

Pulse Modulation

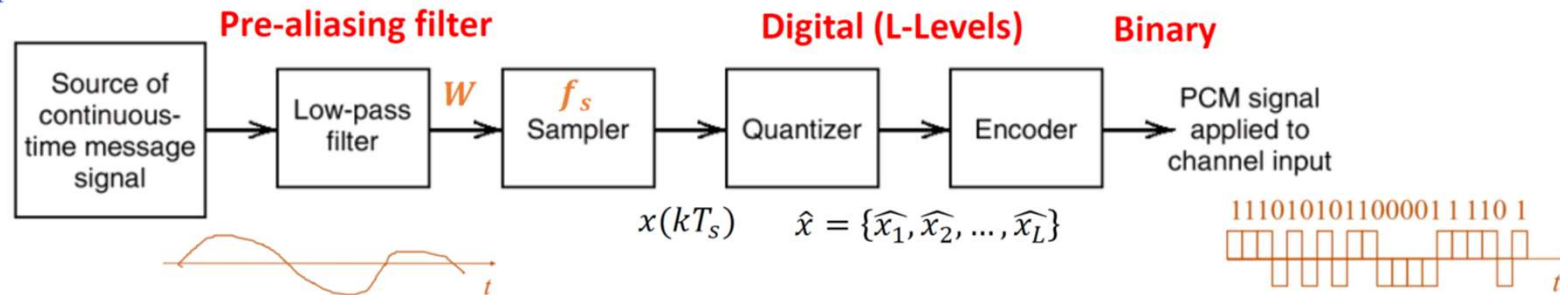
Sampling Theorem

Lecture Outline

- In this this, and the next few lecture, we will address the subject of **pulse code modulation**, where an analog source can be converted into a digital waveform via **sampling**, **quantization**, and **binary encoding**.
- This lecture focuses on Ideal Sampling and the Sampling Theorem.
- The phenomenon of aliasing is explained in detail.
- In the next lecture, we will present two other sampling techniques, which are natural and flat-topped sampling.

Pulse Code Modulation

- Sources are of two types; **analog and digital**. For an analog source, the input transducer is used to convert the physical message generated by the source into a time-varying electrical signal called the *message signal* (like the human voice). This is a continuous time continuous amplitude signal.
- An analog source can be converted into digital via sampling, quantization, and encoding. This process is called **pulse code modulation**



- **Sampler:** If W is the highest frequency component in a signal, then the sampling rate required to reconstruct the message from its samples should follow the Nyquist Rate where $f_s > 2W$.
- The output of the sampler is a continuous amplitude discrete time signal.
- **Quantizer:** Converts the continuous amplitude samples $x(kT_s)$ into **discrete** level samples $\hat{x}(kT_s)$ taken from a finite set of L possible values $\hat{x} = \{\hat{x}_1, \hat{x}_2, \dots, \hat{x}_L\}$.
- **Binary Encoder:** Each quantized level is represented by $r = \log_2 L$ binary digits

sampling techniques

- **Sampling:** is the process by which a continuous time continuous amplitude signal is converted into a discrete time continuous amplitude signal.

There are three types of sampling:

- Ideal sampling: To be presented in this lecture
- Natural sampling: To be discussed in the next lecture
- Flat-topped sampling (sample and hold): To be discussed in the next lecture.

Ideal Sampling: The Periodic Train of Impulses

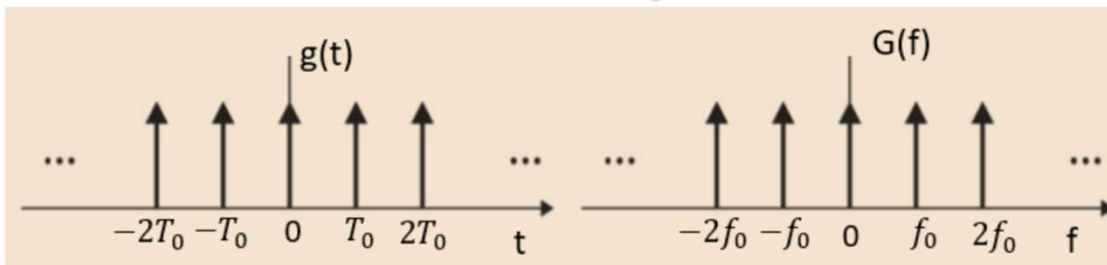
- **Periodic Signals:** A periodic signal $g(t)$ is expanded in the complex Fourier series form as:

- $g(t) = \sum_{n=-\infty}^{\infty} C_n e^{jn\omega_0 t} \Rightarrow \mathfrak{T}\{g(t)\} = \sum_{n=-\infty}^{\infty} C_n \delta(f - nf_0)$

Example: Consider the following train of impulses $g(t) = \sum_{m=-\infty}^{\infty} \delta(t - mT_0)$

Solution: The Fourier coefficients are obtained by integrating over one period of $g(t)$.

- $C_n = \frac{1}{T_0} \int_{-T_0/2}^{T_0/2} g(t) e^{-jn\omega_0 t} dt = \frac{1}{T_0} = f_0$; Note that the sifting property has been used.
- Therefore, the complex Fourier series of $g(t)$ is
- $g(t) = \frac{1}{T_0} \sum_{n=-\infty}^{\infty} e^{jn\omega_0 t}; \Rightarrow \mathfrak{T}\{g(t)\} = \frac{1}{T_0} \sum_{n=-\infty}^{\infty} \mathfrak{T}\{e^{jn\omega_0 t}\} = \frac{1}{T_0} \sum_{n=-\infty}^{\infty} \delta(f - nf_0)$
- $\mathfrak{T} \sum_{m=-\infty}^{\infty} \delta(t - mT_0) = \frac{1}{T_0} \sum_{n=-\infty}^{\infty} \delta(f - nf_0) .$

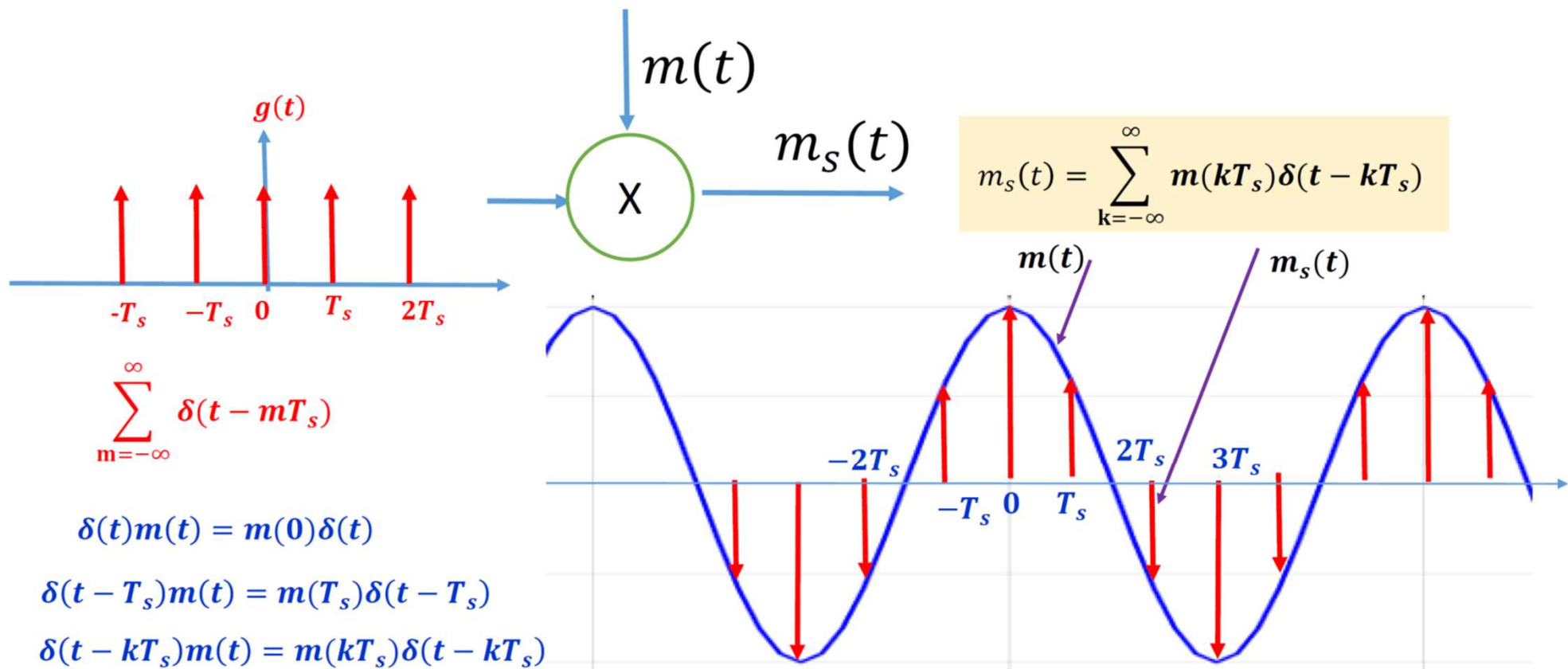


Remark 1: Note that the signal is periodic in the time domain and its Fourier transform is periodic in the frequency domain.

