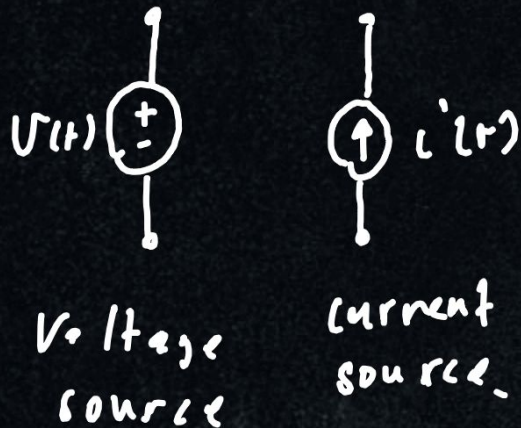


CH 9: Sinusoidal Steady State Analysis

Sinusoidal source:- The source that produces a voltage or current varies sinusoidally with time.



$$x(t) = X_m \sin(\omega t + \phi) ; x \in \{v, i\}$$

where X_m : peak, magnitude, or amplitude.

ω : Electric radian frequency
[rad/sec]

$$\omega = 2\pi f \rightarrow \text{Frequency [Hz]}$$

$$f = \frac{1}{T} \rightarrow \text{period.}$$

RMS Value of $x(t)$

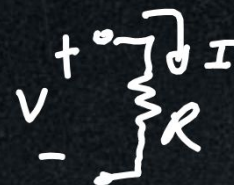
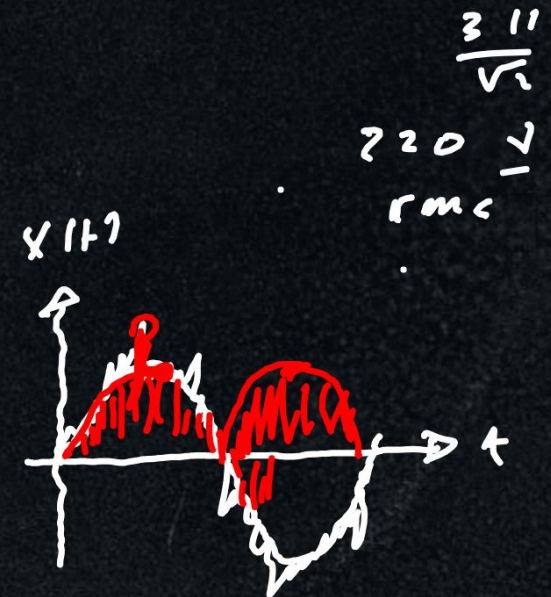


It is defined as the square root of the mean value of the squared function

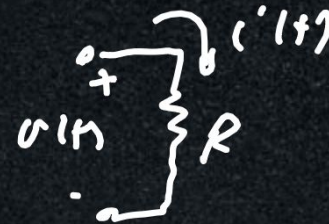
$$X_{RMS} = \sqrt{\frac{1}{T} \int_0^T x^2(t) dt}$$

$$x(t) = X_m \sin(\omega t + \phi)$$

$$X_{RMS} = \frac{X_m}{\sqrt{2}}$$



$$P = VI$$



$$P = \frac{1}{2} V_m I_m = V_{RMS} I_{RMS}$$

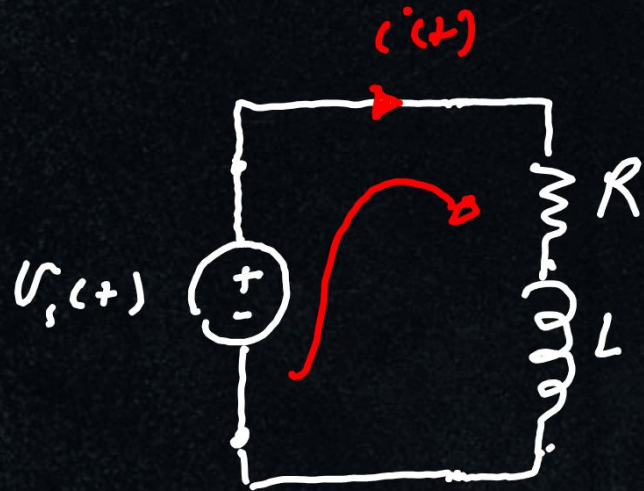
EX: $v(t) = 300 \cos(\underbrace{120\pi t}_w + 30^\circ)$

Calculate

- 1) ω
- 2) ϕ
- 3) T
- 4) Peak Value of $v(t)$
- 5) RMS Value of $v(t)$
- 6) phase angle of $v(t)$

- 1) $\omega = 120\pi \text{ rad/s}$
- 2) $\omega = 2\pi f = 120\pi$
 $f = 60 \text{ Hz}$
- 3) $T = \frac{1}{60} = 16.67 \text{ msec}$
- 4) $V_m = 300 \text{ V}$
- 5) $V_{RMS} = \frac{V_m}{\sqrt{2}} = 212.13 \text{ V}$
- 6) $\phi = 30^\circ = 30^\circ \cdot \frac{\pi}{180} \text{ rad}$

Sinusoidal Response



$$V_s(t) = V_m \cos(\omega t + \phi)$$

The solution is given by :-

$$i(t) = \underbrace{\frac{-V_m}{Z} \cos(\phi - \theta) e^{-t/\tau}}_{\text{Transient Component}} + \underbrace{\frac{V_m}{Z} \cos(\omega t + \phi - \theta)}_{\text{Steady state solution}}$$

Transient Component

$$\tau = L/R, Z = \sqrt{(\omega L)^2 + R^2}$$

$$\theta = \tan^{-1}(\omega L/R)$$

Steady state solution

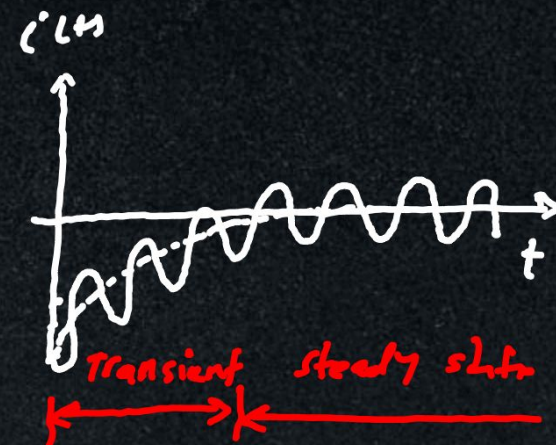
KVL in the loop:-

$$V_s(t) = R i(t) + L \frac{di(t)}{dt}$$

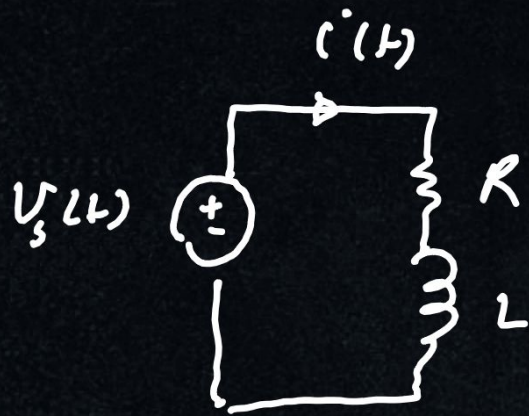
$$V_m \cos(\omega t + \phi) = R i(t) + L \frac{di(t)}{dt}$$

1st order diff. equation

(Linear, non-homog-)



Note: In this chapter, we will focus on the steady solution.



$$\begin{array}{c} \text{source} \\ \text{signal } V_s(t) \\ \hline V_m \cos(\omega t + \phi) \end{array}$$

$$\begin{array}{c} \text{Response} \\ \text{signal } i(t)_{ss} \end{array} \xrightarrow{\text{steady state.}} \frac{V_m}{Z} \cos(\omega t + \phi - \theta)$$

characteristics of SS solution

- sinusoidal function
- ω of source signal = ω of response signal
- peak of source signal = $V_m \neq$ peak of response signal = $\frac{V_m}{Z}$
- phase of source signal = $\phi \neq$ phase of response signal = $\phi - \theta$

The phasor

It is a complex number that carries the amplitude and phase angle of sinusoidal function.

$$x(t) = X_m \cos(\omega t + \phi)$$

$$\vec{X} = \mathcal{P}[x(t)] = \mathcal{P}[X_m \cos(\omega t + \phi)] = X_m \underline{\angle \phi}$$

$$x(t) = \mathcal{P}^{-1}[\vec{X}] = \mathcal{P}^{-1}[X_m \underline{\angle \phi}] = X_m \cos(\omega t + \phi)$$

Form, of phasor

1) Exponential form

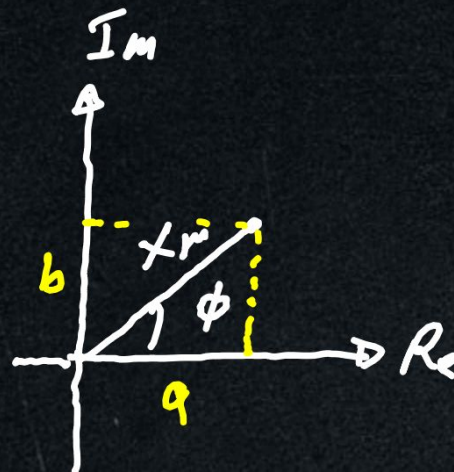
$$\vec{X} = X_m e^{j\phi} \quad ; \quad j = \sqrt{-1}$$

