Ch 3

$$a_{11} X_{1} + a_{12} X_{2} + \cdots + a_{1n} X_{n} = b_{1}$$
 $a_{21} X_{1} + a_{22} X_{2} + \cdots + a_{2n} X_{n} = b_{2}$
 \vdots
 $a_{n1} X_{1} + a_{n2} X_{2} + \cdots + a_{nn} X_{n} = b_{n}$

Cost (complexity): is the number of operations +, -, x, : required to complete a certain calculation.

Exp Let A = \[\begin{array}{c} a b \]. Find the cost of finding IAI = \det(A)

$$|A| = axd - bxc \Rightarrow Cost = 3$$

Exp Let A = \[\begin{pmatrix} a & b & c \\ d & e & f \\ \emptyset \]. Find the cost of calculating IAI.

$$|A| = a \times \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \times \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \times \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$

Cost = 14

Remark: My student proved that the cost of finding | Anxn) for n > 2 is 1 cost =ni 2K-1 or

Exercise show that n! \(\frac{2k-1}{k!} = [n! e-2] \) 53.1 where [] is the greatest integer function Proof: $n! = \sum_{k=2}^{n} \frac{2k-1}{k!} = n! = \sum_{k=2}^{n} \left(\frac{2k}{k!} - \frac{1}{k!} \right)$ K| = K(K-1)! $= n! / 2 \sum_{k=1}^{n} \frac{1}{(k-1)!} - \sum_{k=1}^{n} \frac{1}{k!}$ $= n! \left[2 \left(1 + \sum_{K=2}^{n} \frac{1}{(K-1)!} \right) - \sum_{K=2}^{n} \frac{1}{K!} + \sum_{K=2}^{n} \frac{1}{K!} - \sum_{K=2}^{n} \frac{1}{K!} \right]$ =n! $\left[2+\sum_{k=2}^{n}\frac{1}{k!}+2\left(\sum_{k=3}^{n}\frac{1}{(k-1)!}-\sum_{k=3}^{n}\frac{1}{k!}\right)\right]$ shifting index K Note that $\sum_{k=1}^{n-1} \frac{1}{k!} = \sum_{k=1}^{n-1} \frac{1}{n!} = \frac{-1}{n!}$

$$= n! \left[2 + \sum_{k=2}^{1} \frac{1}{k!} - \frac{2}{n!} \right]$$

$$\sum_{k=2}^{n} \frac{1}{k!}$$

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$$= n! \begin{bmatrix} \sum_{k=0}^{n} \frac{1}{k!} - \frac{2}{n!} \end{bmatrix}$$

$$= n! \sum_{k=0}^{n} \frac{1}{k!} - 2$$

• But
$$e' = \sum_{n=0}^{\infty} \frac{x^2}{n!}$$
 so $e = \sum_{K=0}^{\infty} \frac{1}{K!}$

• Hence,
$$n! = n! \sum_{k=0}^{n} \frac{1}{k!} + n! \sum_{k=n+1}^{\infty} \frac{1}{k!}$$

• That is,
$$n! \sum_{k=0}^{n} \frac{1}{k!} = n! e - n! \sum_{k=n+1}^{\infty} \frac{1}{k!}$$

• Now
$$n! \sum_{k=2}^{n} \frac{2k-1}{k!} = n! \sum_{k=0}^{n} \frac{1}{k!} - 2$$

$$= n! e - 2 - \begin{bmatrix} n! & \frac{1}{k!} \\ k=n+1 \end{bmatrix}$$

- · Noke that R represents the error of calculating nie which is always less than one "since k starts at n+1 and we have $n \ge 2$ ".
- So we can get rid of R by taking the floor function or greatest integer number.

• That is,
$$n! \sum_{k=2}^{n} \frac{2k-1}{k!} = [n!e-2]$$

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$$[2.9] = 2$$

 $[2.9] = 2$
 $[-2.9] = -3$
 $[-3.1] = -3$

$$Cost = (9)(5) = 45$$

Exp 4 Let A and B be 3x3 matrices. Find the cost of A + 1B1 B

131 requires cost = 14 by Exp 1131 × B requires cost = 9 A + IBIB requires cost = 9

Total Cost = 32 STUDENTS-HUB.com

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Result: If A is nxn matrix, then the cost of calculating A2 is 2n-n2 See $E_{NP}^{3} \Rightarrow n=3 \Rightarrow 2(3)^{3}-(3)^{2}=2(27)-9$ = 54 - 9

Backward substitution method used to solve a linear system of equations that has an upper-triangular coefficient matrix:

$$a_{11} X_1 + a_{12} X_2 + a_{13} X_3 + \cdots + a_{1n} X_n = b_1$$

$$a_{12} X_2 + a_{23} X_3 + \cdots + a_{2n} X_n = b_2$$

$$a_{33} X_3 + \cdots + a_{3n} X_n = b_3$$

ann Xn = bn

ann
$$x_n = b$$

ann $x_n = b$

coefficient matrix

Exp Solve the following linear system using Backward Substitution and find the cost.

