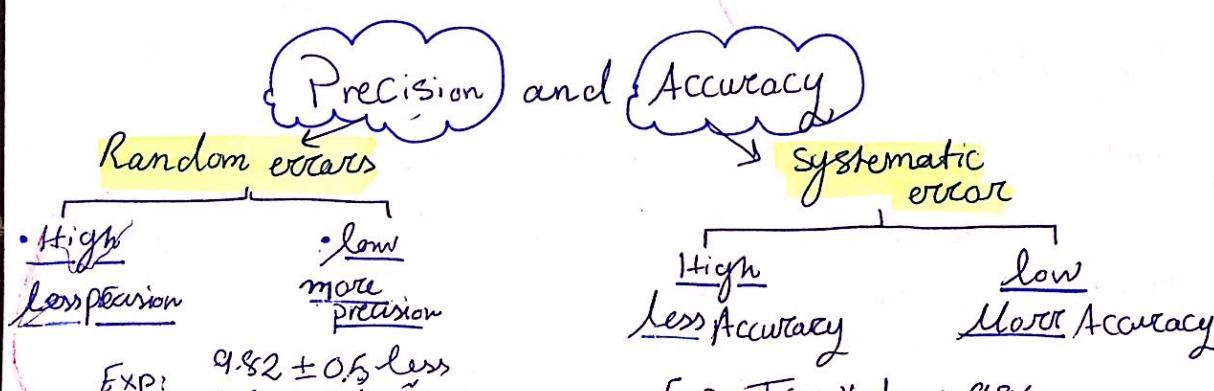
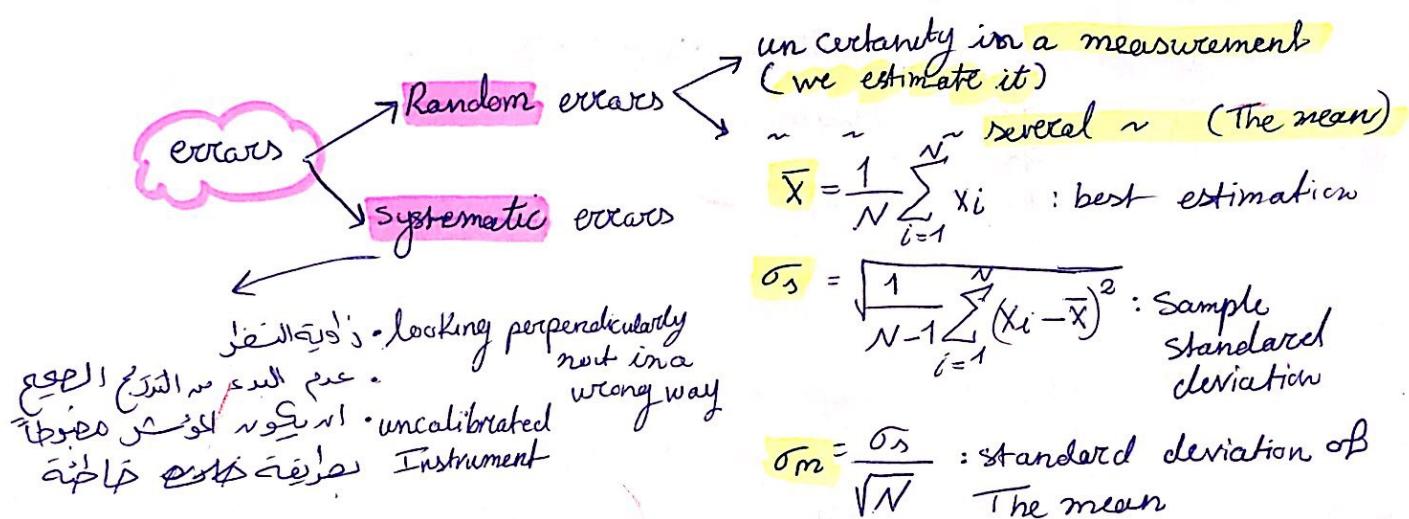


# Measurements and Uncertainties

## Sources of errors:-

- 1- Choice of instruments
- 2- The Experimenter
- 3- The Environment
- 4- The way The experiment is done
- 5- The way The physical quantity is measured