2) Polar form

$$\vec{X} = X_m \angle \phi$$

3) Rectangular form

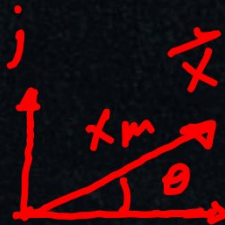
$$\vec{X} = a + jb$$



polar $\longrightarrow$ Rectangular

$$\vec{X} = X_m \angle \theta$$

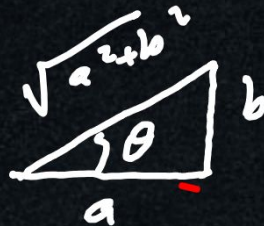
$$\vec{X} = X_m \cos \theta + j X_m \sin \theta$$



Rectangular $\longrightarrow$ polar

$$\vec{X} = a + jb$$

$$\vec{X} = \left(\sqrt{a^2 + b^2} \right) \angle \tan^{-1}(b/a)$$



EX :- $\vec{Y}_1 = 20 \angle -30^\circ$, $\vec{Y}_2 = 40 \angle 60^\circ$

$\underline{A} e^{j\theta_a}$ $\underline{B} e^{j\theta_b}$

Find 1) $\vec{Y}_1 + \vec{Y}_2$

2) $\vec{Y}_1 \vec{Y}_2$

$$1) \vec{Y}_1 + \vec{Y}_2 = 20 \angle -30^\circ + 40 \angle 60^\circ$$

$$= (7.32 - j10) + (20 + j34.64)$$

$$= 27.32 + j24.64$$

$$= 44.72 \angle 33.43^\circ$$

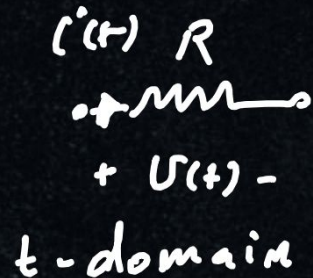
$$2) \vec{Y}_1 \vec{Y}_2$$

$$= (20(40)) \angle -30^\circ + 60^\circ$$

$$= 800 \angle 30^\circ$$

Passive elements in phasor-domain

① Resistor

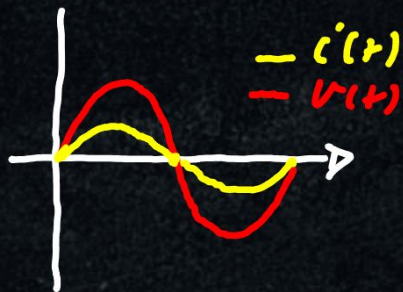


$$U(t) = R i(t)$$

Assume that

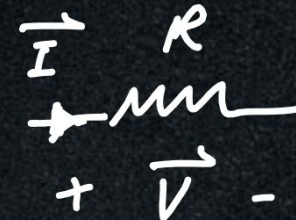
$$i(t) = I_m \cos(\omega t + \theta_i) \xrightarrow{P} \vec{I} = I_m \angle \theta_i$$

$$U(t) = R I_m \cos(\omega t + \theta_i) \xrightarrow{P} \vec{V} = (R I_m) \angle \theta_i$$



$$\vec{V} = R (I_m \angle \theta_i) = R \vec{I}$$

$$\boxed{\vec{V} = R \vec{I}}$$



The current & voltage are in-phase.

② Inductor

$i(t)$ L
 $\rightarrow$ 

+ $v(t)$ -

t -domain

$$v = L \frac{di}{dt}$$

Assume that

$$i(t) = I_m \cos(\omega t + \theta_i)$$

$$\underline{\vec{I}} = I_m \angle \theta_i$$

$$v = L \frac{di}{dt} = -\omega L I_m \sin(\omega t + \theta_i) = \omega L I_m \sin(\omega t + \theta_i + 180^\circ)$$

$$v = \omega L I_m \cos(\omega t + \theta_i + 90^\circ)$$

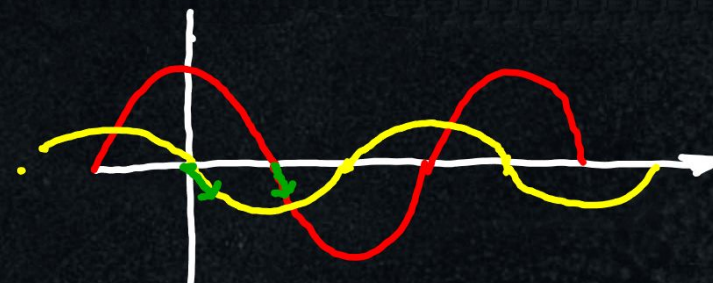
$$\underline{\vec{V}} = \omega L I_m \angle \theta_i + 90^\circ = \omega L I_m e^{j(\theta_i + 90^\circ)}$$

$$\underline{\vec{V}} = j\omega L \underline{I_m e^{j\theta_i}} \Rightarrow \underline{\vec{V}} = (j\omega L) \underline{\vec{I}}$$

$$\theta_v = \theta_i + 90^\circ$$

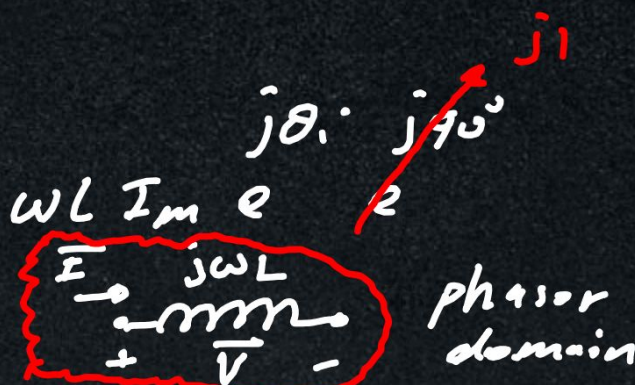
$$\theta_i = \theta_i$$

— $i(t)$
 — $v(t)$

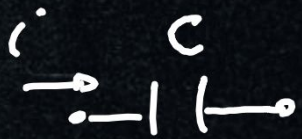


i lags v by 90°

$$\theta_v - \theta_i = 90^\circ$$



③ Capacitor



+ V -

t - domain

$$i = C \frac{dv}{dt}$$

Assume $v = V_m \cos(\omega t + \theta_v)$

$$i = -\omega C V_m \sin(\omega t + \theta_v)$$

$$i = \omega C V_m \sin(\omega t + \theta_v + 180^\circ)$$

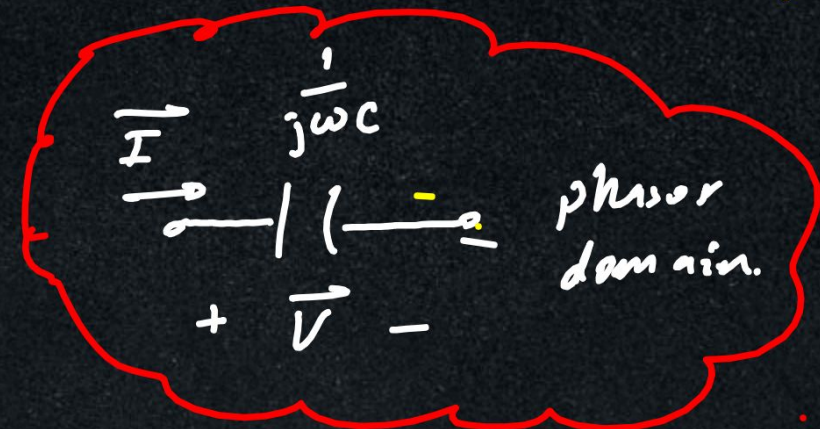
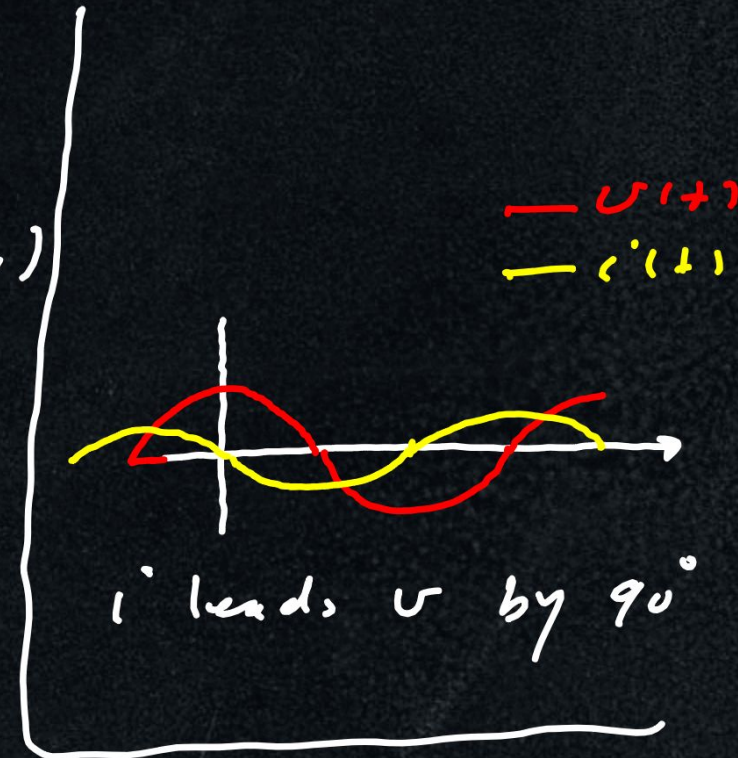
$$i = \omega C V_m \cos(\omega t + \theta_v + 90^\circ)$$