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$$-X_2 + 2X_3 + 3X_4 = 20$$

$$-2X_2 + 7X_3 - 4X_4 = -7$$

$$6X_3 + 5X_4 = 4$$

$$3X_4 = 6$$

step 1:
$$x_y = \frac{6}{3} = 2$$

Step 2:
$$X_3 = \frac{4-5\times2}{6} = -1 =$$
Three operations

step 3:
$$X_2 = \frac{-7 \times -1 + 9 \times 2 - 7}{-2} = -9$$
 => Five operations $\frac{-1}{2} \times \frac{2}{3} = \frac{-1}{2} \times \frac{3}{3} = \frac{1$

step 4:
$$X_1 = \frac{1x-4-2x-1-3x^2+20}{4} = 3$$

Hence, total cost =
$$16 = (4)^2 = n^2$$

Cost of Backward Substitution (B.S.) for solving nxn linear system

O .		
step	+,-	x , ÷
1	0	1
2)	2
3	2	3
4	3	4
, , ,	9 0	1
n	n-1	n

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Total +,- is
$$0+1+2+3+\cdots+n-1 = \frac{n(n-1)}{2} = \frac{n^2-n}{2}$$

Total x,: is $1+2+3+4+\cdots+n = \frac{n(n+1)}{2} = \frac{n^2+n}{2}$
Hence, total cost = $\frac{n^2-n}{2} + \frac{n^2+n}{2} = n^2$

$$1+2+3+\cdots+n=\sum_{k=1}^{n}k=\frac{n(n+1)}{2}$$

$$1 + 2 + 3 + \dots + n^{2} = \sum_{k=1}^{n} k^{2} = \frac{n(n+1)(2n+1)}{6}$$

Five Methods to solve the linear system AX = b

$$(A1b) \longrightarrow (IX)$$

$$(AII) \longrightarrow (IIA)$$

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9 Cramer's Rule:

• Then
$$X_1 = \frac{|A_1|}{|A|}$$
, $X_2 = \frac{|A_2|}{|A|}$, ..., $X_n = \frac{|A_n|}{|A|}$

[5] LU Factorization:

n-1 for +

· Write A = LU where L is lower triangle matrix U is upper triangle matrix

· Let Y = UX AX=b becomes LUX = b

. Now solve LY = b by F. 5 and find Y

. Then solve UX = Y by B.5 and find X

Remark: The speed of these methods is like this

Exp show that if A is nxn matrix, then the cost of finding A is $2n^3 - n^2$

$$A = AA = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{2n} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{2n} & \cdots & a_{nn} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1n} \\ c_{21} & c_{22} & \cdots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{2n} & \cdots & a_{nn} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{2n} & \cdots & a_{nn} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{2n} & \cdots & a_{nn} \end{bmatrix}$$

C₁₁ = a₁₁ x a₁₁ + a₁₂ x a₁₂ + ... + a_{1n} x a_{1n} Costs n for x

Hence, C11 costs 2n-1 But A2 has n2 elements and each one costs zn-1

Hence, total cost of calculating A is $n^2(2n-1) = 2n-n^2$

The Augmented matrix is denoted by

$$[A1b] = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_{1} \\ a_{21} & a_{22} & \cdots & a_{2n} & b_{2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n_{1}} & a_{n_{2}} & \cdots & a_{nn} & b_{n} \end{bmatrix}$$

--. *

Th (Elementary Row Operations ERO)

The following operations applied to the augmented matrix

* yield an equivalent linear system:

Row Operation I: Interchange two rows

Row Operation II: Multiply a row by a nonzero constant

Row operation III: The row R_K can be replaced by the sum of R_K and a nonzero multiple of any other row R_P . That is, $R_K = R_K - \frac{m}{KP} R_P$

where $m_{kp} = \frac{a_{kp}}{a_{pp}}$ is called the multiplier

STUDENTS-HUB.com the following linear system:

$$X_1 + 2X_2 + X_3 + 4X_4 = 13$$

$$2x_1 + 4x_3 + 3x_4 = 28$$

$$4X_1 + 2X_2 + 2X_3 + X_4 = 20$$

$$-3x_1 + X_2 + 3X_3 + 2X_4 = 6$$

[Express this system in augmented matrix fo		spress thi	syskm	in	augmented	matrix	form.
--	--	------------	-------	----	-----------	--------	-------

$$m_{y_1} = \frac{q_{y_1}}{q_{y_1}} = -3$$

are the multipliers

[ii] Find an equivalent upper-triagular system using G.E.