Remark 2: This sequence will be found useful when the sampling theorem is considered later in this lecture.

Ideal Sampling

- **Ideal Sampling:** The message $m(t)$, with Fourier transform $M(f)$, which is band-limited to W Hz, is multiplied by a periodic sequence of ideal impulses with period T_s to produce the sampled signal $m_s(t)$.



Ideal Sampling

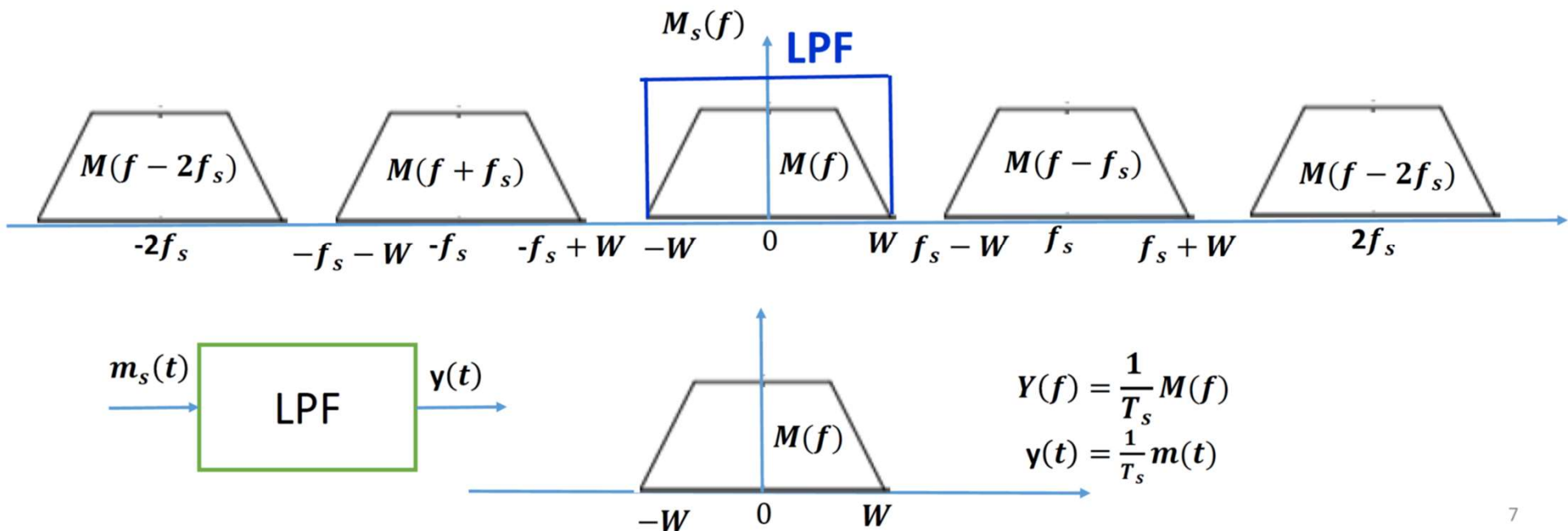
- $m_s(t) = m(t)g(t) = m(t) \sum_{m=-\infty}^{\infty} \delta(t - mT_s) = \sum_{k=-\infty}^{\infty} m(kT_s)\delta(t - kT_s)$
- Recall the Fourier transform pair: $\mathbf{G(f) = \mathfrak{F}(g(t)) = \frac{1}{T_0} \sum_{n=-\infty}^{\infty} \delta(f - nf_0)}$
- Hence, $m_s(t) = m(t) \frac{1}{T_0} \sum_{n=-\infty}^{\infty} e^{jn\omega_0 t}$; Product of two functions in the time domain.
- The Fourier transform of $m_s(t)$ is the convolution of $M(f)$ and $G(f)$
- $M_s(f) = M(f) * G(f) = M(f) * \frac{1}{T_s} \sum_{n=-\infty}^{\infty} \delta(f - nf_s)$

$$\mathbf{M_s(f) = \frac{1}{T_s} \sum_{n=-\infty}^{\infty} M(f - nf_s)}$$

Ideal Sampling: $f_s > 2W$

$$M_s(f) = \frac{1}{T_s} \sum_{n=-\infty}^{\infty} M(f - nf_s)$$

- Let $M(f)$ be as given in the figure. When $f_s > 2W$, $M_s(f)$ will look like



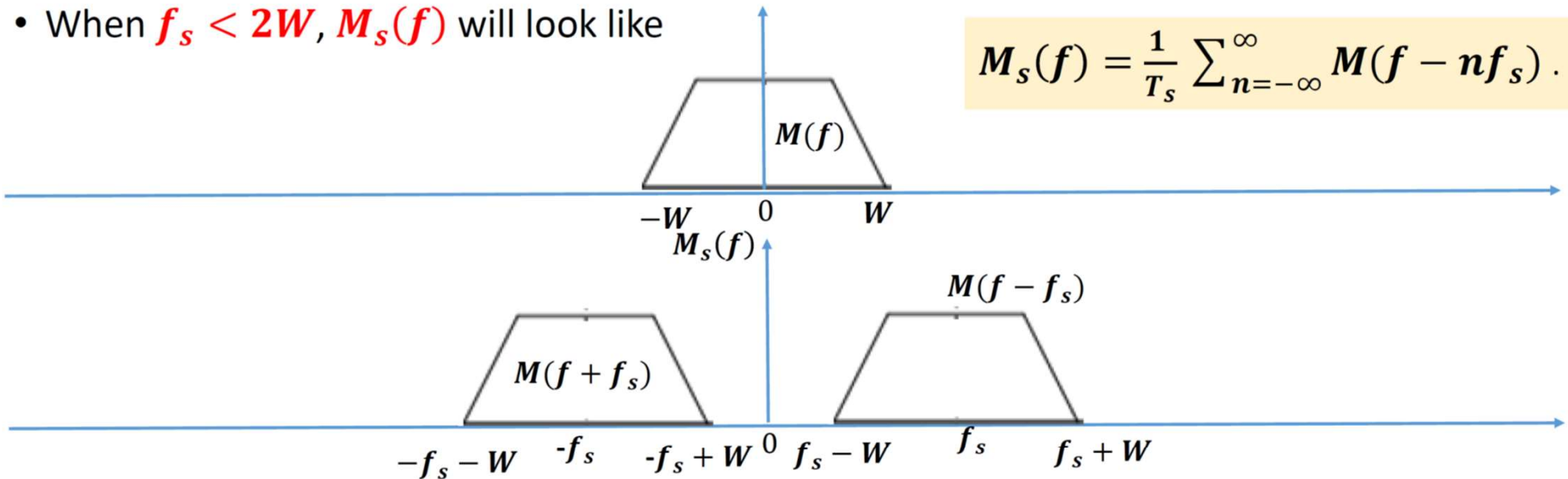
The Sampling Theorem

- A bandlimited signal with no frequency components above W Hz can be recovered uniquely from its samples taken every T_s seconds provided that $f_s \geq 2W$, where $f_s = 1/T_s$ is the sampling rate in samples/sec.
- The message $m(t)$ can be recovered from $m_s(t)$ using an ideal LPF with bandwidth W .
- The Sampling frequency $f_s = 2W$, is called the Nyquist rate. It represents the minimum rate at which a signal must be sampled in order to reconstruct it from its samples without distortion.
- When the sampling rate is less than the Nyquist rate, a distortion type of noise called **Aliasing** results.