$$\vec{I} = \omega C V_m \angle \theta_v + 90^\circ = \omega C V_m e^{j(90^\circ + \theta_v)}$$

$$\vec{I} = \omega C V_m e^{j\theta_v} e^{j90^\circ}$$

$$\vec{I} = j\omega C \underbrace{V_m e^{j\theta_v}}_{\vec{V}} \Rightarrow \vec{I} = (j\omega C) \vec{V}$$

$$\vec{V} = \left(\frac{1}{j\omega C}\right) \vec{I}$$



	t-domain	phasor-domain	
Resistor	R	R	i & v are in phase.
Inductor	L	$j\omega L$	i lags v by 90°
Capacitor	C	$\frac{1}{j\omega C} = -\frac{j}{\omega C}$	i leads v by 90°

Passive elements in phasor-domain

1) $\begin{array}{ccc} \begin{array}{c} i \\ \rightarrow \\ \text{---} R \text{---} \\ + \quad v \quad - \end{array} & \xrightarrow[\text{phasor transform}]{\mathcal{P}} & \begin{array}{c} \vec{I} \\ \rightarrow \\ \text{---} R \text{---} \\ + \quad \vec{V} \quad - \end{array} \end{array}$ i & v are in-phase

$$v = R i \qquad \vec{V} = R \vec{I}$$

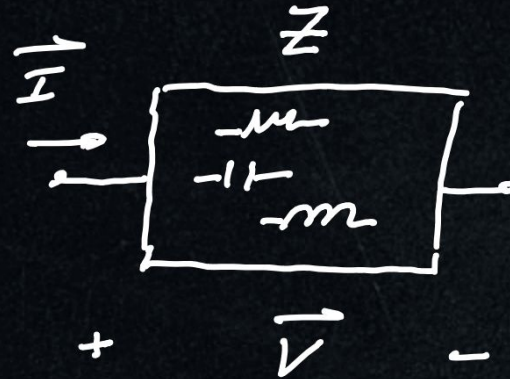
2) $\begin{array}{ccc} \begin{array}{c} i \\ \rightarrow \\ \text{---} L \text{---} \\ + \quad v \quad - \end{array} & \xrightarrow{\mathcal{P}} & \begin{array}{c} \vec{I} \\ \rightarrow \\ \text{---} j\omega L \text{---} \\ + \quad \vec{V} \quad - \end{array} \end{array}$ i lags v by 90° $\theta_v = \theta_i + 90^\circ$

$$v = L \frac{di}{dt} \qquad \vec{V} = (j\omega L) \vec{I}$$

3) $\begin{array}{ccc} \begin{array}{c} i \\ \rightarrow \\ \text{---} C \text{---} \\ + \quad v \quad - \end{array} & \xrightarrow{\mathcal{P}} & \begin{array}{c} \vec{I} \\ \rightarrow \\ \text{---} \frac{1}{j\omega C} \text{---} \\ + \quad \vec{V} \quad - \end{array} \end{array}$ i leads v by 90° $\theta_i = \theta_v + 90^\circ$

$$i = C \frac{dv}{dt} \qquad \vec{V} = \left(\frac{1}{j\omega C}\right) \vec{I}$$