• Step 2 • Find multipliers
$$m_{32} = \frac{-6}{-4} = 1.5$$
 and $m_{42} = \frac{7}{-4} = -1.75$

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$$R_3 - 1.5 R_2$$

$$R_4 + 1.75 R_2$$

** Apply Hem
$$\begin{vmatrix} 1 & 2 & 1 & 4 & 13 \\ 0 & -4 & 2 & -5 & 2 \\ 0 & 0 & -5 & -7.5 & -35 \\ 0 & 0 & 9.5 & 5.25 & 48.5 \end{vmatrix}$$
 STUDENTS-HUB.com
$$R_{3} - 1.5 R_{2}$$

$$R_{4} + 1.75 R_{2}$$

• Step 3 • Find the multiplier
$$m_3 = \frac{9.5}{-5} = -1.9$$

$$X_{4} = \frac{-18}{-9} = 2$$

$$X_{3} = \frac{7.5(z) - 35}{-5} = 4$$

$$X_2 = -\frac{2(4) + 5(2) + 2}{-4} = -1$$

$$X_1 = 13 - 2(-1) - 9 - 9(2) = 3$$

[iv] Find the cost of solving this system using a.E.

· Cost 1: (A1b) -> (U/c) for this yxy system

Step	+,-	÷,X
)	3 (4)	3, 3(4)
2	2(3)	2, 2(3)
3	1(2)	1, 1(2)
Total	20	26

cost 1 = 46

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2) The cost of solving nxn linear system using G.E is $\frac{4n^{3} + 9n^{2} - 7n}{6}$

Proof \square Cost of $(A|b) \longrightarrow (U|c)$ as we have seen in Exp - iv page 61 is as follow:

	4		
step	+,-	<u>.</u>	V
1	(n-1) n	n-1	(n-1) n
2	(n-2)(n-1)	n-2	
	\$ 5 0		(n-2)(n-1)
· K	(n-k)(n-k+1)	n-k	(n-x)(
Total	n-1	•	(n-k)(n-k+1)
lotal	$\sum (n-k)(n-k+1)$	n-1 (n-k)	M-1
	K=1	K=1	(n-k)(n-k+1)
			K=1

$$= 2 \frac{n(n-1)(2n-1)}{6} + 3 \frac{n(n-1)}{2} = \frac{4n+3n-7n}{6}$$

(2) Cost of any nxn system using G.E is cost of (A1b) -> (U1c) + $= \frac{yn^3+3n^2-7n}{6} + n^2 = \frac{yn^3+9n^2-7n}{6}$ cost of B.S.

Gaussian Elimination and Pivoting

63

- · If the pivot element app = 0 in row p, then row p can not be used to eliminate the elements in column p below the main diagonal.
- . The process of finding a row k with nonzero pivole element ap to, K>P and interchang row p by row k is called pivoting.

· Pivoting is two types:

I Trivial pivoting:

. if app $\neq 0$, then do not switch rows . if app = 0, then switch row p by the first row, below, s.t $a_{KP} \neq 0$.

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$$\begin{bmatrix} 0 & -1 & 2 & 3 \\ 0 & 2 & 4 & 7 \\ 1 & 2 & 3 & 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 2 & 4 & 7 \\ 0 & -1 & 2 & 3 \end{bmatrix}$$
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12 Partial Pivoting:

- · if app = 0 or app + 0, choose the pivotal row K whose pivot akp, K>P satisfy | ap| = max { | app |, | ap+1, p |, ..., | anp | }
- · This will make all multipliers mrp, r=p+1, ..., n less than or equal to 1 in absolute value.
- · And hence, reducing the error being propagated when using a finite-digit arithmetic

Exp Consider the following linear system

1.133
$$X_1 + 5.281 X_2 = 6.414$$

24.14 $X_1 - 1.210 X_2 = 22.93$

whose solution is $(X_1, X_2) = (1, 1)$.

1 Use G.E. with trivial pivoting and use four-digit arithmetic to solve this system.

Pivot → [1.133] 5.281 | 6.414] since pivot a₁₁ ≠ 0 R₂-m R₁ 24.14 -1.210 | 22.93 | so we do not switch rows

$$m_{21} = \frac{a_{21}}{a_{11}} = \frac{24.14}{1.133} = 21.31$$

$$X_2 = \frac{-113.8}{-113.7} = 1.00$$

65

$$X_1 = \frac{6.414 - 5.281(1.001)}{1.133} = 0.9956$$

Note that the error in the solution is due to the magnitude of the multiplier mz, which is >>1.

2) Use G.E. with partial pivoting and use four-digit arithmetic to solve this system.

$$m_{21} = \frac{1.133}{24.14} = 0.04693 < 1$$

$$X_2 = \frac{5.338}{5.338} = 1$$

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No Error

2 LU - Factorization

66

To solve the linear system AX = b:

- · Write A = LU where L is lower triangular matrix and U is upper triangular matrix
- · Let Y=UX =>

AX=b becomes LUX=b LY=b

- · Now solve LY = b by F.S and find Y
- · Then solve UX=Y by B.5 and find X

* We will see that:

cost of LU = cost of G.E.