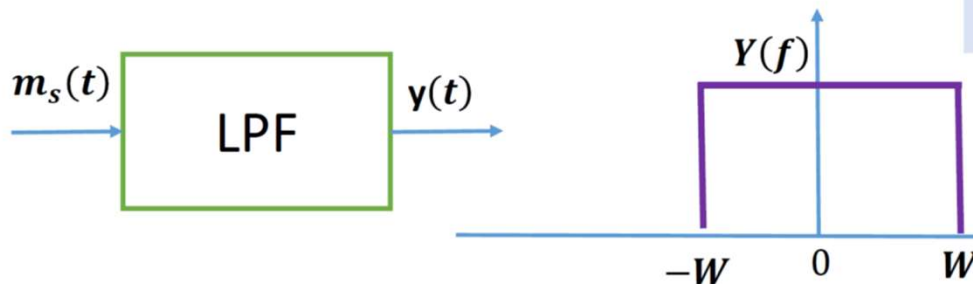
Sampling Theorem and Aliasing

- Let $M(f)$ be the Fourier transform of the message $m(t)$.
- When $f_s < 2W$, $M_s(f)$ will look like

$$M_s(f) = \frac{1}{T_s} \sum_{n=-\infty}^{\infty} M(f - nf_s)$$



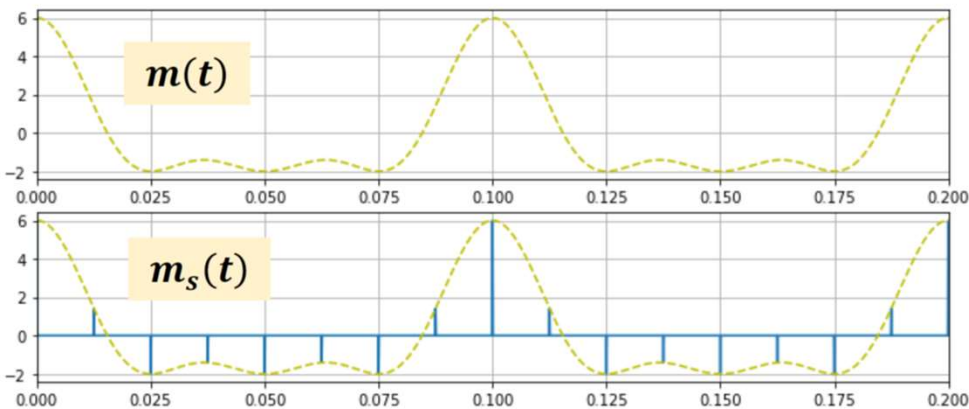
$$Y(f) = LP\{M(f) + M(f - f_s) + M(f + f_s)\}$$



$$Y(f) \neq \frac{1}{T_s} M(f)$$

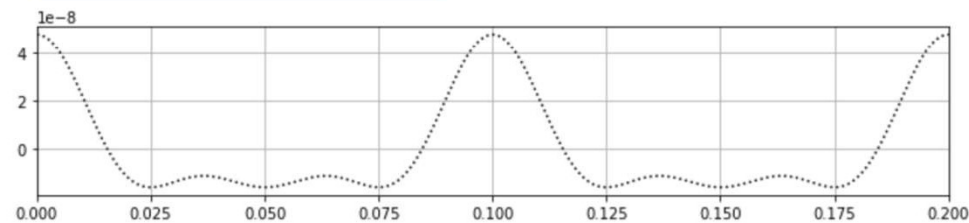
$$y(t) \neq \frac{1}{T_s} m(t)$$

Sampling Theorem: Example $f_s > 2W$

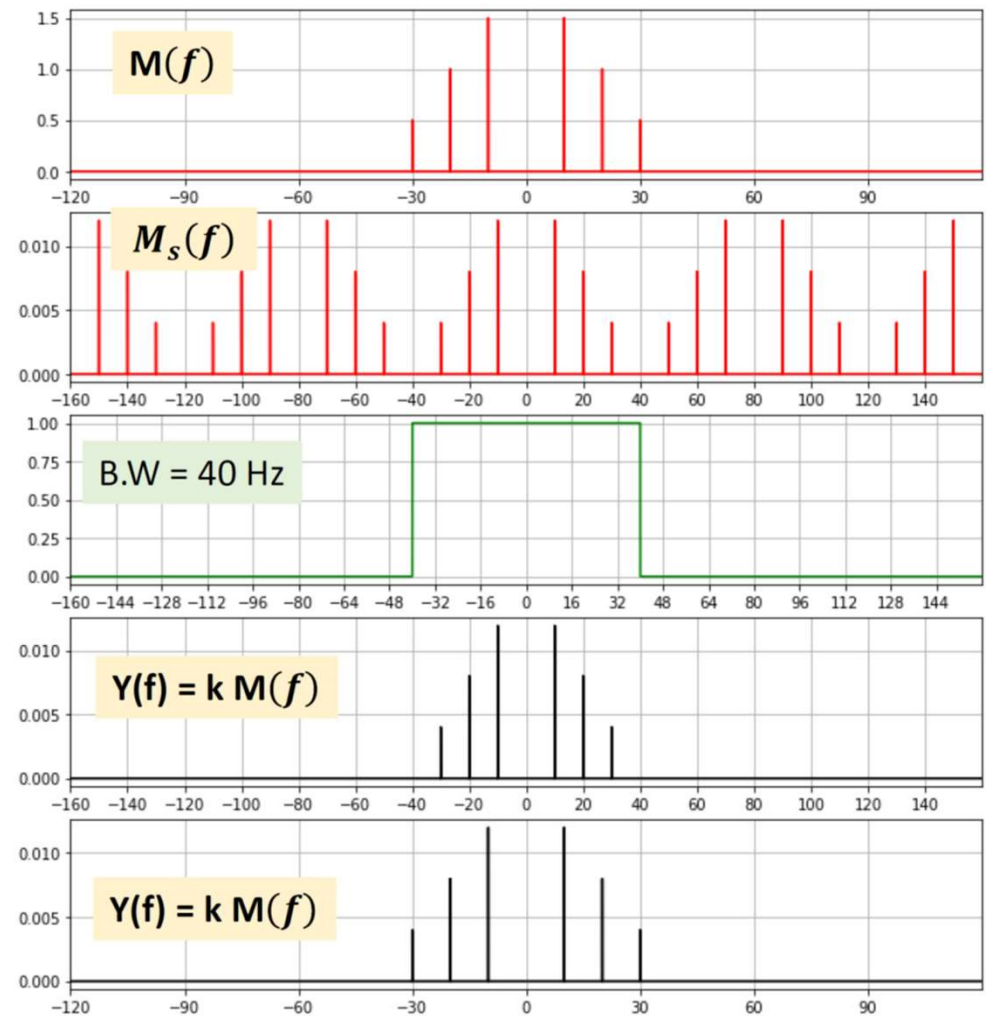


$$m(t) = 3\cos 2\pi(10)t + 2\cos 2\pi(20)t + \cos 2\pi(30)t$$

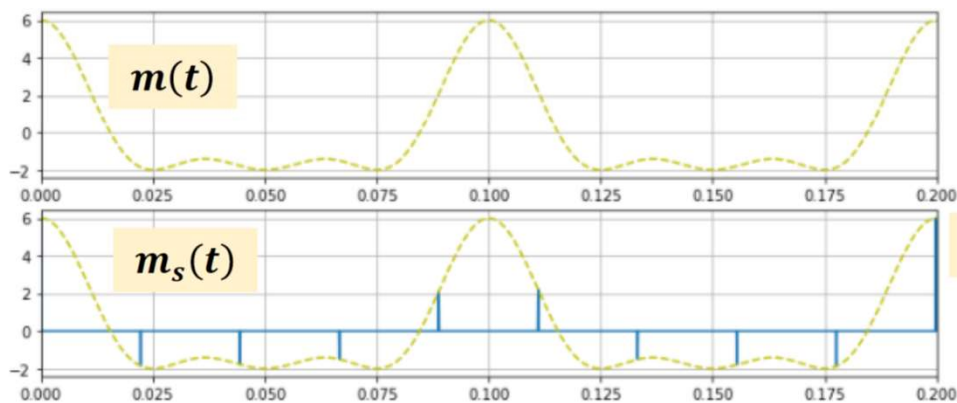
$$f_s = 80; T_s = 0.0125$$



- Since the sampling rate is greater than the Nyquist rate, the original signal is recovered without distortion.
- Output contains the message frequencies: 10, 20, 30