Impedance



$$\vec{V} = Z \vec{I}$$

↓
impedance

The impedance is measured in $[\Omega]$

$$Z = R + jX$$

↓ impedance $[\Omega]$

→ reactance $[\Omega]$

→ resistance $[\Omega]$

	R	X	Z
R	R	0	R
L	0	ωL	$j\omega L$
C	0	$\frac{-1}{\omega C}$	$\frac{-j}{\omega C}$

$$Z = R$$

$$Z = j\omega L$$

$$Z = \frac{-j}{\omega C}$$

Admittance :- It is the reciprocal of impedance
and measured in siemens or $[S]$

$$Y = \frac{1}{Z} = \text{Complex number}$$

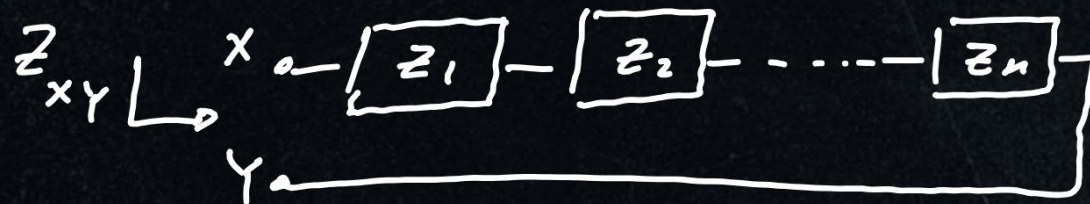
$$Y = G + jB$$

Ad.
 $[S]$

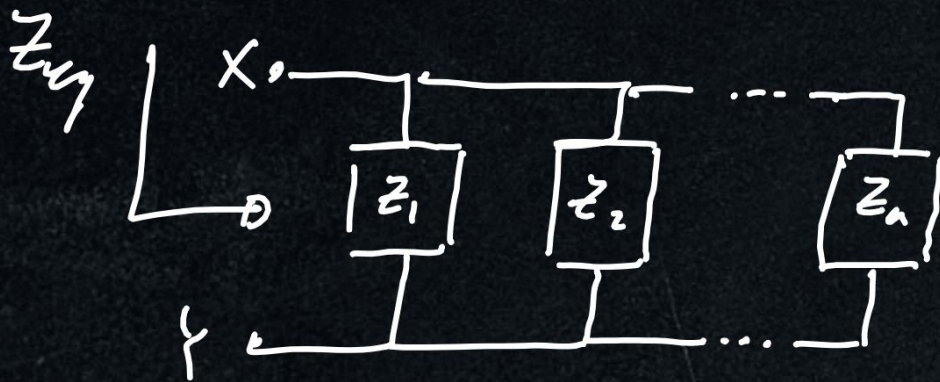
Conductance
 $[S]$

Susceptance
 $[S]$

Impedances in series

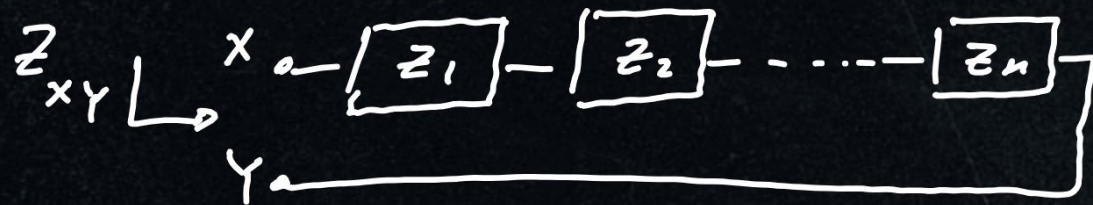


$$Z_{xy} : Z_{xy} = z_1 + z_2 + \dots + z_n$$

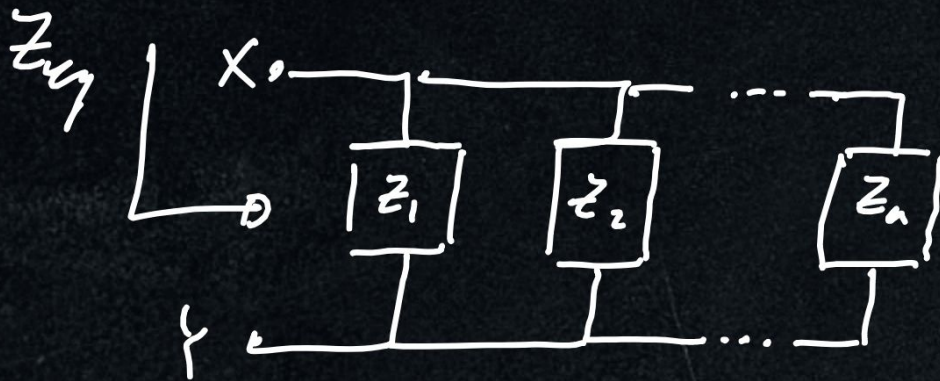


$$Z_{xy} = \frac{1}{\frac{1}{z_1} + \frac{1}{z_2} + \dots + \frac{1}{z_n}}$$

Impedances in series



$$Z_{xy} : Z_{xy} = Z_1 + Z_2 + \dots + Z_n$$



$$Z_{xy} : \frac{1}{Z_1} + \frac{1}{Z_2} + \dots + \frac{1}{Z_n}$$

KVL & KCL

t-domain

$$\sum i| = 0$$

node

$$\sum v| = 0$$

loop

phasor-domain

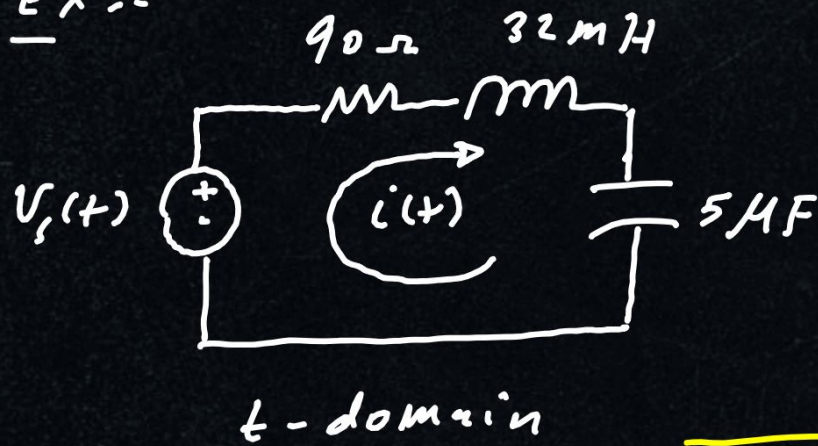
$$\sum \vec{I}| = 0$$

node

$$\sum \vec{V}| = 0$$

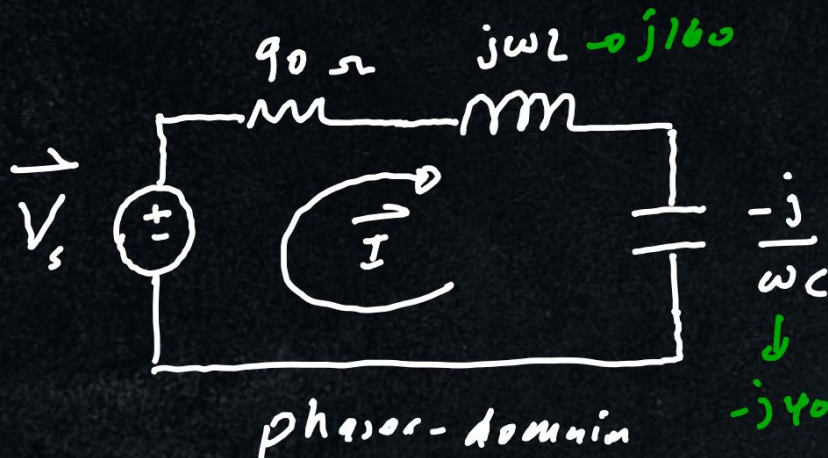
loop

EX:-



calculate the steady state current

$$V_s(t) = 750 \cos(\underbrace{5000t}_{\omega} + 30^\circ) \text{ V}$$



$$\vec{V}_s = 750 \angle 30^\circ \text{ V}$$

$$j\omega L = j5000 \times 32 \times 10^{-3} = j160 \Omega$$

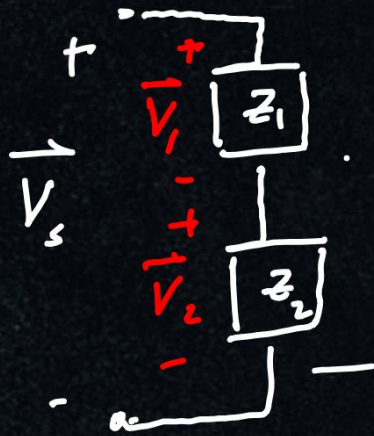
$$\frac{-j}{\omega C} = \frac{-j}{5000 \times 5 \times 10^{-6}} = -j40 \Omega$$

$$\vec{I} = \frac{(\vec{V}_s = 750 \angle 30^\circ)}{90 + j160 - j40} = \frac{750 \angle 30^\circ}{90 + j120} = \frac{750 \angle 30^\circ}{150 \angle 53.13^\circ} = 5 \angle -23.13^\circ$$

$$\vec{I} = 5 \angle -23.13^\circ \text{ A} \Rightarrow i(t) = 5 \cos(5000t - 23.13^\circ) \text{ A}$$

Voltage & Current Dividers

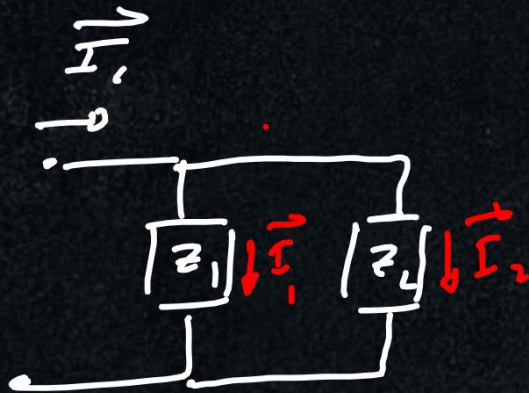
VD



$$\vec{V}_1 = \frac{Z_1}{Z_1 + Z_2} \cdot \vec{V}_s$$

$$\vec{V}_2 = \frac{Z_2}{Z_1 + Z_2} \cdot \vec{V}_s$$

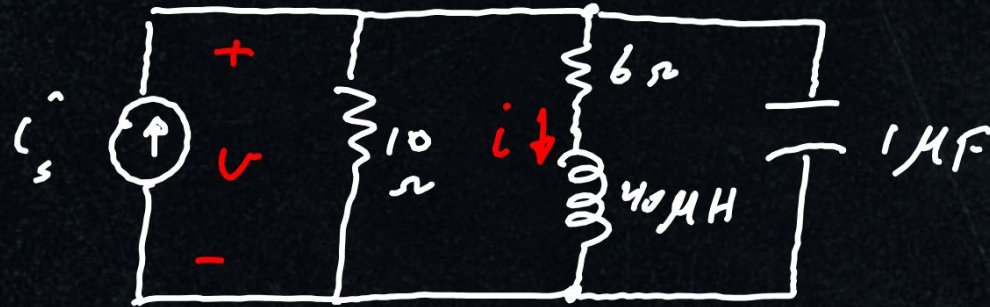
CD



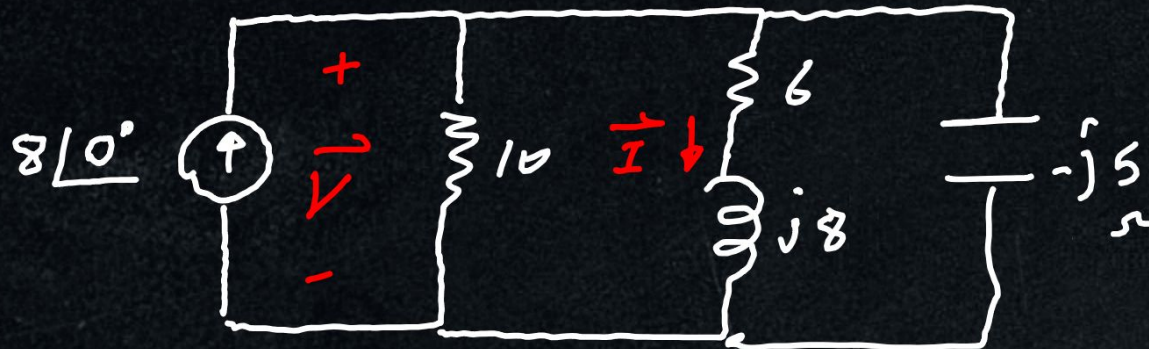
$$\vec{I}_1 = \frac{Z_2}{Z_1} \cdot \vec{I}_s = \frac{Z_2}{Z_1 + Z_2} \cdot \vec{I}_s$$

$$\vec{I}_2 = \frac{Z_1}{Z_2} \cdot \vec{I}_s = \frac{Z_1}{Z_1 + Z_2} \cdot \vec{I}_s$$

Ex:

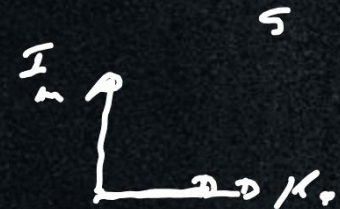
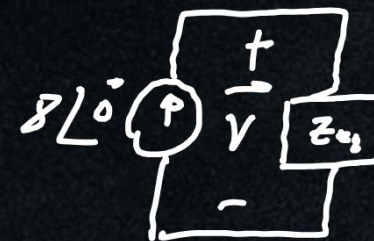
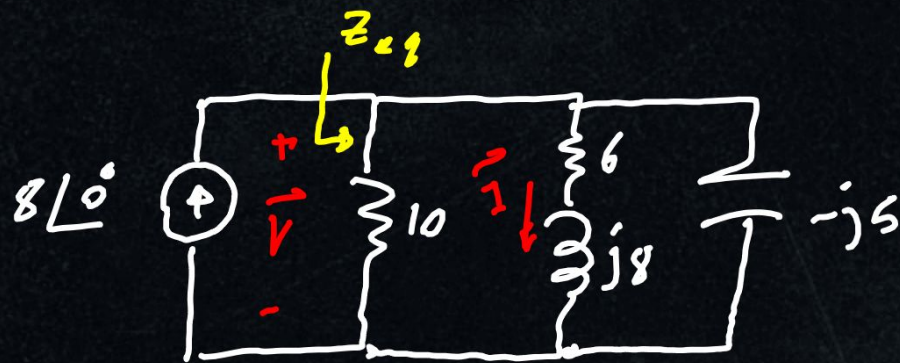


