Synchronous Maters In a Synchronous machine: (constant) magnetic field (slip rings & Brushes) · Stater: 3 phase current source will produce Rotaling magnetic field (In Synchronous speed) Scoupling occurs between the Stator and Rotor we know that nm = 120 fe

Video

• Electrical freequency for the rotating magnific field when the N-s poles couples with N-s poles on rotan and coupling occurs, then the rotar will try to rotate with the speed of the Stater in the Synchronous Speed

Add - Frequency can be controlled using an inverter

• We need a pushing force for the rotor to ease coupling [Not self started]

Force is obtained from included electricity in the bars (Squirell cage)

Speed of motor is constant only if load is very high and motor will be over loaded

Squirl cage will have no effect because when votor and stator have save speed the bears will have the same speed as Magnetic STUDENTS-HUBEdom, and the lines will not Mohammad Awa Wolch encluded voltage on bors.

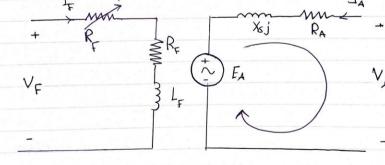
Slides

Synchonous motors: Synchronous machines used to convert electrical power to mechanical power

- Ir (field current) → BR (Steady State magnetic freld)
- · 3 phase I (on stater) Bs (rotating
- → Rotor field will line up with stator field and the rotor will try to catch up with staton

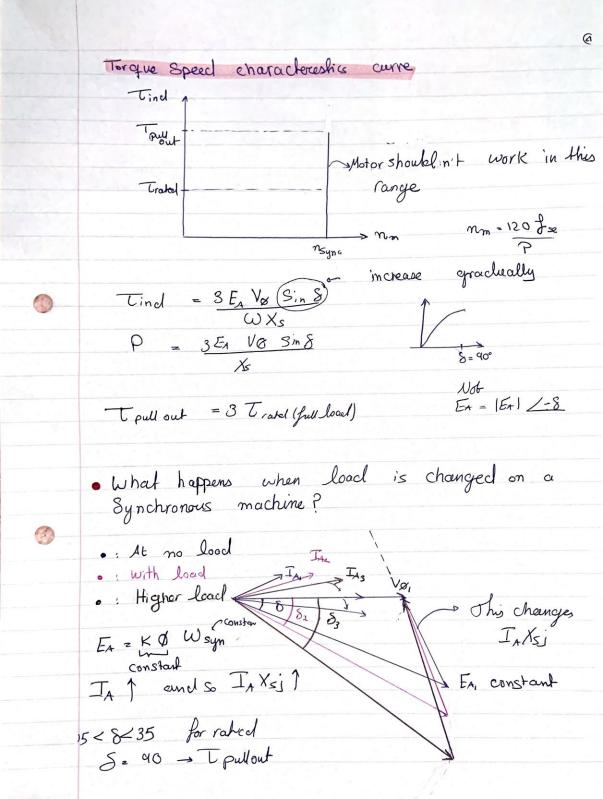
Single Phase Circuit

Same as generator but power flows neverseed and IA is reversed on



KVL: VO = EA + IA (RA + XSI)

Difference between motor and generalor Generator BR produces EA, Bret produces Vox, Bs produces Estat Assuming RAZO Tind = KBR X Bret = KBR Bret sin 8 Motor and Torque is higher until Tind = Tead at this point: machine operates at Steady State eand Synchrouns speed again



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