Sampling Theorem and Aliasing : $f_s < 2W$

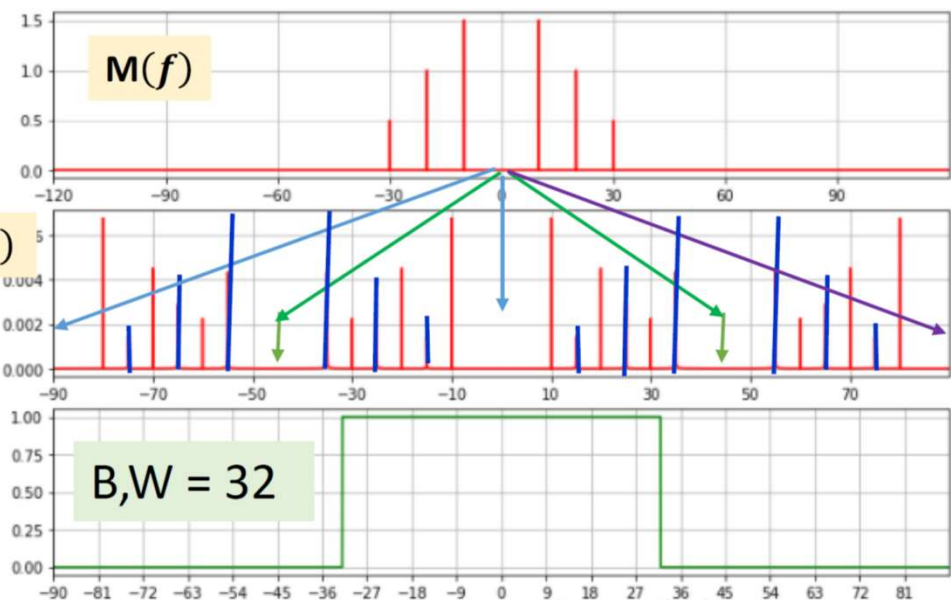


$$m(t) = 3\cos 2\pi(10)t + 2\cos 2\pi(20)t + \cos 2\pi(30)t$$

$$f_s = 45; T_s = 1/45 = 0.022$$

1e-8

$M_s(f)$

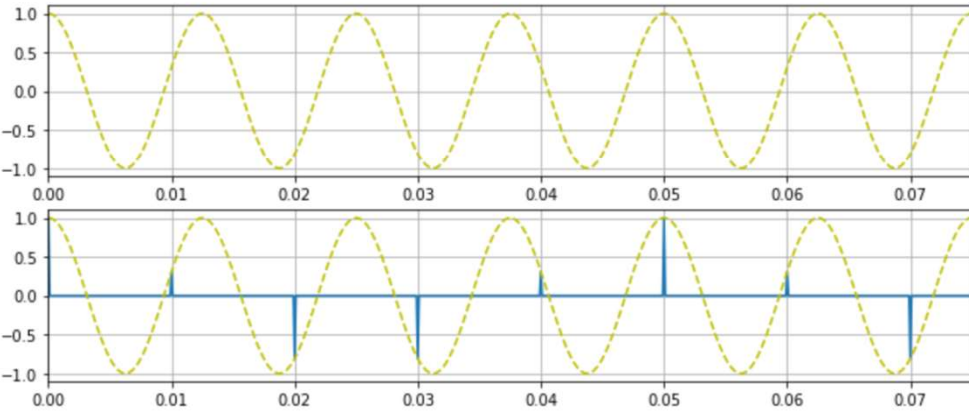


$$M_s(f) = \frac{1}{T_s} \{M(f) + M(f - f_s) + M(f + f_s) + \dots\}$$

Output contains the message frequencies: 10, 20, 30 Hz. In addition to aliasing frequencies within message bandwidth $(45 - 20) = 25$ and $(45 - 30) = 15$

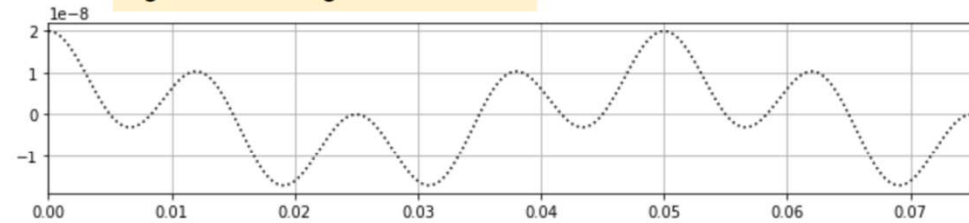
$$y(t) = k\{3\cos 2\pi(10)t + 2\cos 2\pi(20)t + \cos 2\pi(30)t + 2\cos 2\pi(25)t + \cos 2\pi(15)t\}$$