Calculate the steady state expressions for V + i
 $i_s = 8 \cos(20,000t) \text{ A}$



$$j\omega L = j(20,000)(40 \times 10^{-6}) = j8 \Omega$$

$$\frac{-j}{\omega C} = \frac{-j}{20,000(10^{-6})} = -j5 \Omega$$



$$Z_{eq} = \frac{1}{\frac{1}{10} + \frac{1}{6+j8} + \frac{1}{-j5}} = \frac{1}{0.1 + \frac{1\angle 0^\circ}{10\angle 53.13^\circ} + j0.2}$$

$$Z_{eq} = \frac{1}{0.1 + 0.1\angle -53.13^\circ + j0.2} = 5\angle -36.87^\circ \Omega$$

$$\vec{V} = Z_{eq} \vec{I} = (5\angle -36.87^\circ) (8\angle 0^\circ) = 40\angle -36.87^\circ \text{ V}$$

$$v = 40 \cos(20,000t - 36.87^\circ) \text{ V}$$

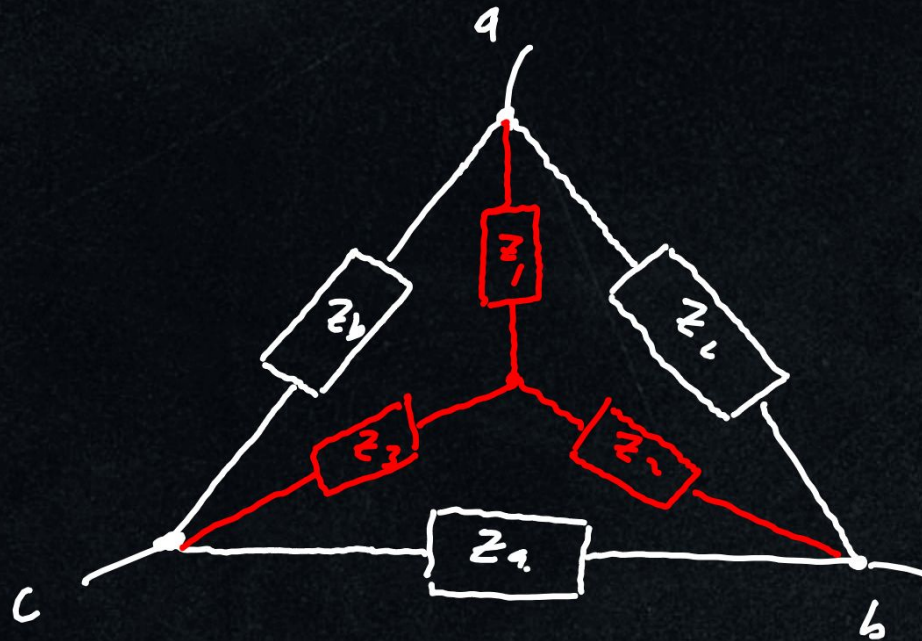


$$\vec{I} = \frac{\vec{V}}{6 + j8} = \frac{40 \angle -36.87^\circ}{6 + j8} = \frac{40 \angle -36.87^\circ}{10 \angle 53.13^\circ}$$

$$\vec{I} = 4 \angle -90^\circ \text{ A}$$

$$i(t) = 4 \cos(20,000t - 90^\circ) \text{ A}$$

$$\underline{Y \rightleftharpoons \Delta}$$



$$Y \rightarrow \Delta$$

$$Z_a = \frac{Z_1 Z_2 + Z_1 Z_3 + Z_2 Z_3}{Z_1}$$

$$Z_b = \frac{Z_1 Z_2 + Z_1 Z_3 + Z_2 Z_3}{Z_2}$$

$$Z_c = (Z_1 Z_2 + Z_1 Z_3 + Z_2 Z_3) / Z_3$$

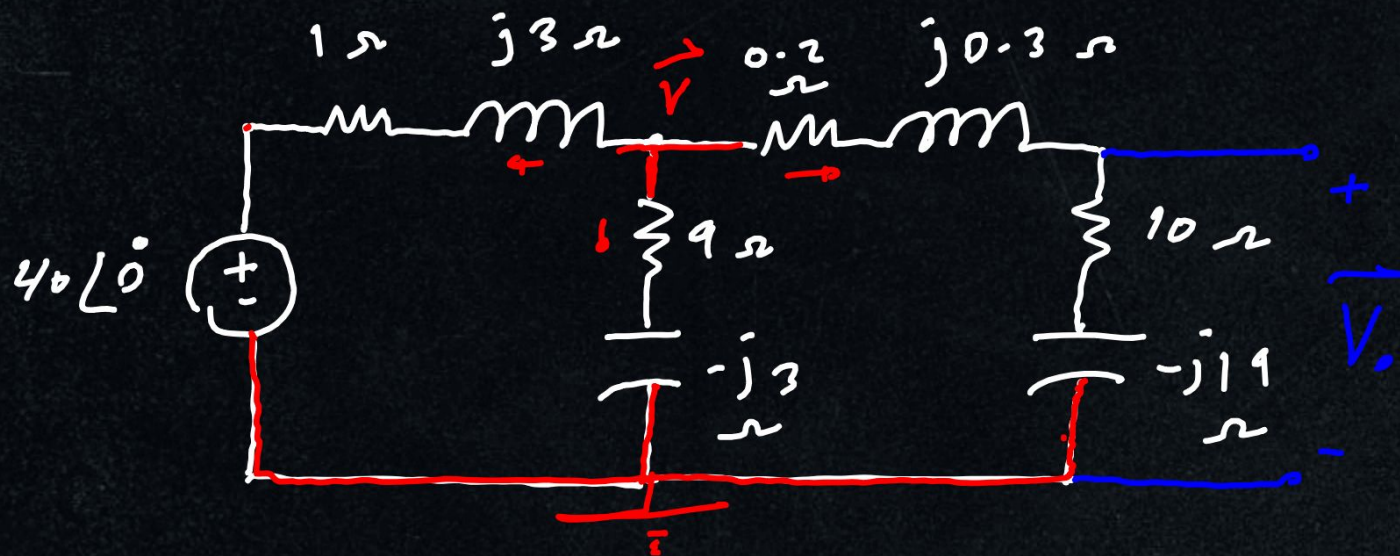
$$\Delta \rightarrow Y$$

$$Z_1 = \frac{Z_b Z_c}{Z_a + Z_b + Z_c}$$

$$Z_2 = \frac{Z_a Z_c}{Z_a + Z_b + Z_c}$$

$$Z_3 = \frac{Z_a Z_b}{Z_a + Z_b + Z_c}$$

EX:- Find $\vec{V}_o$ using Node-voltage method



voltage divider

$$\vec{V}_o = \frac{10 - j19}{10.2 - j18.7} \vec{V}$$

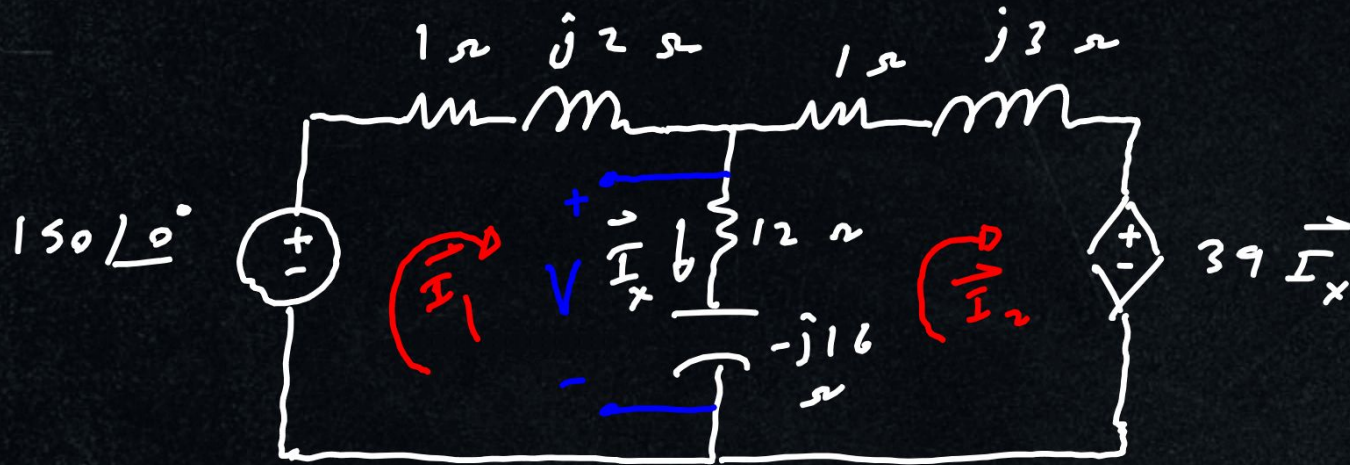
$$\vec{V}_o = 36.12 - j18.84$$

KCL at $\vec{V}$

$$\left(\frac{\vec{V} - 40\angle 0^\circ}{1 + j3} \right) + \left(\frac{\vec{V}}{9 - j3} \right) + \left(\frac{\vec{V}}{10.2 - j18.7} \right) = 0$$

$$\vec{V} \left[\frac{1\angle 0^\circ}{1 + j3} + \frac{1\angle 0^\circ}{9 - j3} + \frac{1\angle 0^\circ}{10.2 - j18.7} \right] = \frac{40\angle 0^\circ}{1 + j3} \Rightarrow \text{Find } \vec{V}$$