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Expo Use LU factorization to solve the linear 67

System:
$$4x_1 + 3x_2 - x_3 = 1$$

$$X_1 + 2X_2 + 6X_3 = 14$$

@ find the cost of this method

$$A = \begin{pmatrix} 4 & 3 & -1 \\ -2 & -4 & 5 \\ 1 & 2 & 6 \end{pmatrix} , b = \begin{pmatrix} 1 \\ 6 \\ 14 \end{pmatrix}$$

- · We need to write A = LU
- · First we find U using row operations:

Step !

$$m_{21} = \frac{a_{21}}{a_{11}} = \frac{-2}{4} = -0.5$$
 \Rightarrow $R_2 + 0.5 R_1$

$$m_{31} = \frac{q_{31}}{q_{11}} = \frac{1}{4} = 0.25 \implies R_3 - 0.25 R_1$$

STUDENTS-HUBICOM = $\frac{q_{32}}{200} = \frac{1.25}{-2.5} = -0.5 \Rightarrow R_3 + 0.5 R_2$ Uploaded By: anonymous

$$U = \begin{pmatrix} 4 & 3 & -1 \\ 0 & -2.5 & 4.5 \\ 0 & 0 & 8.5 \end{pmatrix}$$

$$L = \begin{pmatrix} 1 & 0 & 0 \\ m_{21} & 1 & 0 \\ m_{31} & m_{32} & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ -0.5 & 1 & 0 \\ 0.25 & -0.5 & 1 \end{pmatrix}$$

Note that cost of
$$A = LU$$
 is $13 = \frac{yn^3 - 3n^2 - n}{6}$

$$\begin{pmatrix} 1 & 0 & 0 & | & 1 \\ -0.5 & 1 & 0 & | & 6 \\ 0.25 & -0.5 & | & | & | & 14 \end{pmatrix}$$

$$y_1 = 1$$
 $y_2 = 6 + 0.5(1) = 6.5$
 $+, -: 5$

Note that cost of F.S. is
$$n-n = 3-3 = 9-3 = 6$$

$$X_3 = \frac{17}{8.5} = 2$$

$$X_2 = \frac{6.5 - 4.5(2)}{-2.5} = \frac{-2.5}{-2.5} = 1$$

$$X_1 = \frac{1 + (2)(+1) - 3(1)}{4} = \frac{9}{9} = 0$$

Note that cost of B.S. is
$$n^2 = 3^2 = 9$$

Remark The total cost of solving any linear nxn system AX = b using LU factorization is cost of LU + cost of F.S. + cost of B.S. $= \frac{4n^3 - 3n^2 - n}{6} + n^2 - n + n^2$ $= \frac{4n^3 + 9n^2 - 7n}{6}$

Exp Let A be 3x3 matrix and b1, b2 are 3x1 vectors.

Find the cost of solving the linear systems AX=b, and AX=b2 using LU factorization.

cost of A = LU is $\frac{4n^3 - 3n^2 - n}{6} = 13$

= cost of G.E.

cost of solving $Ax = b_1 \Rightarrow LY = b_1$ costs $n^2 - n = 6$ by FS STUDENTS-HUB.com P = 6 by FS Uploaded By: anonymous P = 6 by BS P = 6 by BS P = 6

cost of solving $Ax = b_2 \Rightarrow LY = b_2 \cos t_5 6$ using FS $UX = Y \cos t_5 9 \text{ using BS}$

Total cost = 13 + 6 + 9 + 6 + 9= 43

3 Cramer's Rule

70

To solve the linear nxn system AX = b:

- · Find IAI " it should not be zero"
- . The solution $X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$ is obtained as follow:

 $X_i = \frac{|A_i|}{|A|}$ where A_i is obtained by replacing the i^{th} column of A by the column b for all i=1,2,...,n

Exp Solve the following linear system using Cramer's Rule

$$2X_1 - 3X_2 = 8$$

$$X_1 + 5X_2 = -9$$

Then find the cost.

• $A = \begin{pmatrix} 2 & -3 \\ 1 & 5 \end{pmatrix} \Rightarrow |A| = (2)(5) - (1)(-3) = 13$ with cost:

• $X_1 = \frac{|A_1|}{|A|} = \frac{\begin{vmatrix} 8 & -3 \\ -9 & 6 \end{vmatrix}}{|3|} = \frac{|3|}{|3|} = 1$ with cost = 3+1 = 4

STUDENTS-HUB.com $X_2 = \frac{|A_2|}{|A|} = \frac{|A_2|}{|A|} = \frac{|A_2|}{|A|} = \frac{-26}{|A|} = -2 \quad \text{with cost} = 3 + \text{Uploaded By: anonymous}$

Total cost = 3 (3) + 2 = 11

number of cost of division determinants each one

71

Exp Assume Ax=b is 3x3 linear system.