Sampling Theorem and Aliasing : Example $f_s < 2W$

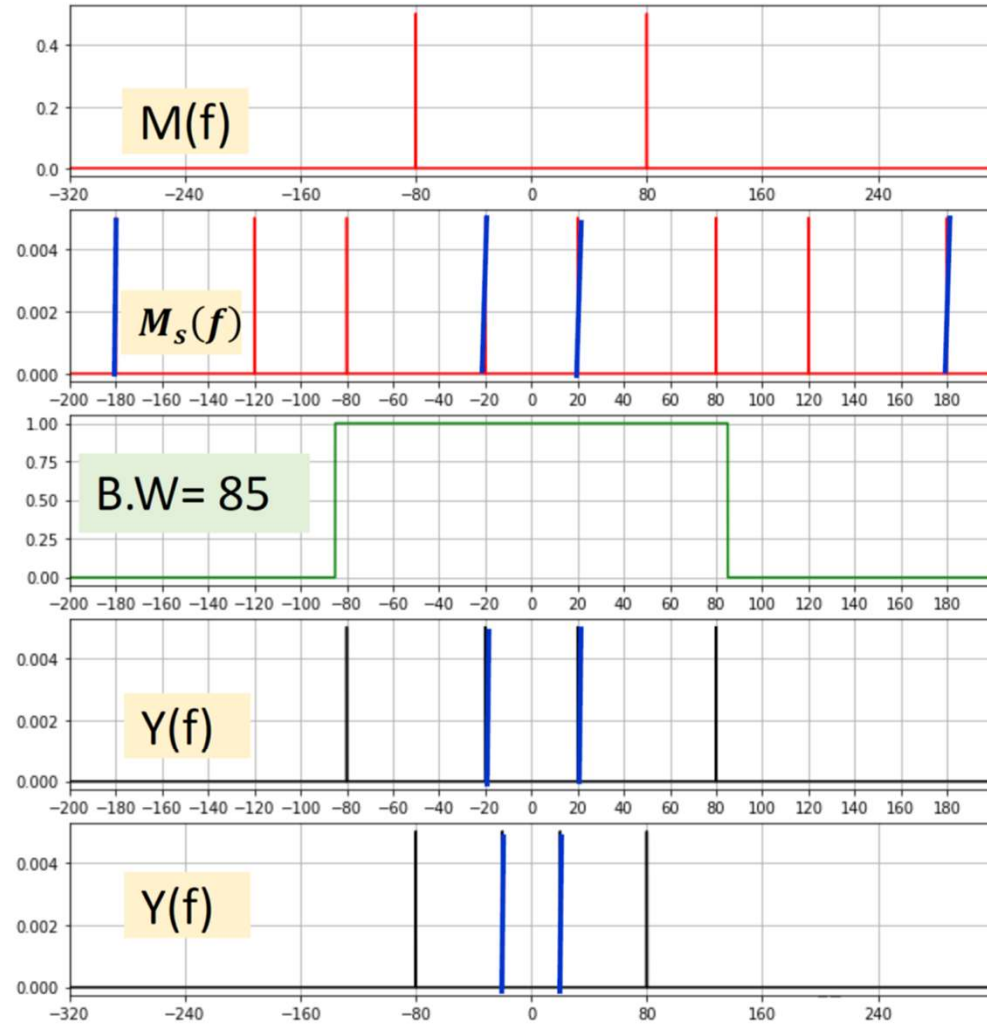


$$m(t) = \cos(2\pi(80)t)$$

$$f_s = 100; T_s = 0.01 =$$



$$y(t) = k\cos(2\pi(80)t) + k\cos(2\pi(20)t)$$



Natural Sampling

Lecture Outline

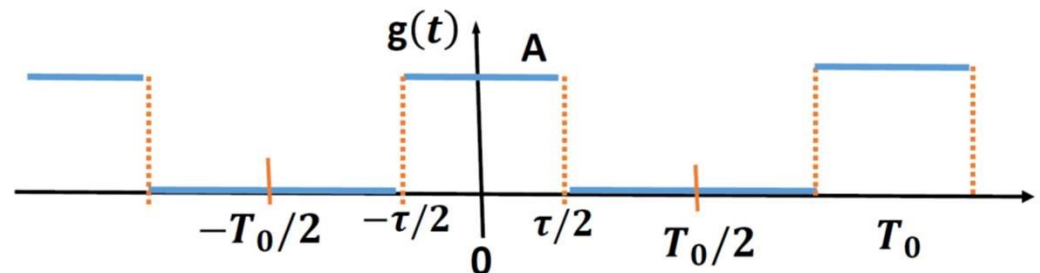
- **Sampling:** is the process by which a continuous time continuous amplitude signal is converted into a discrete time continuous amplitude signal.
- **There are three types of sampling:** Ideal sampling, natural sampling, and flat-topped sampling.
- Ideal sampling, the sampling theorem, and the phenomenon of aliasing were presented in the previous lecture.
- This lecture focuses on natural sampling and the sampling theorem.
- In the next lecture, we consider
 - Flat-topped sampling (sample and hold).
 - Time division multiplexing (TDM)

The Periodic Train of Rectangular Pulses: Fourier Series

- **Example:** Find the trigonometric Fourier series of the periodic rectangular signal defined over one period T_0 as:

$$g(t) = \begin{cases} +A, & -\tau/2 \leq t \leq \tau/2 \\ 0, & \text{otherwise} \end{cases}$$

- **Solution:** The FS is given as $g(t) \sim a_0 + \sum_{n=1}^{\infty} (a_n \cos n\omega_0 t + b_n \sin n\omega_0 t)$
- $a_0 = \frac{1}{T_0} \int_{-\tau/2}^{\tau/2} g(t) dt \Rightarrow \mathbf{a_0 = A\tau/T_0}$; $\mathbf{\tau/T_0}$ is called the duty cycle of the pulse train.
- $b_n = \frac{2}{T_0} \int_{-\tau/2}^{\tau/2} g(t) \sin(\frac{2\pi n}{T_0} t) dt = 0$; $g(t)$ is an even function of t
- $a_n = \frac{2}{T_0} \int_{-\tau/2}^{\tau/2} g(t) \cos(\frac{2\pi n}{T_0} t) dt = \frac{4}{T_0} \int_0^{\tau/2} A \cos(\frac{2\pi n}{T_0} t) dt \Rightarrow \mathbf{a_n = \frac{2A}{n\pi} \sin(\frac{n\pi\tau}{T_0})}$
- $a_n = 0$ when $n = \frac{T_0}{\tau}, \frac{2T_0}{\tau}, \frac{3T_0}{\tau}, \dots$
- This is demonstrated on the next slide



The Periodic Train of Rectangular Pulses: Time and Frequency

The Fourier series of the pulse train is: $g(t) \sim a_0 + \sum_{n=1}^{\infty} (a_n \cos 2\pi n f_0 t)$

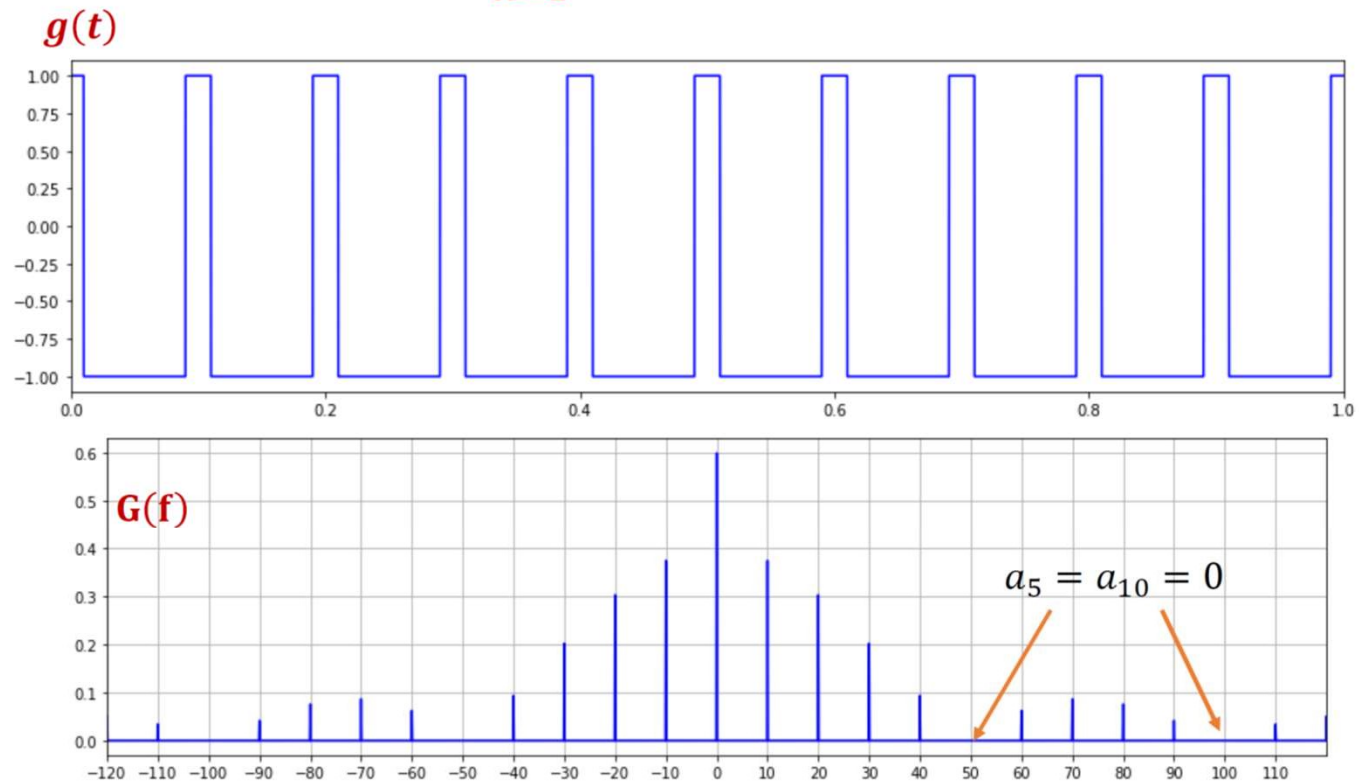
The Fourier transform is : $G(f) = a_0 \delta(f) + \sum_{n=1}^{\infty} \frac{a_n}{2} [\delta(f - n f_0) + \delta(f + n f_0)]$

Example:

