

### Chap 3 Differentiation

(1)

$$* f'(x_0) = \lim_{h \rightarrow 0} \frac{f(x_0 + h) - f(x_0)}{h}$$

\* If  $f$  is diff at  $x=c$  Then  $f$  is cont at  $x=c$

• Diff Rules:-

$$1- (f(x) \pm g(x))' = f'(x) \pm g'(x)$$

$$2- (f(x) \cdot g(x))' = f(x)g'(x) + g(x)f'(x)$$

$$3- \left( \frac{f(x)}{g(x)} \right)' = \frac{g(x)f'(x) - f(x)g'(x)}{[g(x)]^2} \quad g(x) \neq 0$$

$$4- (f \circ g)'(x) = f'(g(x)) \times g'(x)$$

$$4. (f \circ g)'(x) = f'(g(x)) \times g'(x)$$

### • Derivative & Trigonometric

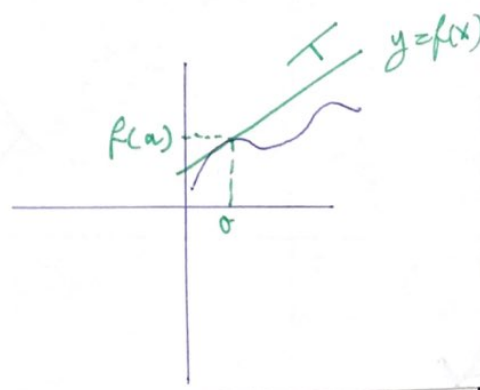
- $(\sin x)' = \cos x$
- $(\cos x)' = -\sin x$
- $(\tan x)' = \sec^2 x$
- $(\cot x)' = -\csc^2 x$
- $(\sec x)' = \sec x \tan x$
- $(\csc x)' = -\csc x \cot x$

### Tangent & Normal

#### • Tangent

$$y - y_0 = m(x - x_0)$$

$$(x_0, y_0) = (a, f(a)) / m = f'(a)$$



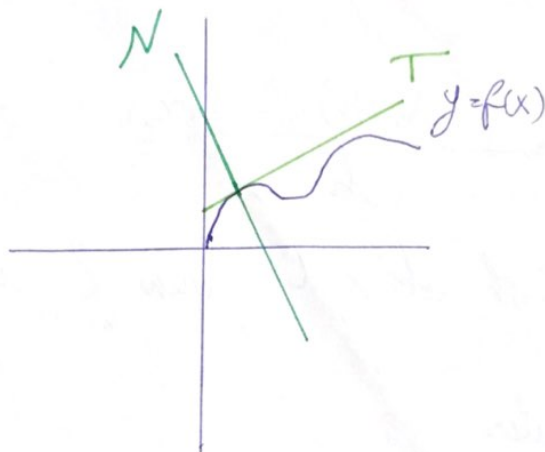
Normal

$$y - y_0 = n(x - x_0)$$

$$(x_0, y_0) = (a, f(a))$$

$$n = \frac{-1}{m}$$

$$mn = -1$$



Implicit differentiation

$\frac{dy}{dx} \rightarrow$  dependant on  $x$  so we diff  $\rightarrow$  respect to  $x$   
 $\frac{dx}{dx} \rightarrow$  Independent

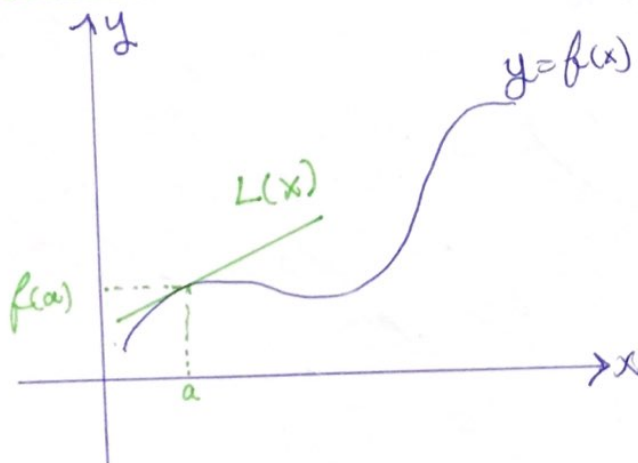
linearization

If  $f$  is diff function at  $x=a$   
 Then The linearization of  $f$  at  $x=a$  is

# linearization

If  $f$  is diff function at  $x=a$   
Then The linearization of  $f$  at  $x=a$  is defined by:-

$$L(x) = f(a) + f'(a)(x-a)$$



حيث  $L$  هو تقريب  
لـ  $f$  (النقطة القريبة من  $a$ )  
 $L(x)$  approximate  $f(a)$  near  
by  $x=a$   
 $L(x) \approx f(x)$   
(Prove) :-  
 $y - y_0 = m(x - x_0)$   
 $(x_0, y_0) = (a, f(a))$   
 $f'(a) = m$   
 $y - f(a) = f'(a)(x - a)$   
 $y = f'(a)(x - a) + f(a)$   
#

(2)

$L(x)$  is the standard linear approximation of  $f(x)$   
near  $x=a$

\* if  $y=f(x)$  is diff at  $x=a$  Then  $\frac{dy}{dx} = f'(x) \Big|_{x=a} = f'(a)$

$$\rightarrow dy = f'(a) dx$$

• dependant variable

• Independent variable  
 $dx = \Delta x$

$$\boxed{dy \approx \Delta y = \Delta f}$$

estimated value      True value

$$\boxed{\Delta L \approx \Delta y}$$

• result: we use the differential  $dy$  to estimate The True change  $\Delta y$

$$\text{Error} = |T - E|$$