EX: Find $\vec{V}$ using Mesh-current method :-



$$150\angle 0^\circ = (1+j2)\vec{I}_1 + (12-j16)(\vec{I}_1 - \vec{I}_2) \quad \dots \textcircled{1}$$

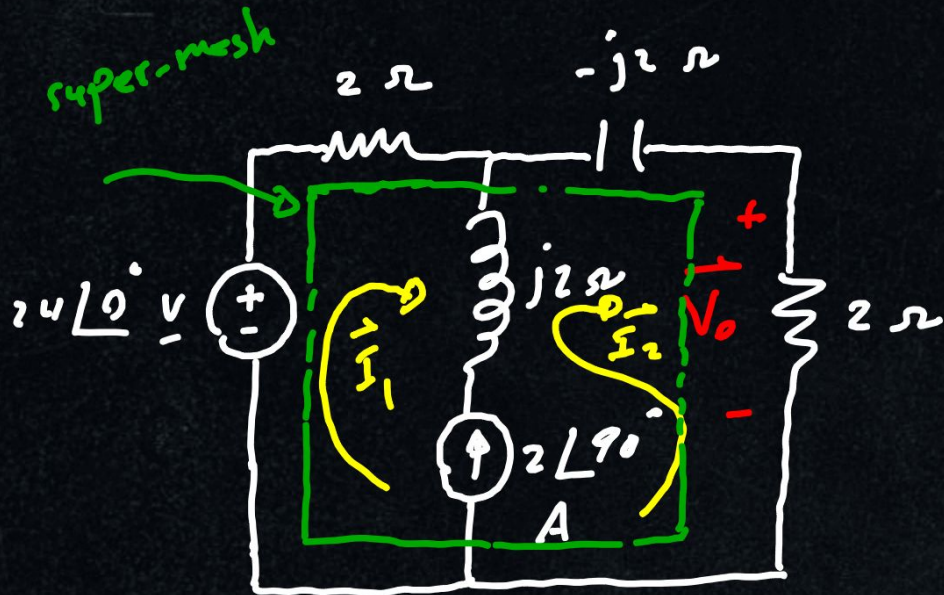
$$(12-j16)(\vec{I}_2 - \vec{I}_1) + (1+j3)\vec{I}_2 + 39\vec{I}_x = 0 \quad \dots \textcircled{2}$$

$$\vec{I}_x = \vec{I}_1 - \vec{I}_2 \quad \dots \textcircled{3}$$

$$\vec{I}_1 = -26 + j52 \text{ A}, \quad \vec{I}_2 = -24 - j58 \text{ A}, \quad \vec{I}_x = -2 + j6 \text{ A}$$

$$\vec{V} = (12-j16)\vec{I}_x = 72 + j104 \text{ V}$$

Ex:- Use (a) Mesh-current method and (b) Thevenin theorem to find $\vec{V}_o$.



(a) KVL in the super-mesh

$$24\angle 0^\circ = 2\vec{I}_1 + (-j2)\vec{I}_2 + 2\vec{I}_2$$

$$24\angle 0^\circ = 2\vec{I}_1 + (2-j2)\vec{I}_2 \quad \text{--- (1)}$$

$$\vec{I}_2 - \vec{I}_1 = 2\angle 90^\circ \quad \text{--- (2)}$$

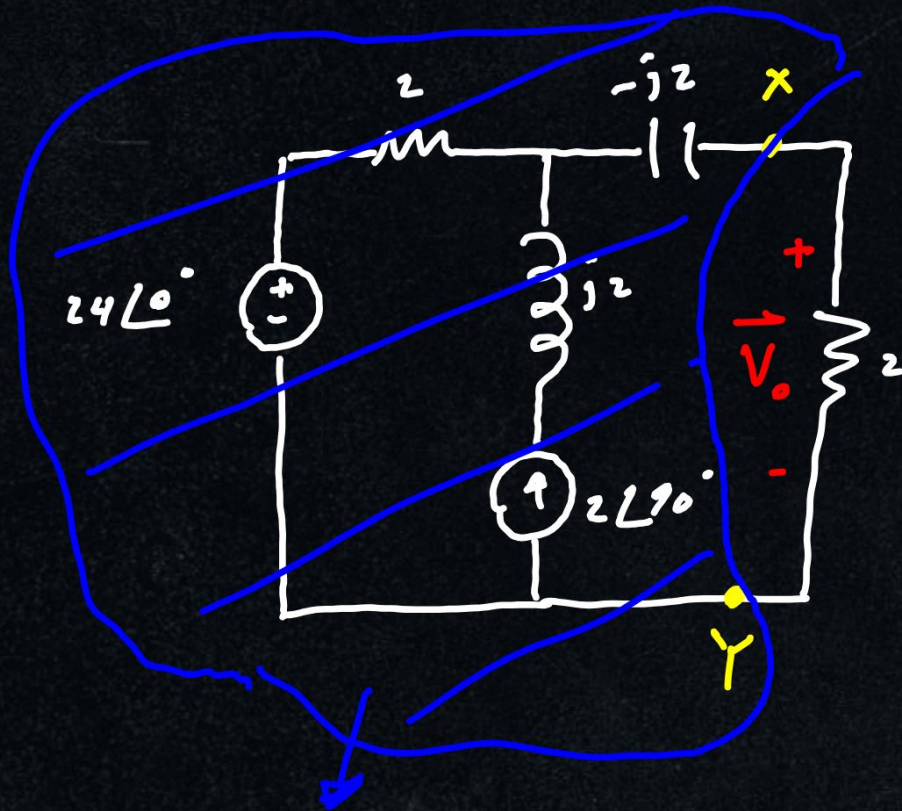
solve for $\vec{I}_2$

(2) $\rightarrow$ (1)

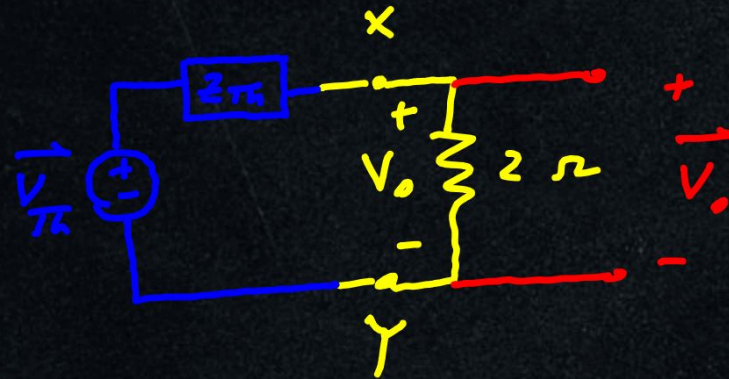
$$\vec{I}_2 = 5.44\angle 36^\circ \text{ A}$$

$$\vec{V}_o = 2\vec{I}_2 = 10.88\angle 36^\circ \text{ V}$$

(b)