- $f_0 = 10 \text{ Hz}; T_0 = 0.1$
- Duty cycle $\frac{\tau}{T_0} = 0.2$
- $a_n = 0$ when:
 - $n = \frac{T_0}{\tau}, \frac{2T_0}{\tau}, \frac{3T_0}{\tau}, \dots$
 - $n = 5, 10, 15, \dots$
- Spectral lines at $5f_0, 10f_0, \dots$ vanish

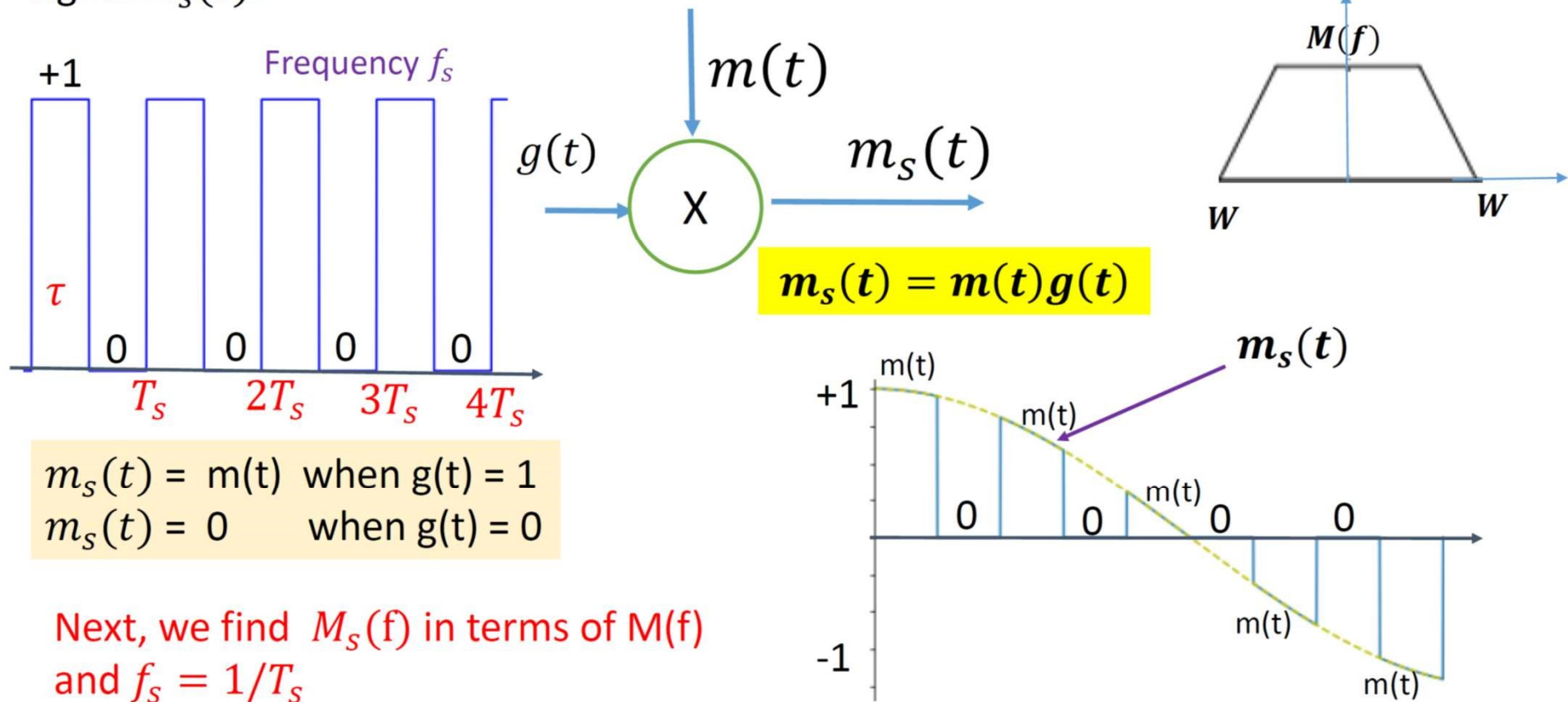
$$a_0 = A\tau/T_0$$

$$a_n = \frac{2A}{n\pi} \sin\left(\frac{n\pi\tau}{T_0}\right)$$



Natural Sampling

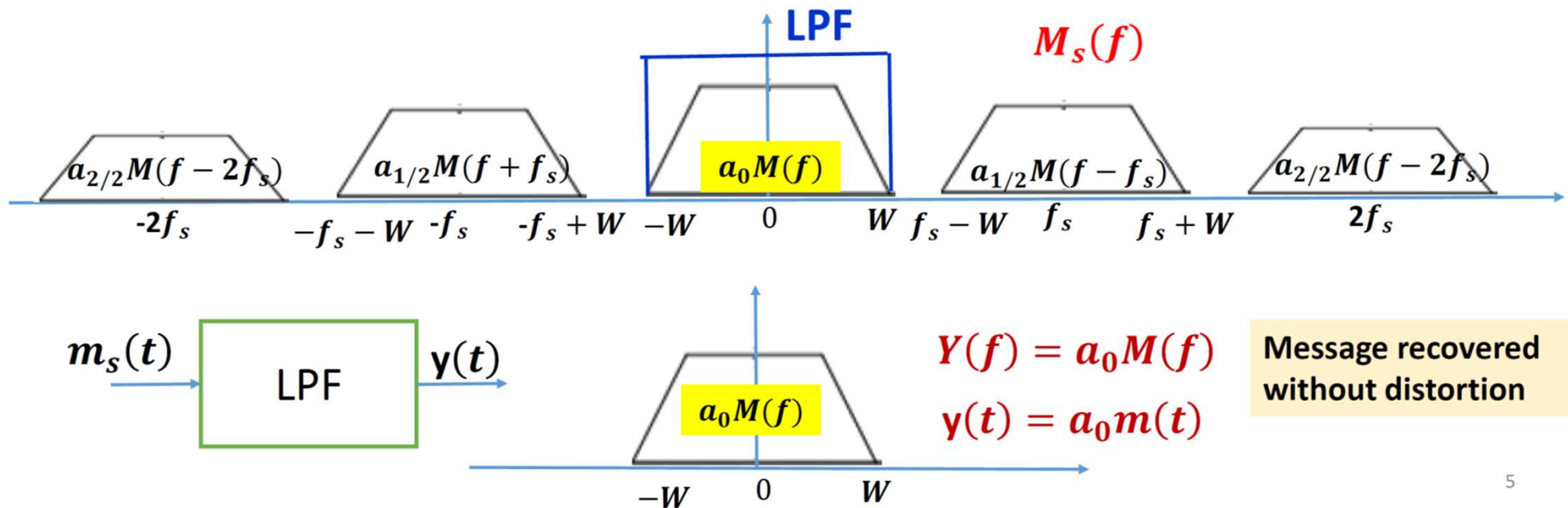
- **Natural Sampling:** The message $m(t)$, with Fourier transform $M(f)$, which is band-limited to W Hz, is multiplied by a periodic sequence of pulses with period T_s to produce the sampled signal $m_s(t)$.