Find the cost of solving this system using Cramer's Rule.

$$X_1 = \frac{|A_1|}{|A|}$$
, $X_2 = \frac{|A_2|}{|A|}$, $X_3 = \frac{|A_3|}{|A|}$

Remark To solve nxn linear system by Cramer's Rule,

the cost will be

Exp: For 4x4 system =>
the cost is

. 50, +4 where

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• Hence,
$$cost = 5 D_y + y$$

= $5(63) + y$
= 319

72

To solve the linear system
$$AX = b$$
:

 $(A|b) \longrightarrow (I|X)$

$$2X_1 + 2X_2 + 2X_3 + 2X_4 = 4$$

 $2X_1 - X_2 + 3X_3 - 5X_4 = -7$

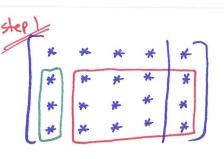
$$3X_1 - 2X_2 - X_3 - 4X_4 = -2$$

$$-X_1 + 3X_2 - 2X_3 + 2X_4 = 0$$

$$(A|b) = \begin{pmatrix} 2 & 2 & 2 & | & 4 \\ 2 & -1 & 3 & -5 & | & -7 \\ 3 & -2 & -1 & -4 & | & -2 \\ -1 & 3 & -2 & 2 & | & 0 \end{pmatrix} \Rightarrow (I|X) = \begin{pmatrix} 1 & 0 & 0 & 0 & | & 1 \\ 0 & 1 & 0 & 0 & | & -1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & | & 2 \end{pmatrix}$$

	step	+,-	÷ , ×
STUDENTS-	\	3 (4)	4 , 3(4)
	HUB.com	3 (3)	3 , 3(3)
	3	3(2)	2 / 3(2)
	4	3 (1)	1 / 3(1)

Total cost =
$$70 = \frac{2n^3 + n^2 - n}{2}$$



cost of
$$x = 3x4 = 12$$

cost of $\pm = 3x4 = 12$

cost of
$$x = 3 \times 3 = 9$$

cost of $\pm = 3 \times 3 = 9$

cost of
$$x = 3xz = 6$$

cost of $\pm = 3xz = 6$

Exp show that the cost of solving nxn linear system using G.J.R is $\frac{2n^3+n^2-n}{2}$

step	+ , -	۲ _{۷۷} ÷
١	(n-1) n	n + (n-1) n
2	(n-1) (n-1)	(n-1) + (n-1)(n-1)
3	(n-1) (n-2)	(n-2)+ (n-1) (n-2)
\$	0	0
K	(n-1) (n-k+1)	(n-K+1)+(n-1)(n-K+1)
:	9 6 6	*
n	(n-1)(1)	1 + (n-1)(1)

$$= (2n-1) \left[n \sum_{k=1}^{n} - \sum_{k=1}^{n} k + \sum_{k=1}^{n} \right]$$

$$=(2n-1)\left[n^2-\frac{n(n+1)}{2}+n\right]$$

STUDENTS-HUB(20m-1) ($\frac{n^2+n}{2}$)

$$=\frac{2n^3+n^2-n}{2}$$

5 Inverse Method

To solve the linear system AX=b:

Exp Find the cost of solving the following linear system using inverse method:

· Cost of Azza:

Step	+ ,-	÷	/	X	
1	2 (5)	5	,	2(5)	
2	2 (4)	4	,	2(4)	
3	2(3)	3	,	2(3)	Uploaded By: a

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Total cost of $\overline{A}_{3x_3} = 60 = \frac{n}{2}(2n-1)(3n-1)$ • (ost of $x = \overline{A}_{b} = \frac{n(6n^2-5n+1)}{2}$ at n=3

$$= \begin{pmatrix} * & * & * \\ * & * & * \\ * & * & * \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \\ * & * & * \end{pmatrix}$$
 is $(3+3+3)+(2+2+2) = 15 = n(2n-1)$
= $2n^2-n$ at $n=3$

· Hence, total cost of 3x3 linear system using inverse method is 60+15=75

$$S \neq p$$
 + , -
 \vdots
 , X

 1
 $(n-1)(2n-1)$
 $(2n-1)$
 $(n-1)(2n-1)$

 2
 $(n-1)(2n-2)$
 $(2n-2)$
 $(n-1)(2n-2)$

 3
 $(n-1)(2n-3)$
 $(2n-3)$
 $(n-1)(2n-3)$
 \vdots
 \vdots

 K
 $(n-1)(2n-k)$
 $(2n-k)$
 $(n-1)(2n-k)$
 \vdots
 \vdots

 n
 $(n-1)(n)$
 $(n-1)(n)$

Total cost of
$$\hat{A} = \sum_{k=1}^{n} [(n-1)(2n-k) + (2n-k) + (n-1)(2n-k)]$$

$$= \sum_{k=1}^{n} (2n-1)(2n-k)$$

$$= 2n^{2}(2n-1) - (2n-1)\sum_{k=1}^{n} k$$

STUDENTS-HUB.com = $2n^2(2n-1) - (2n-1) \frac{n(n+1)}{2}$ Uploaded By: anonymous = $(2n-1)(2n^2 - \frac{n^2+n}{2})$

$$=\frac{n}{2}\left(2n-1\right)\left(3n-1\right)$$

Hence total cost of solving nxn linear system by inverse method is $\frac{n}{2}(2n-1)(3n-1) + n(2n-1) = \frac{n}{2}(2n-1)(3n+1)$

We will study the following three Methods:

I Newton's Method > for 2x2 nonlinear system

[3] Gauss-Seidel Iteration Jonalinear systems

I Newton's Method

· Given 2x2 non linear system

$$f(x_1y) = 0$$
$$g(x_1y) = 0$$

with initial point (xo, yo)