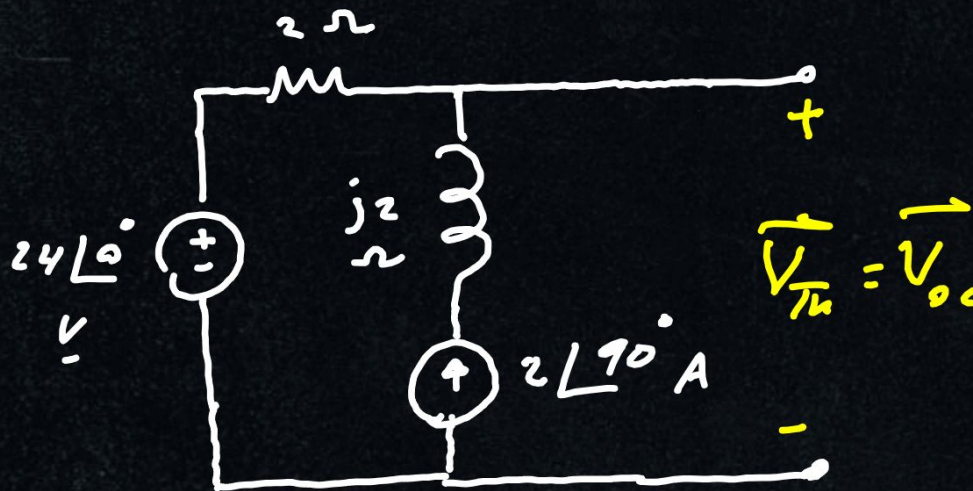


Thevenin
Equivalent
Circuit



$$\vec{V}_o = \frac{2}{2 + Z_{Th}} \cdot \vec{V}_{Th}$$

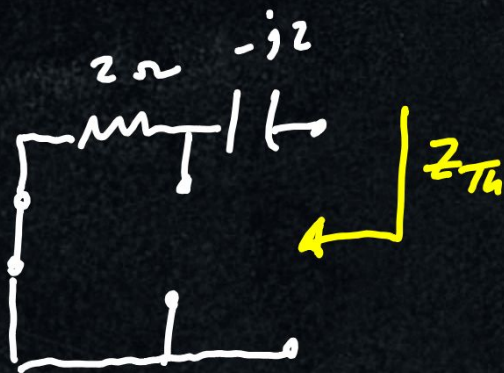
$V_{Th} ??$



$$\vec{V}_{Th} = 2(2\angle 90^\circ) + 24$$

$$\vec{V}_{Th} = 24 + j4 \text{ V}$$

$Z_{Th} ??$ "Method II"

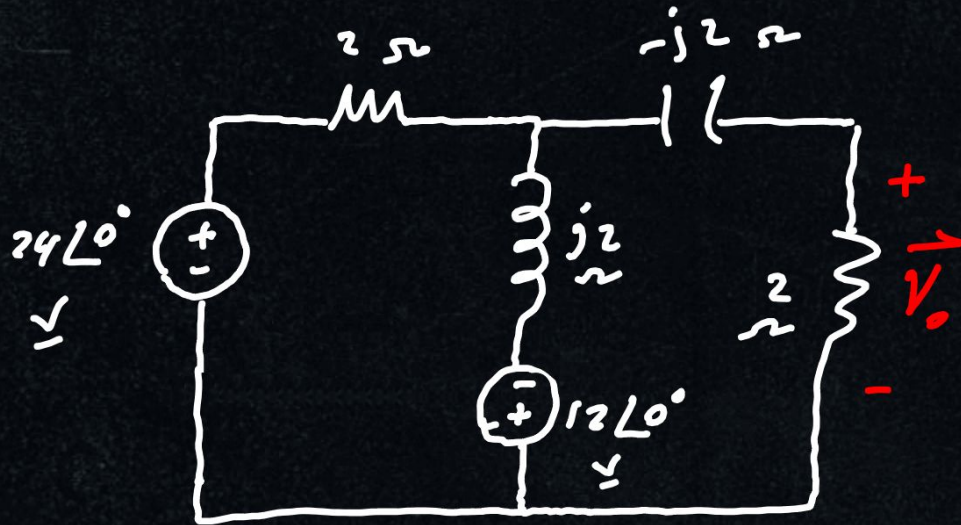


$$Z_{Th} = 2 - j2 \Omega$$

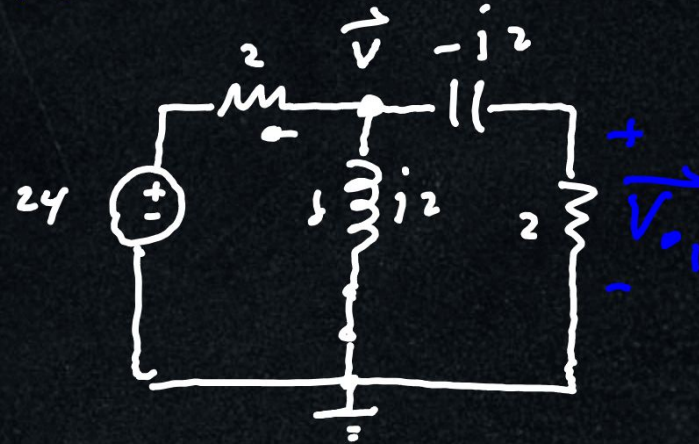
$$\vec{V}_o = \frac{2}{2 + Z_{Th}} \cdot \vec{V}_{Th} = \frac{2}{2 + (2 - j2)} (24 + j4)$$

$$\vec{V}_o = 10.88 \angle 36^\circ \text{ V}$$

EX:- Find $\vec{V}_o$ using superposition and Thevenin theorem?

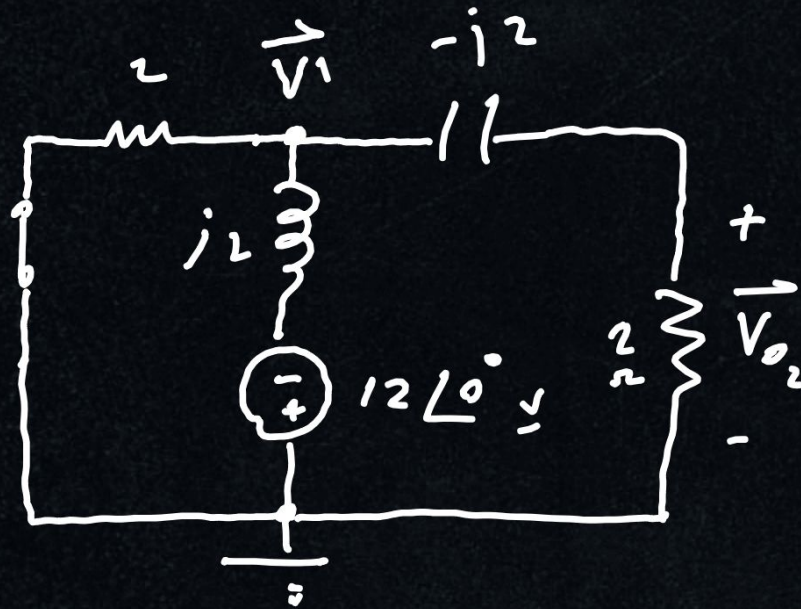


super position



$$\frac{\vec{V} - 24}{2} + \frac{\vec{V}}{j2} + \frac{\vec{V}}{2 - j2} = 0 \Rightarrow \text{calculate } \vec{V}$$

$$\vec{V}_o = \frac{2}{2 - j2} \vec{V} \Rightarrow \text{calculate } \vec{V}_o$$



$$\frac{\vec{V}_1}{2} + \frac{\vec{V}_1 + 12}{j2} + \frac{\vec{V}_1}{2 - j2} = 0$$