Natural Sampling: $f_s > 2W$

- $m_s(t) = m(t)g(t) = m(t)\{a_0 + \sum_{n=1}^{\infty} a_n \cos 2\pi n f_s t\}$
- $m_s(t) = m(t)g(t) = a_0 m(t) + \sum_{n=1}^{\infty} a_n m(t) \cos 2\pi n f_s t$
- $M_s(f) = a_0 M(f) + \sum_{n=1}^{\infty} \frac{a_n}{2} [M(f - n f_s) + M(f + n f_s)]$
- When $f_s > 2W$, $M_s(f)$ will look like

$$f_s - W \geq W \Rightarrow f_s \geq 2W$$



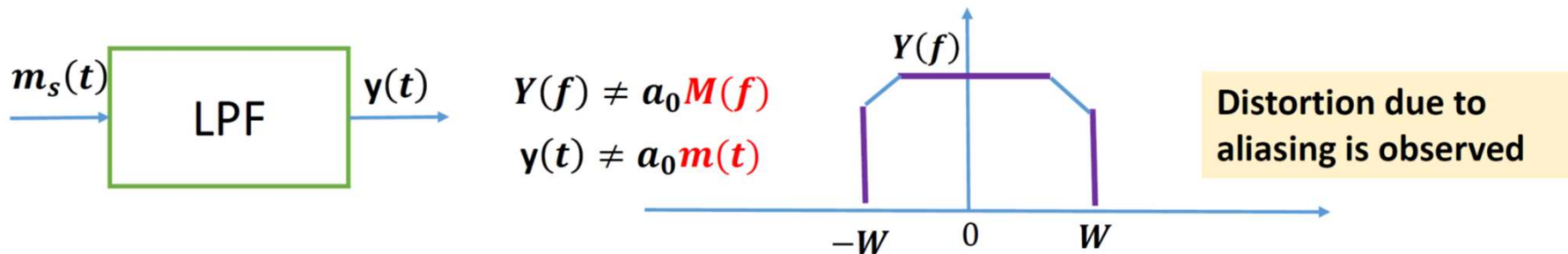
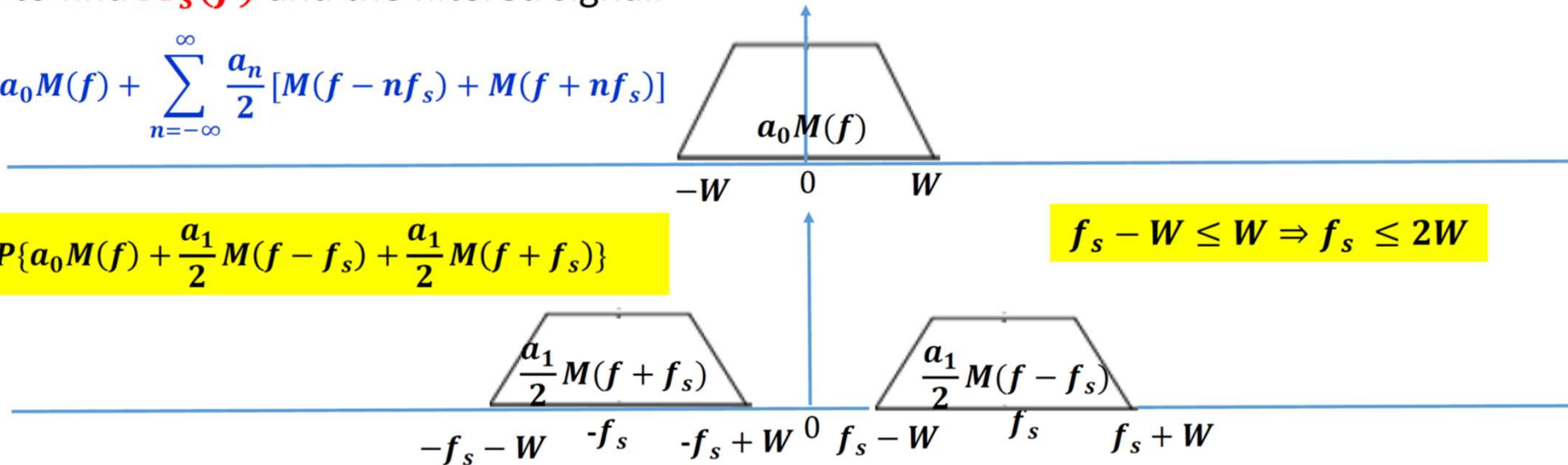
The Sampling Theorem

- A bandlimited signal with no frequency components above W Hz can be recovered uniquely from its samples taken every T_s seconds provided that $f_s \geq 2W$, where $f_s = 1/T_s$ is the sampling rate in samples/sec.
- The message $m(t)$ can be recovered from $m_s(t)$ using an ideal LPF with bandwidth W .
- The Sampling frequency $f_s = 2W$, is called the Nyquist rate. It represents the minimum rate at which a signal must be sampled in order to reconstruct it from its samples without distortion.
- When the sampling rate is less than the Nyquist rate, a distortion type of noise called **Aliasing** results.

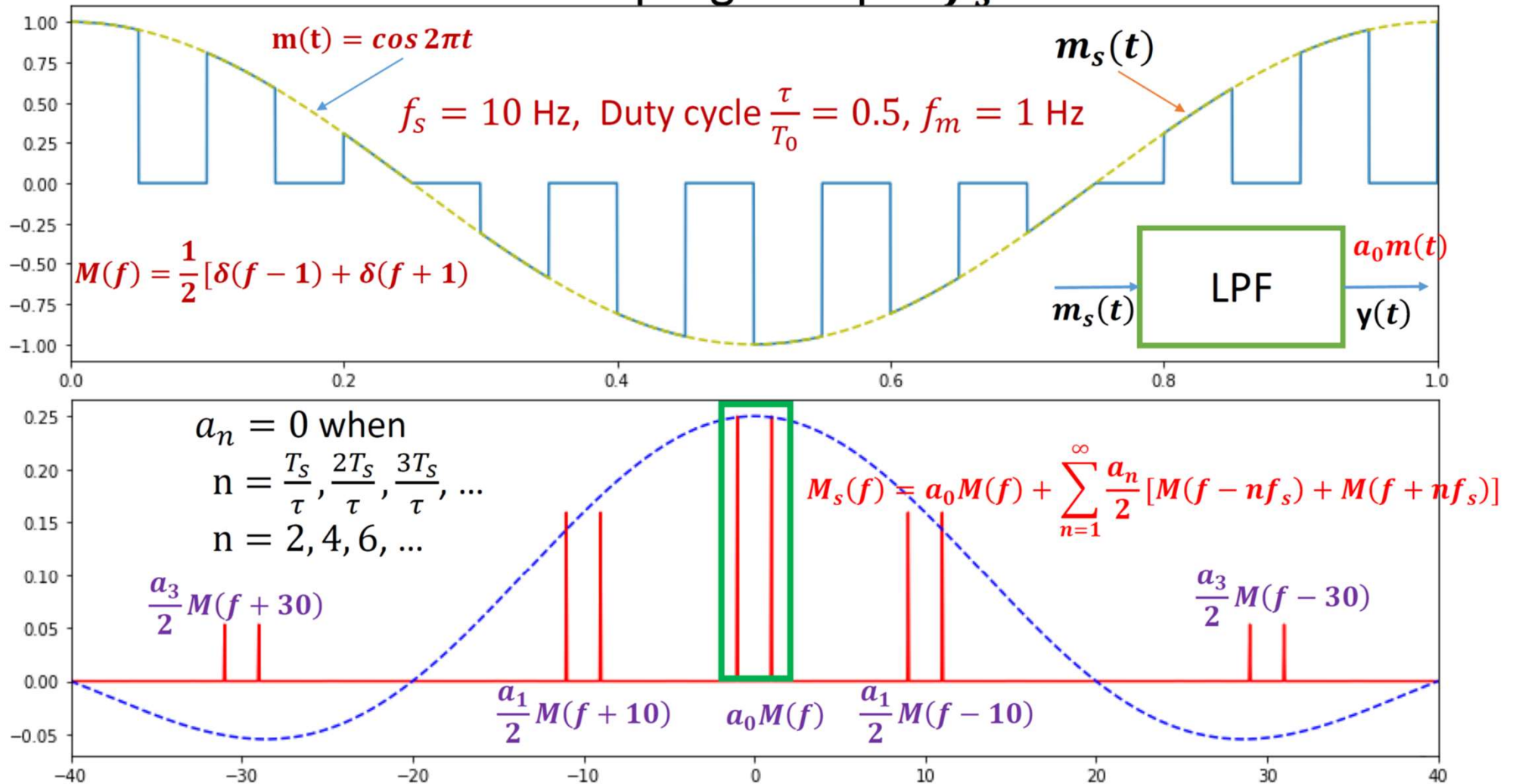
Natural Sampling: $f_s < 2W$

- Let $m(t)$ be the baseband signal with bandwidth W Hz. Assume that $f_s < 2W$
- Need to find $M_s(f)$ and the filtered signal.