· This method find a sequence of points (x, y,), (x, y,), that approximates (x, y)

· We will only find (x1, y,) as follow:

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$$X_0$$
 $= \frac{1}{J(x_0, y_0)} \left(f(x_0, y_0) \right)$ $= \frac{1}{J(x_0, y_0)} \left(g(x_0, y_0) \right)$

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where J is the Jacobian matrix given by

$$\overline{J}(x,y) = \begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix}$$

$$x^{2} + y^{2} = 10$$

 $xy = 5$

•
$$x^2 + y^2 - 10 = 0$$
 $\Rightarrow f(x,y) = x^2 + y^2 - 10$
 $xy - 5 = 0$ $\Rightarrow g(x,y) = xy - 5$

•
$$(x_0, y_0) = (1, \frac{1}{2}) \implies f(1, \frac{1}{2}) = 1 + 0.25 - 10 = -8.75$$

 $g(1, \frac{1}{2}) = 1 - 5 = -4.50$

$$J(x,y) = \begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix} = \begin{pmatrix} 2x & 2y \\ y & x \end{pmatrix} J(1,\frac{1}{2}) = \begin{pmatrix} 2 & 1 \\ 0.5 & 1 \end{pmatrix}$$

$$\overline{J}(1,\frac{1}{2}) = \frac{1}{1.5} \begin{pmatrix} 1 & -1 \\ -0.5 & 2 \end{pmatrix} = \begin{pmatrix} 0.667 & -0.667 \\ -0.334 & 1.33 \end{pmatrix}$$

$$\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} - \frac{-1}{J}(x_0, y_0) \begin{pmatrix} f(x_0, y_0) \\ g(x_0, y_0) \end{pmatrix}$$

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$$\begin{pmatrix} 1 \\ 0.5 \end{pmatrix} - \begin{pmatrix} 0.667 & -0.667 \\ -0.334 & 1.33 \end{pmatrix} \begin{pmatrix} -8.75 \\ -4.50 \end{pmatrix}$$
 Uploaded By: anonymous $\begin{pmatrix} 1 \\ 0.5 \end{pmatrix} - \begin{pmatrix} -2.84 \\ -3.07 \end{pmatrix} = \begin{pmatrix} 3.84 \\ 3.57 \end{pmatrix}$

To find
$$\begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} - \overline{J}(x_1, y_1) \begin{pmatrix} f(x_1, y_1) \\ g(x_1, y_1) \end{pmatrix}$$

Exp Find the first iteration that approximates
the solution of the following nonlinear system $x^{2}-2x-y+0.5=0$

$$x^{2} + yy^{2} - y = 0$$

using Newton's method and starting with (2, 0.25).

•
$$f(X_1y) = x^2 - 2x - y + 0.5 \Rightarrow f(2, 0.25) = 0.25$$

 $g(x_1y) = x^2 + 4y^2 - 4 \Rightarrow g(2, 0.25) = 0.25$

•
$$(x_0, y_0) = (2, 0.25)$$

$$\cdot \quad \overline{J(x_1 y)} = \begin{pmatrix} 2x - 2 & -1 \\ 2x & 8y \end{pmatrix} \Rightarrow \overline{J(z_1 0.25)} = \begin{pmatrix} 2 & -1 \\ 4 & 2 \end{pmatrix}$$

•
$$\overline{J}(2,0.25) = \frac{1}{8} \begin{pmatrix} 2 & 1 \\ -4 & 2 \end{pmatrix} = \begin{pmatrix} 0.25 & 0.125 \\ -0.5 & 0.25 \end{pmatrix}$$

$$\begin{pmatrix} X_1 \\ Y_1 \end{pmatrix} = \begin{pmatrix} 2 \\ 0.25 \end{pmatrix} - \begin{pmatrix} 0.25 & 0.125 \\ -0.5 & 0.25 \end{pmatrix} \begin{pmatrix} 0.25 \\ 0.25 \end{pmatrix}$$

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$$(0.0938)$$
 $-(0.0625)$

 $= \begin{pmatrix} 1.91 \\ 0.313 \end{pmatrix}$

• Given the following nonlinear system f(x,y) = 0

$$9(x_1y) = 0$$

starting at (xo, yo)

. The Taylor series expansions of f and g at (xo, yo) are

$$f(x_1y) \approx f(x_0, y_0) + f_x(x-x_0) + f_y(y-y_0)$$

 $g(x_1y) \approx g(x_0, y_0) + g_x(x-x_0) + g_y(y-y_0)$

· But f(x,y) = g(x,y) = 0 =>

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} f(x_0, y_0) \\ g(x_0, y_0) \end{pmatrix} + \begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix} \begin{pmatrix} x - x_0 \\ y - y_0 \end{pmatrix}$$

· Multiply both sides by J(x0,40) >>

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \overline{J} \begin{pmatrix} f(x_0, y_0) \\ g(x_0, y_0) \end{pmatrix} + \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$

students-Hub.com the last equation =)

$$\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} - \frac{-1}{J}(x_0, y_0) \begin{pmatrix} f(x_0, y_0) \\ g(x_0, y_0) \end{pmatrix}$$