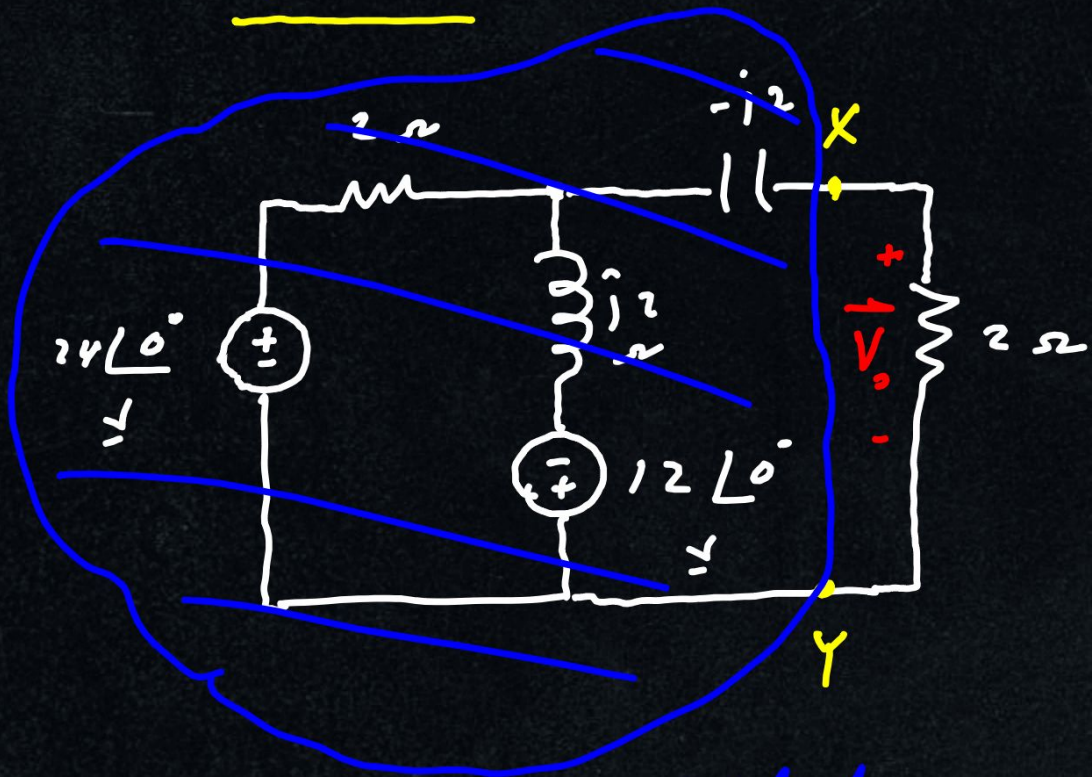
⇒ calculate $\vec{V}_1$

$$\vec{V}_{o_2} = \frac{2}{2 - j2} \vec{V}_1$$

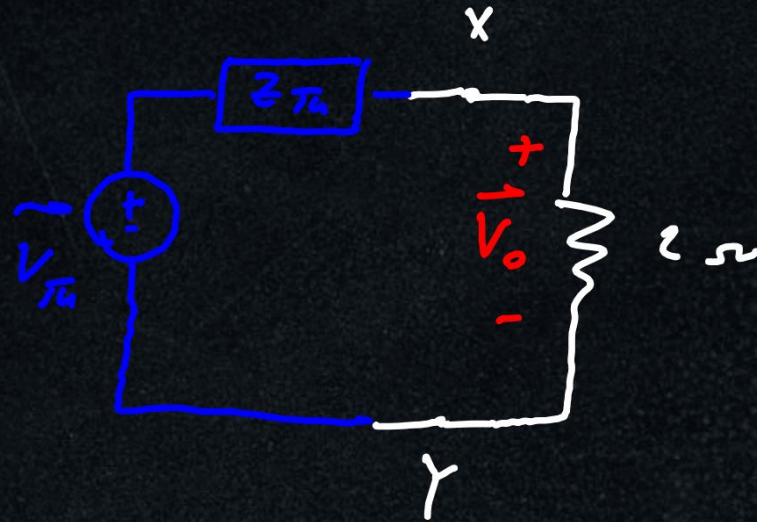
⇒ calculate $\vec{V}_{o_2}$

$$\vec{V}_0 = \vec{V}_{o_1} + \vec{V}_{o_2} = 12 \angle 90^\circ$$

Thevenin



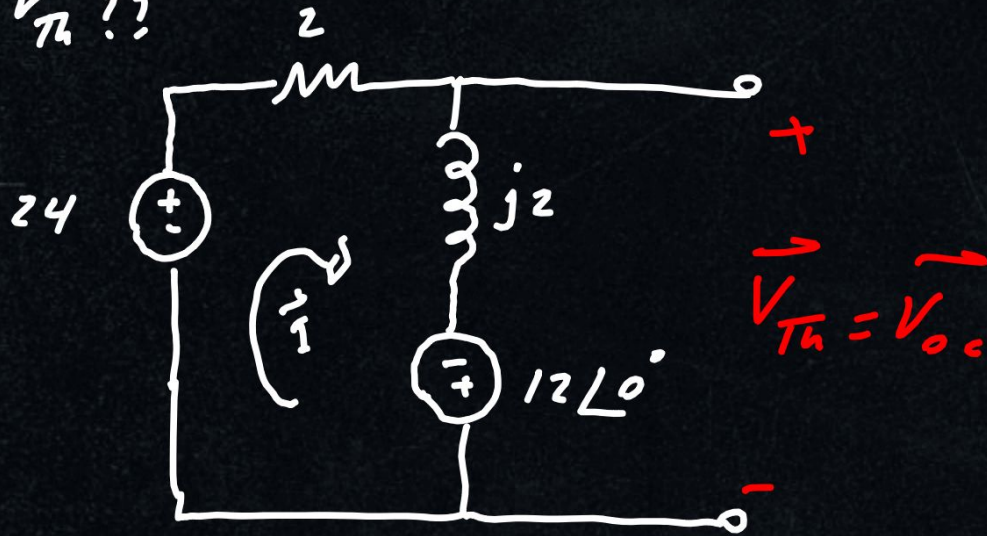
Thevenin equivalent
circuit



$$\vec{V}_o = \frac{2}{2 + Z_{Th}} \cdot \vec{V}_{Th}$$

Voltage
divider

$V_{Th} ??$



KVL in the loop

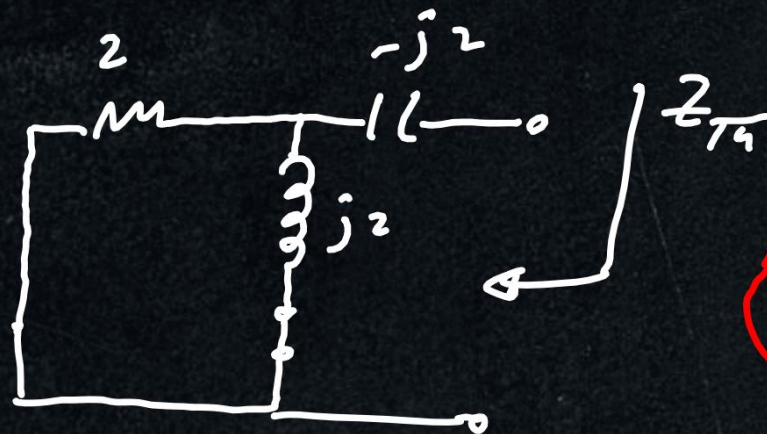
$$-24 + (2 + j2) \vec{I} - 12 = 0$$

$$\vec{I} = \frac{36 \angle 0^\circ}{2 + j2} \text{ A}$$

$$\vec{V}_{Th} = 2(-\vec{I}) + 24$$

$$\vec{V}_{Th} = \frac{72 \angle 180^\circ}{2 + j2} \text{ V} = \text{---}$$

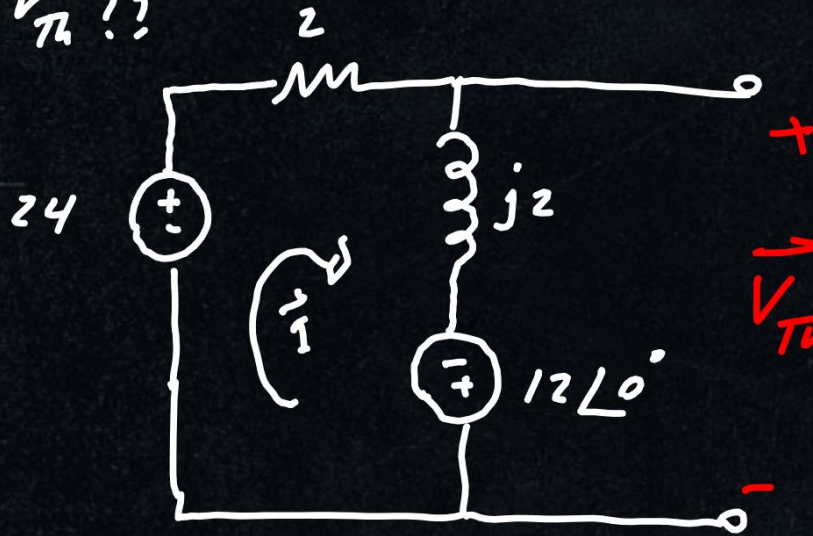
$Z_{Th} ??$ "Method II"



$$Z_{Th} = (2 \parallel j2) + (-j2) = \text{---}$$

$$\vec{V}_o = \frac{2}{2 + Z_{Th}} \cdot \vec{V}_{Th} = 12 \angle 90^\circ \text{ V}$$

$V_{Th} ??$



$\vec{V}_{Th} = V_{oc}$

KVL in the loop

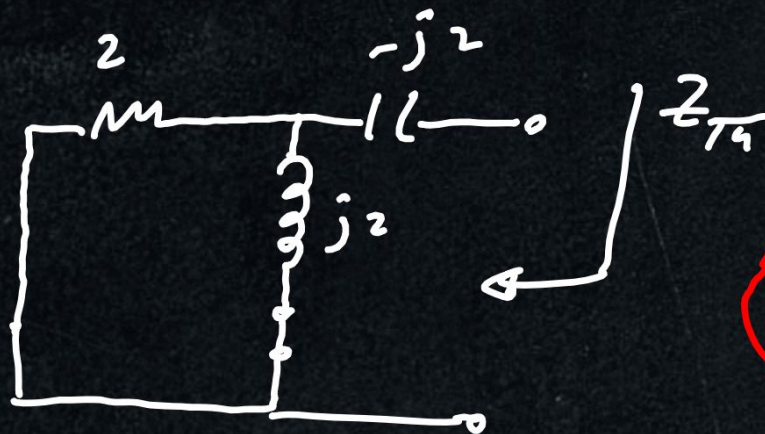
$$-24 + (2 + j2) \vec{I} - 12 = 0$$

$$\vec{I} = \frac{36 \angle 0^\circ}{2 + j2} \text{ A}$$

$$\vec{V}_{Th} = 2(-\vec{I}) + 24$$

$$\vec{V}_{Th} = \frac{72 \angle 180^\circ}{2 + j2} \text{ V} = \underline{\hspace{2cm}}$$

$Z_{Th} ??$ "Method II"



$$Z_{Th} = (2 \parallel j2) + (-j2) = \underline{\hspace{2cm}}$$

$$\vec{V}_o = \frac{2}{2 + Z_{Th}} \cdot \vec{V}_{Th} = 12 \angle 90^\circ \text{ V}$$