#### **Biometrics Introduction** By Hafez Barghouthi

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# Definition

"Biometric Technologies" are automated methods of verifying or recognizing the identity of a living person based on a physiological or behavioural characteristic

# **Definition Explaining**

#### Automated

Different from human identification

#### Living person

- Single persons, no groups
- Alive not dead (just JOKING) I

# **Definition Explaining**

- Physiological biometrics
  - Fingerprint, Iris, Face, Hand
- Behavioural biometrics
  - Signature, Gait, Voice

# History - 1

- Dates back to ancient Egypt
- Anthropometry (bodily measurements):
  - Adolphe Quetelet (1871), Belgian mathematician
  - Alphonse Bertillon (1880's), French policeman
- Fingerprints and palmprints
  - Used already by Babylonian kings
  - Jan Evangelista Purkinje, Czech studying sweat glands
  - Juan Vucetich, Argentinian policeman, first to take fingerprints in ink
  - Francis Galton, Edward Henry: Galton-Henry system for classification

# History - 2

- Fingerprints and facials, 1880's, Henry Faulds, William Herschel and Francis Galton
- fingerprint recognition on current form, 1960's
- Hand geometry, 1970's
- Retinal, signature and face verification, 1980's
- Iris recognition, 1990's
- Newer and newer: gait, keystroke dynamics, mouse movement, cardiac sounds, brain waves

# Positive / Negative

- Positive recognition
  - To prevent multiple people from using the same identity
- Negative recognition
  - To prevent one person from using multiple identities

# Physiological / Behavioural

#### • Physiological:

- Physical features "unchangeably" attached to a person
- E.g. fingerprint, DNA, and face
- Behavioural:
  - Behaviour that is very specific to a person
  - E.g. signature, gait, and voice

#### Examples - Ear

#### • Shape of ear can be used for authentication



(a) Anatomy.

(b) Measurements.

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## **Examples - Face**

- Used by humans
- Many different techniques available

## **Examples - Thermograms**

#### • Facial, hand, hand vein





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# **Examples - Fingerprint**

#### Global features

#### Local features



	Termination		
	Bifurcation		
	Lake		
	Independent ridge		
8	Point or island		
	Spur		
	Crossover		

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#### Examples - Gait

 "Great Juno comes; I know her by her gait" from "The Tempest" by Shakespeare



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#### **Examples - Geometry**

#### • Hand and finger geometry



# **Examples - Iris**

- Remains unchanged after 2 years
- Iris code.



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# **Examples - Keystroke**

- Typical way of typing
- Combinations of keys
- Speed, force and press-down

# Examples - Odor

- Used by humans
- Many problems

## Examples – Retinal Scan

- Supposed to be the most secure biometric
- Not user friendly



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#### Characteristics - overview

- Universality
- Distinctiveness
- Permanence
- Collectability
- Performance
- Acceptability
- Circumvention

# **Characteristic - Universality**

- Each person should have the characteristic
  - Failure to Enroll Rate (FER)

# Distinctiveness

- Different persons should have different biometric properties
  - False Match Rate (FMR)

# Characteristic – Permanence

- The characteristic should be sufficiently invariant over a period of time
  - False Non-Match Rate (FNMR)

# Characteristic – Collectability

 The biometric property should be easy to collect (electronically) and to quantify

# Characteristic – Performance

- This refers to the achievable recognition accuracy and speed
  - False Non Match Rate (FNMR)
  - Failure to Capture Rate (FCR)

# **Characteristic – Acceptability**

 To which extent are people willing to accept the use of a specific biometric

#### Characteristic – Circumvention

- Reflects how easy it is to fool the system
  - False Match Rate (FMR)

# **Application Environments**

- Overt vs. covert
- Habituated vs. non-habituated
- Attended vs. non-attended
- Standard vs. non-standard
- Public vs. private
- Open vs. closed

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#### Overt vs. covert

- Overt:
  - User is aware that the biometric feature is being measured (e.g. finger on a fingerprint reader)
- Covert:
  - User is unaware that the biometric feature is being measured (e.g. face recognition)

# Habituated vs. non-habituated

#### • Habituated:

- System is used on a daily basis (e.g. to have access to the PC at work)
- Non-habituated:
  - System is used irregularly (e.g. to access a personal safe in a bank)

## Attended vs. non-attended

#### • Attended:

- Use is observed and guided by system management (e.g. access to a building)
- Non-attended:
  - No observation or (regular) help is provided (e.g. access to PC)

## Standard vs. non-standard

#### • Standard:

- System is in a static environment with controlled conditions (e.g. fixed lightning and background for face recognition)
- Non-standard:
  - System in a dynamic environment (e.g. background noise for voice recognition)

# Public vs. private

- Public:
  - "Anybody" can use the system (e.g. voice recognition for bank transfers via phone)
- Private:
  - Only employees can use the system (e.g. access to a factory or office building)

