number of data blocks
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	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	1.5*B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	
Insert	2*D	$((\log_2 B) + B)*D$	
Delete	(0.5*B+1)*D	$((\log_2 B) + B)*D$	

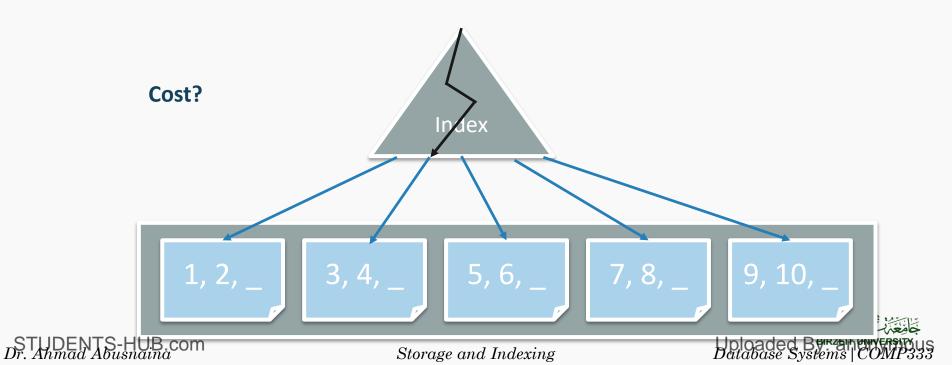
- **B:** The number of data blocks
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## Find the record with key 3

Search the index: =  $log_F (1.5 * B) * D$ 

- Each page load narrows search by factor of F
- Lookup record in heap file by record-id = D



	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	1.5*B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	((log <sub>F</sub> 1.5*B))*D
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	
Insert	2*D	$((\log_2 B) + B)*D$	
Delete	(0.5*B+1)*D	$((\log_2 B) + B)*D$	

- **B:** The number of data blocks
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	Heap File	Sorted File	Clustered Index
Scan all records	B*D	B*D	1.5*B*D
Equality Search	0.5*B*D	(log <sub>2</sub> B)*D	((log <sub>F</sub> 1.5*B))*D
Range Search	B*D	((log <sub>2</sub> B)+pages))*D	
Insert	2*D	((log <sub>2</sub> B)+B)*D	
Delete	(0.5*B+1)*D	((log <sub>2</sub> B)+B)*D	

- **B:** The number of data blocks
- R: Number of records per block
- D: Average time to read/write disk block

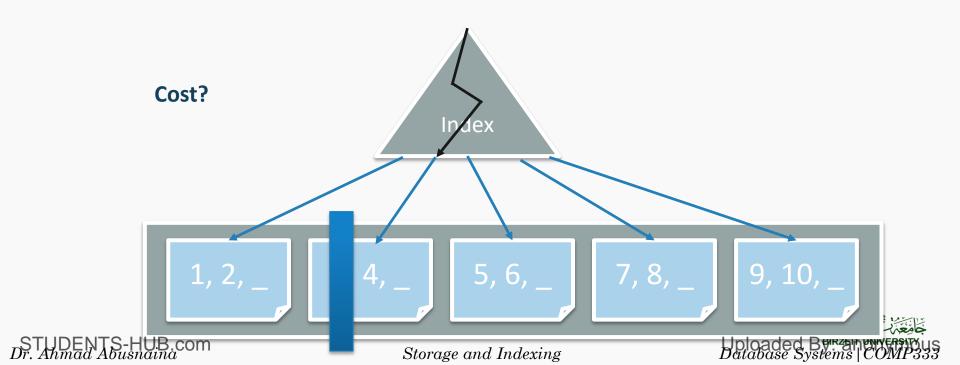


## Find keys between 3 and 7

Search the index: =  $log_F (1.5 * B) * D$ 

- Each page load narrows search by factor of F
- Lookup record in heap file by record-id = D
- Scan the data pages until the end of range

= (#matching pages) \* D



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Delete	(0.5*B+1) * D	((log <sub>2</sub> B)+B)*D	((log <sub>F</sub> 1.5*B)+2)*D	

- **B:** The number of data blocks
- R: Number of records per block
- D: Average time to read/write disk block

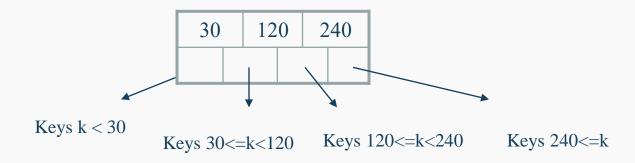


### Tree-Based Indexing

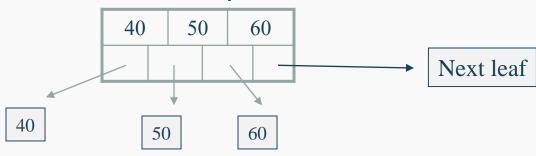
- Usually B+ tree is used.
- Each node points to one block
  - Make leaves into a linked list (range queries are easier)