- A measurement can never be taken without any error. But it can be estimated when all errors are very small



Exp: True value: 9.86

$$x_A = 9.82 \pm 0.01 \rightarrow \text{More Accurate}$$

$$x_B = 10.1 \pm 0.1 \rightarrow \text{Less Accurate}$$

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## Discrepancy test : accepted / not accepted

\* True value  $X$

\* Result  $\bar{X} \pm \Delta X$

- steps :

$$1 - D = |X - \bar{X}|$$

$$2 - 2^{\times} \Delta X$$

3 - if  $D > 2\Delta X$  not accepted

if  $D \leq 2\Delta X$  accepted

## significant figures

• حس الارقام المكتوبة التي يمكن عدّها

Exp: 900: 1 significant

900: 3 ~

900.0: 4 sig

0.020: 2 sig

$\Delta X$ : should always be 1 sig figure

unless the leading digit was one

Then we keep the digit after Exp  $0.123 \approx 0.12$

$0.16 \approx 0.17$

or 1.6

## Roundling Rules :-

- any number less than 5 we fix the sig. fig
- " " more ~ 5 we round the last sig fig up
- If it was 5: Exp  $3,5 \rightarrow 40$

$$\begin{array}{r} 45 \\ \text{drop off 8} \\ \hline 40 \end{array}$$

$$\begin{array}{r} 0.7251 \\ \text{drop off 5} \\ \hline 0.73 \end{array}$$

## Values

### \* Addition and subtraction

- The no with the fewest decimal places limits the number of decimal places in the result  
→ eg. 2.333

### \* Multiplication and division

- we find how much of sig fig there is in the numbers multiplied: The less controls the result  
→ eg. 2.333

$$\sqrt{13} = \underline{3.682} \approx 3.7$$

$$\sqrt{2.4 + 10.2} = \sqrt{12.6} = 3.549 \text{ accurate to } 3 \text{ s.f.}$$

$$\begin{aligned}\sin(24) &= (0.406) \\ &\approx 0.41\end{aligned}$$

$$\cos(70) = \frac{0.342}{\approx 0.3}$$

## Uncertainty

### \* Addition and subtraction

$$R = x \pm y, \quad \Delta R = \Delta x + \Delta y : \text{general rule}$$

### \* Constant multipliers

$$R = ax \pm by, \quad \Delta R = a\Delta x + b\Delta y$$

But if  $a$  and  $b$  are not const  
Then  
 $\Delta R = a\Delta x + x\Delta a + b\Delta y + \Delta b$

### \* Multiplication and division

$$A = xy$$

$$\frac{\Delta A}{A} = \frac{y\Delta x + x\Delta y}{xy} \quad \text{for 2 values}$$

$$\frac{\Delta A}{A} = \frac{y\Delta x}{xy} + \frac{x\Delta y}{xy} \quad \text{for more than 2 values}$$

$$= \frac{\Delta x}{x} + \frac{\Delta y}{y}$$

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\* Raising to powers

$$R = X^l Y^m Z^n$$

$$\frac{\Delta R}{R} = |l| \frac{\Delta X}{X} + |m| \frac{\Delta Y}{Y} + |n| \frac{\Delta Z}{Z}$$

\*  $R = e^x$

$$\hookrightarrow \Delta R = e^x \Delta x$$

\*  $R = \ln X$

$$\hookrightarrow \Delta R = \frac{1}{X} \Delta x$$

\*  $R = \sin \theta$

$$\hookrightarrow \Delta R = \cos \theta \Delta \theta$$

\*  $R = \cos \theta$

$$\hookrightarrow \Delta R = -\sin \theta \Delta \theta$$

Radius  $\rightarrow$   $\sqrt{x^2 + y^2}$   $\rightarrow$   $\theta = \tan^{-1} \frac{y}{x}$

$2\pi \rightarrow 180^\circ$  طرفة عين

الاستعاضة الصغرى

$$\bullet R = R(X, Y, Z)$$

$$\hookrightarrow \bullet \Delta R = \left| \frac{\partial R}{\partial X} \right| \Delta x + \left| \frac{\partial R}{\partial Y} \right| \Delta y + \left| \frac{\partial R}{\partial Z} \right| \Delta z$$

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