. This method can be used to solve 2x2 or 3x3 nonlinear systems:

$$f_1(x_1y) = 0$$

 $f_2(x_1y) = 0$

$$f_1(x_1y, z) = 0$$

 $f_2(x, y, z) = 0$

 $f_3(x,y,z) = 0$

· For 2x2 system:

$$\rightarrow \text{ write } x = g_1(x,y)$$

$$y = g_2(x,y)$$
(1)

> The FPI is

$$P_{n+1} = g_1(P_n, q_n)$$

· For 3x3 system:

⇒ Write
$$x = g_1(x, y, z)$$

 $J = g_2(x, y, z)$ (2)
 $Z = g_3(x, y, z)$

-> The FPI is

Def. The point (P, 7) is fixed point of the system (1) if

$$P = 9, (P, 9)$$
 and

n=0,1,2,...

STUDENTS-HUB.com $q = g_2(p,q)$.

· The point (P, 7, r) is fixed point of the system (2) If

$$P = 9, (P, 2, r)$$
 and

$$9 = 9_2(P, 9, r)$$
 and

$$r = g_3(P, q, r)$$
.

Find the fixed points of the following system
$$x - \sin y = 0$$

$$x^2 + \cos^2 y = \frac{y}{\pi} + \frac{1}{2}$$

•
$$x = g(x,y) \Leftrightarrow x = siny$$

$$y = g_2(x, y) \iff y = (x^2 + \cos^2 y) - \frac{1}{2}) \pi$$

Hence,
$$(P,q) = (x,y) = (1, \mathbb{T})$$
 is fixed point

Exp Consider the following nonlinear system:

$$x^{2}+y^{2}-x=0$$

 $x^{2}+y^{2}-y=0$

Use initial approximation (Po, 90) = (0.5, 0.4) to find the next three approximation using the FPI. (3-digits)

•
$$x = g_1(x, y) = x^2 + y^2$$
 $\Rightarrow P_{n+1} = P_n^2 + P_n^2$
 $y = g_2(x, y) = e^x + y^2$ $\Rightarrow P_{n+1} = e^x + P_n^2$

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•
$$P_1 = 9_1(P_0, P_0) = 9_1(0.5, 0.4) = 0.25 + 0.16 = 0.41$$
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$$P_1 = 9_2(P_0, P_0) = 9_2(0.5, 0.4) = 1.65 + 0.16 = 1.81$$

•
$$P_2 = g_1(P_1, q_1) = g_1(0.41, 1.81) = 0.168 + 3.28 = 3.45$$

 $q_2 = g_2(P_1, q_1) = g_2(0.41, 1.81) = 1.51 + 3.28 = 4.79$

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$$q_3 = g_2(p_2, q_2) = g_2(3.45, 4.79) = 31.5 + 22.9 = 54.4$$

· Note that the FPI here divergs (see 3 in Remark below).

Th* (Convergence of FPI - Two dimensions)

- . Assume (P, q) is fixed point of x = g(x, y) and $y = g_2(x, y)$.
- If (P_0, P_0) is sufficiently close to (P_1, P_1) and if $\left|\frac{\partial g_1}{\partial x}(P_1, P_2)\right| + \left|\frac{\partial g_1}{\partial y}(P_1, P_2)\right| < 1 \quad \text{and} \quad \left|\frac{\partial g_2}{\partial x}(P_1, P_2)\right| + \left|\frac{\partial g_2}{\partial y}(P_1, P_2)\right| < 1$

then the FPI converges to the fixed point (P, 9)

Remarks: [] Converges of FPI for three dimensions follows similarly to The above by adding z-component.

[2] In Exp page 81 => note that

(A) ---
$$\left|\frac{\partial x}{\partial y}\right| + \left|\frac{\partial y}{\partial y}\right| = 2|x| + 2|y| < 1 \Leftrightarrow |x| + |y| < \frac{1}{2}$$

$$(B) - \left| \frac{\partial g_2}{\partial x} \right| + \left| \frac{\partial g_2}{\partial y} \right| = e^{x} + 2|y| < 1$$

but (Po, 90) = (0.5, 0.4) does not satisfy (A).

That is why the FPI in this Exp* diverges from the fixed point.

Exercise I Find the fixed point in Expx

2 Solve Exp* again using (Po, Po) = (-0.45, 0.04) and show the FPI still diverges.

Exp Consider the following nonlinear system:

$$x^2 + yy^2 = y$$
 "Ellipse"

Use the FII to approximate the solutions

$$x = 9_1(x,y) = \frac{x^2 + 0.5}{2}$$

$$y = g_2(x_1y) = \frac{-x^2 - yy^2 + 8y + y}{8}$$
 add to each side

· This system has two solutions (or fixed points of *):

$$(P, 9) \in \{ (-0.2, 1), (1.9, 0.3) \}$$

· To find the first solution (P,q) = (-0.2, 1) we apply formula * as follows:

$$P_{n+1} = \frac{P_n^2 - q_n + 0.5}{2} = g_1(P_n, q_n)$$

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$$\frac{-P_n^2 - 4 \frac{9^2}{7^n} + 8 \frac{9}{7^n} + 4 \frac{9}{7^n}}{8} = g_2(P_n, q_n)$$