### **B+ Trees Basics**

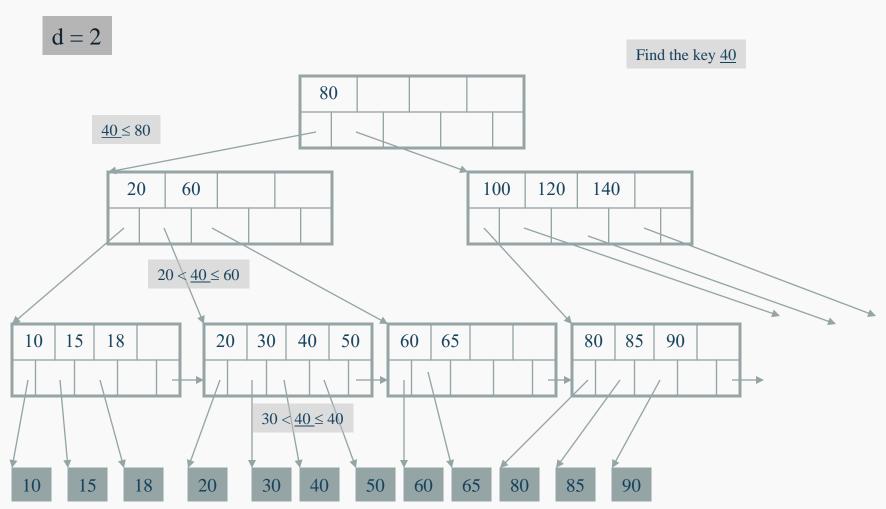
- Parameter d = the degree
- Each node has >= d and <= 2d keys (except root)</li>



Each leaf has >=d and <= 2d keys:</li>



### B+ Tree Example



## Searching a B+ Tree

- Exact key values:
  - Start at the root
  - Proceed down, to the leaf

Select name From people Where age = 25

- Range queries:
  - As above
  - Then sequential traversal

Select name
From people
Where 20 <= age
and age <= 30



### **B+ Trees in Practice**

- Typical order: d= 100.
- Typical fill-factor: 67%.
  - average fanout = 133
- Typical capacities:
  - Height 4:  $133^4 = 312,900,700 \text{ records}$
  - Height 3:  $133^3$  = 2,352,637 records
- B-Trees dynamic, good for changing data, range queries

The average number of children for a non-leaf node is called the **fan-out** of the tree.

How many I/O needed to search for a record within 312 million records?



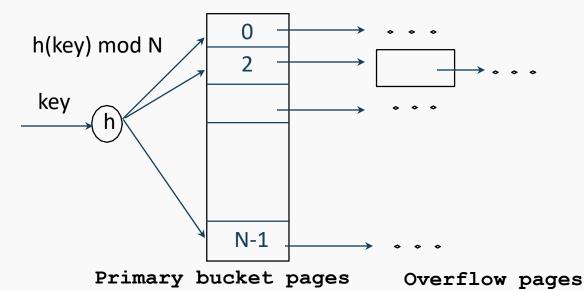
### Hash-Based Indexes

- Good for equality selections.
- Index is a collection of buckets.
- Bucket = primary page plus zero or more overflow pages.
- Buckets contain data entries.
- Hashing function h: h(r) = bucket in which (data entry for) record r belongs.
- h looks at the search key fields of r.



### Static Hashing

- # primary pages fixed, allocated sequentially, never de-allocated;
- overflow pages if needed.
- $h(k) = k \mod N = bucket to which data entry with key k belongs. (N = # of buckets)$ 
  - h(k) = (a \* k + b) usually works well.
  - a and b are constants





## Summary

- Many file organizations, with tradeoffs
  - Heap Files, Sorted Files, Clustered Files and Indexes
  - Benefits depend on the common operations
  - Compute expected costs
- Indexes: fast lookup of data entries by search key
  - Lookup: equivalence, range, region ...
  - Search key: arbitrary columns
- Data Entries:
  - 3 alternatives: By Value, By Reference, By List of References



## Summary

- Often multiple indexes per file of data records
  - Each with a different search key
- Indexes can be classified as clustered vs unclustered
  - Important consequences for utility/performance



### Summary

	(a) Scan	(b) Equality	(c ) Range	(d) Insert	(e) Delete
(1) Heap	BD	0.5BD	BD	2D	Search +D
(2) Sorted	BD	Dlog 2B	D(log 2 B) +D. # pgs w. match recs	Search + BD	Search +BD
(3) Clustered	1.5BD	Dlog F 1.5B	D(log F 1.5B) + D. # pgs w. match recs	l	Search +D
(4) Unclust. Tree index	BD(R+0.15)	D(1 + log f 0.15B)	D(log F 0.15B + # match recs)	Search + 2D	Search + 2D
(5) Unclust. Hash index	BD(R+0.125)	2D	BD	Search + 2D	Search + 2D