# Open vs. closed

- Open:
  - System can interact with other (biometric) system (e.g. biometric passport)
- Closed:
  - System is stand-alone and no information is shared (e.g. systems to access classified information)

# **Biometrical Systems**

- A biometrical systems consists of 2 modules:
  - Enrollment module
    - Template created and stored in database
  - Authentication module
    - Checked against stored template

## **Biometrical Systems**



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#### Errors

- False Non-Match Rate (FNMR)
- False Match Rate (FMR)
- False Rejection Rate (FRR) (used wrongly in literature). USE (FNMR) instead
- False Acceptance Rate (FAR) used wrongly in literature. USE (FMR) instead
- Failure to Enroll Rate (FER)
- Failure to Capture Rate (FCR)

# Hypotheses and decisions

- H<sub>o</sub>: input biometric does **not** belong to the same person as the template biometric
- H<sub>1</sub>: input biometric does belong to the same person as the template biometric
- D<sub>o</sub> : Person is **not** who he claims to be
- D<sub>1</sub> : Person is who he claims to be

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# False Match Rate (FMR)

- Probability that a false claimed identity is not recognized as false
- Also called Type I Error
- Probability that D<sub>1</sub> is decided, given that H<sub>0</sub> is true:
  - Prob( $D_1 | H_o$ )
- Depends on a threshold t

# False Non-Match Rate (FNMR)

- Probability that a correctly claimed identity is not recognized as true
- Also called Type II Error
- Probability that D<sub>o</sub> is decided, given that H<sub>1</sub> is true:
  - Prob(  $D_o \mid H_1$  )
- Depends on a threshold t

# Failure to Enroll Rate (FER)

- Probability that a person cannot enroll in the biometric system
- Person doesn't have biometric feature
- Person has poor quality biometric feature
- Trade-off between FMR/FNMR and FER

# Failure to Capture Rate (FCR)

- Probability of failure to capture the biometric feature when trying to authenticate
- Bad capturing conditions
  - Too dark for face recognition
  - Dirty fingerprint reader
  - Background noise for voice recognition

# Equal Error Rate (EER)

• EER is the point where FMR and FNMR are equal

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#### Distance metrics - 1

- In biometrics we need to compare extracted features that will differ a bit every time they are measured
- Need a way to compare extracted features
- "Inter person" distance must be large
- "Intra person" distance must be small

#### **Distance metrics - 2**

- We want to know how far 2 sequences **x** and **y** are apart or how close together they are.
- Let  $\mathbf{x} = (x_1, x_2, ..., x_n)$
- Let  $\mathbf{y} = (y_1, y_2, ..., y_n)$
- Assume **x** can be compared to **y**

## **Absolute Distance**

- Sum the absolute differences between each of the components of x and y
- $\mathbf{d}_{1}(\mathbf{x},\mathbf{y}) = \Sigma | \mathbf{x}_{i} \mathbf{y}_{i} |$
- Extremely easy to calculate

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## **Euclidean Distance**

• Sum the squares of the differences between each of the components of **x** and **y** 

• 
$$\mathbf{d}_2(\mathbf{x},\mathbf{y}) = \sqrt{\left[ \Sigma (\mathbf{x}_i - \mathbf{y}_i)^2 \right]}$$

Also easy to calculate

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## Maximum Difference Distance

- The distance between **x** and **y** is defined as the maximum absolute difference of its components
- $d_3(\mathbf{x},\mathbf{y}) = \max |\mathbf{x}_i \mathbf{y}_i|$
- Extremely easy to calculate

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## More distance metrics?

- Many more distance metrics possible
- Sometimes first a mathematical transformation of the data is needed
- Not all parts of the data need to be taken into account

# Threshold

- Features are extracted from biometric characteristic
- Features are compared to template
- Distance metric gives distance d
- Use of threshold t
- d≤t: authentication OK
- d>t: authentication NOT OK

### **Example - Distance scores**

	Templ 1	Templ 2	Templ 3	Templ 4	Templ 5
Test 1	0,182	0,588	0,435	0,208	0,909
Test 2	0,323	0,213	0,286	0,476	0,244
Test 3	0,909	0,625	0,147	0,476	1,111
Test 4	0,238	0,294	0,476	0,256	0,526
Test 5	0,588	0,454	1,250	0,526	0,130

# Example – FNMR/FMR

- If t=0.256 we see that
  - (FNMR,FMR) = ( 0/5 , 3/20 )
- If t=0.213 we see that
  - (FNMR,FMR) = (1/5,1/20)
- If t=0.212 we see that
  - (FNMR,FMR) = ( 2/5 , 1/20 )
- If t=0.207 we see that
  - (FNMR,FMR) = ( 2/5, 0/20 )

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# **ROC Curve**

#### • ROC: Receiver Operating Characteristic



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