è	(1) (Po, 40) =	(0,1)
n	Pn	9 _n
1	-0.25	l
2	-0.21875	0.9921875
3	-0.2221680	0.9939880
4	-0.2223147	0.9938121
5	-0.2221941	0.9938029
6	-0.2222163	0.9938095

	12) (Po, 90) = (2,0)					
n	Pn	9 _n				
١	2.25	0				
2	2.78125	-0.1328125				
3	4.184082	-0.6085510				
4	9.307547	-2.4870360				
5	44.80623	-15.891091				
6	1011.995	-392.60426				

This FPI converges to the first solution

This FPI diverges

· Note that Theorem in page 82 can be used to show that iteration (1) converges to the fixed point near (-0.2, 1):

$$\left|\frac{\partial g_{1}}{\partial x}\right| + \left|\frac{\partial g_{1}}{\partial y}\right| = |x| + 0.5 < 1 \iff |x| < 0.5$$

$$\left|\frac{\partial g_{2}}{\partial x}\right| + \left|\frac{\partial g_{2}}{\partial y}\right| = \frac{|x|}{y} + \left|1-y\right| < \frac{0.5}{y} + \left|1-y\right| < 1 \iff 0.125 < y < 1.875$$

- . The fixed point (9,q)=(-0.2,1) satisfy (2) and so Th implies that the FPI converges to (9,q)=(-0.2,1).
- · However, the fixed point (P,q) = (1.9,0.3) does not satisfy (2):

$$\left| \frac{\partial 9}{\partial x} (1.9, 0.3) \right| + \left| \frac{\partial 9}{\partial y} (1.9, 0.3) \right| = 2.4 > 1$$
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$$\left| \frac{\partial 9}{\partial x} (1.9, 0.3) \right| + \left| \frac{\partial 9}{\partial y} (1.9, 0.3) \right| = 1.16 > 1$$

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so the FPI diverges from (1.9, 0.3) if we use (1).

· Hence, the iteration (1) can not be used to find the second solution (1.9,0.3).

- · To find this solution, we need a different formula for this iteration (1).
- If we add -2x to the first equation and -114 to the second equation, we get

$$x^{2} - 4x - y + 0.5 = -2x$$

 $x^{2} + 4y^{2} - 11y - 4 = -11y$

· The iteration now is

$$P_{n+1} = g_1(P_n, q_n) = \frac{-P_n^2 + 4P_n + P_n - 0.5}{2}$$

$$q_{n+1} = q_2(p_n, q_n) = \frac{-p_n^2 - q_{n+1}^2 + 11q_n + q_n}{11}$$

· Starting from same point (Po, 90) = (2,0) =)

	•	•	
	n	Pn	9n
	. 1	1.75	0
	2	1.71875	0.0852273
	3	1.753063	0.1776676
	4	1.808345	0.2504410
	8	1.903595	0.3160782
	12	1.900924	0.3112267
	16	1.900652	0.3111994
STUDENTS-HUB	.com	1.900677	0.3112196
			The state of the s

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The FPI converges to the second solution using formula (2)

3 Seidel Iteration (Improvement of FPI) 86

· This method can be used to solve zxz or 3x3 non linear systems:

$$f_1(x_1y) = 0$$

 $f_2(x_1y) = 0$

or
$$f_1(x,y,z) = 0$$

 $f_2(x,y,z) = 0$
 $f_3(x,y,z) = 0$

· For 2x2 system:

$$\rightarrow$$
 Write $x = g_1(x_1y)$

- The Seidel Iteration is

$$f_{n+1} = 9(p_n, q_n)$$

$$q_{n+1} = g_2(P_{n+1}, q_n)$$

· For 3x3 system:

$$\rightarrow$$
 Write $x = g(x, y, z)$

-> The Seidel Iteration is

Exp. Consider the following nonlinear system:

STUDENTS-LYUB.com - x 2+4

- · Use Seidal iteration to find the next two approximations if the initial approximation of the solution is (1,-1,2).
- · Use 4 significant digits.

•
$$x = g_1(x,y,z) = e^x + zy$$

 $y = g_2(x,y,z) = xy - x^2z + y$
 $z = g_3(x,y,z) = x^2 - yz$

•
$$f_1 = g_1(1, -1, 2) = e - 2 = 0.7180$$

 $f_2 = g_2(0.7180, -1, 2) = -0.7180 - (0.5155)(2) + y = 2.25$
 $f_3 = g_3(0.7180, 2.251, 2) = 0.5155 - 4.502 = -3.987$

•
$$f_2 = g_1(f_1, f_1, r_1) = g_1(0.7180, 2.251, -3.987) = -6.925$$

 $f_2 = g_2(-6.925, 2.251, -3.987) = -202.8$
 $f_3 = g_3(-6.925, -202.8, -3.987) = -760.6$