$$M_s(f) = a_0 M(f) + \sum_{n=-\infty}^{\infty} \frac{a_n}{2} [M(f - nf_s) + M(f + nf_s)]$$



Natural Sampling Example: $f_s > 2W$

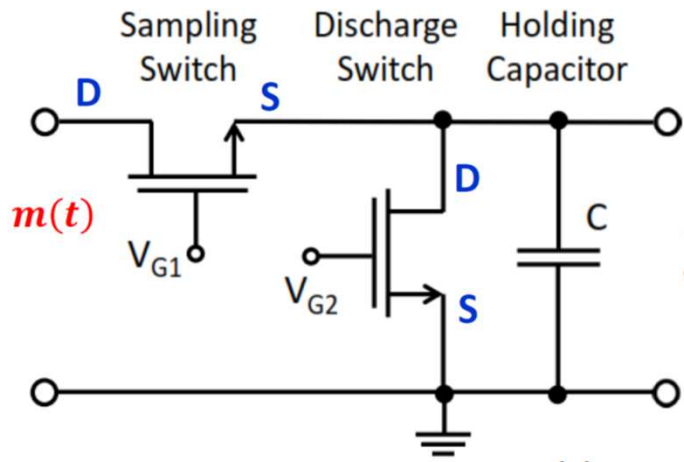


Flat-Topped Sampling

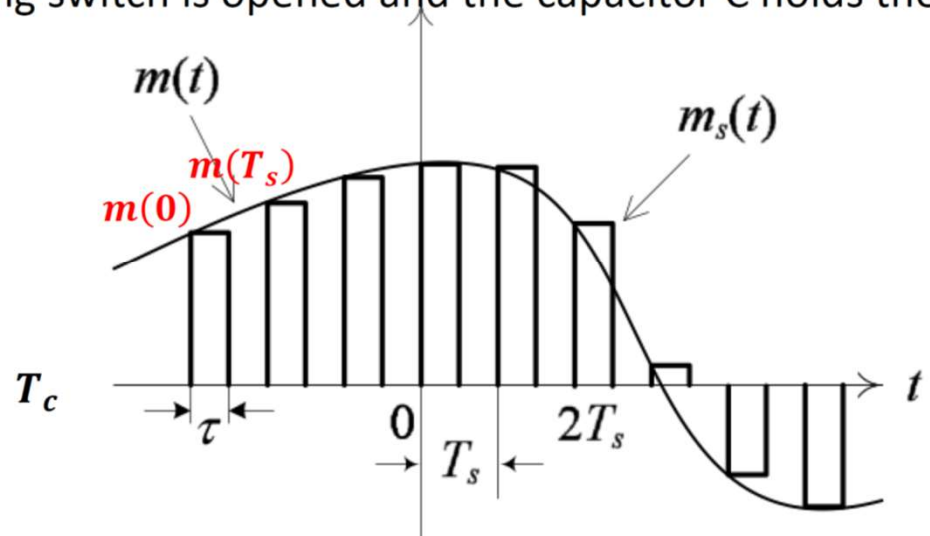
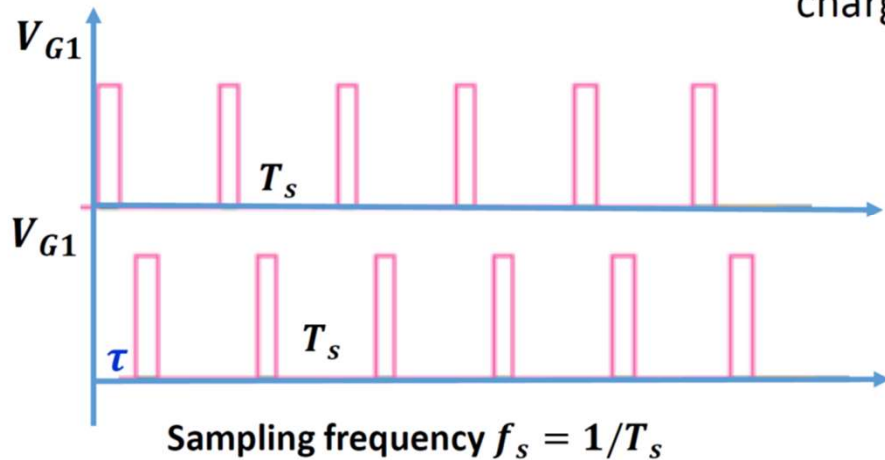
Lecture Outline

- This lecture continues the coverage of the techniques via which a continuous message signal can be sampled, as part of a PCM system
- **Sampling:** is the process by which a continuous time continuous amplitude signal is converted into a discrete time continuous amplitude signal.
- **There are three types of sampling:** Ideal sampling, natural sampling, and flat-topped sampling.
- Ideal sampling, natural sampling, the sampling theorem, and the phenomenon of aliasing were presented in the previous two lectures.
- In this lecture, we address the following topics
 - Flat-topped sampling (sample and hold).
 - Time division multiplexing (TDM)

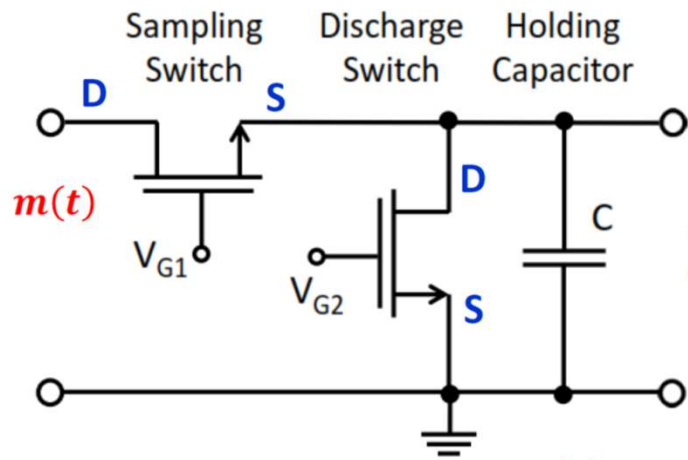
Flat-topped sampling (zero order hold sampling)



- The sample and hold circuit performs the task of sampling.
- The message $m(t)$ is bandlimited to W Hz.
- The sample and hold circuit consists of two field effect transistor (FET) switches and a capacitor.
- The sampling switch is closed for a short duration by a short pulse applied to the gate $G1$ of the transistor. During this period, the capacitor C is quickly charged up to a voltage equal to the instantaneous sample value of the incoming signal $m(t)$.
- The sampling switch is opened and the capacitor C holds the charge.

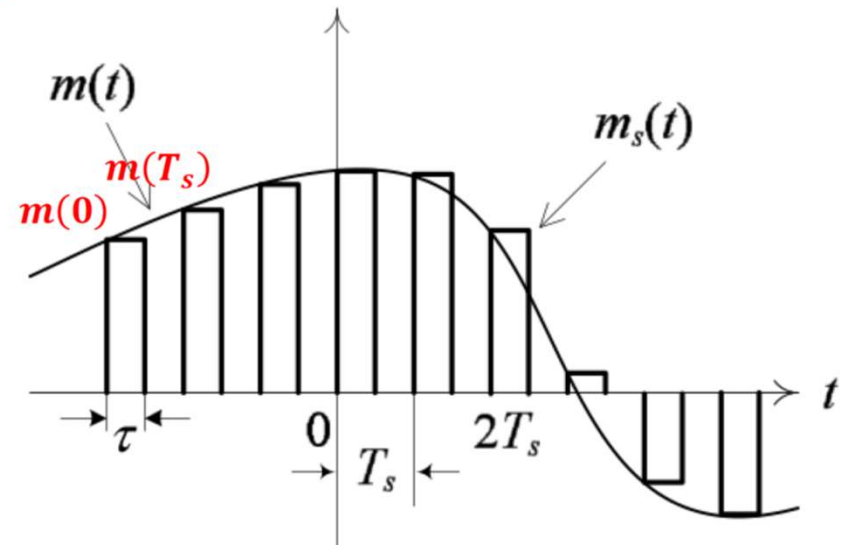
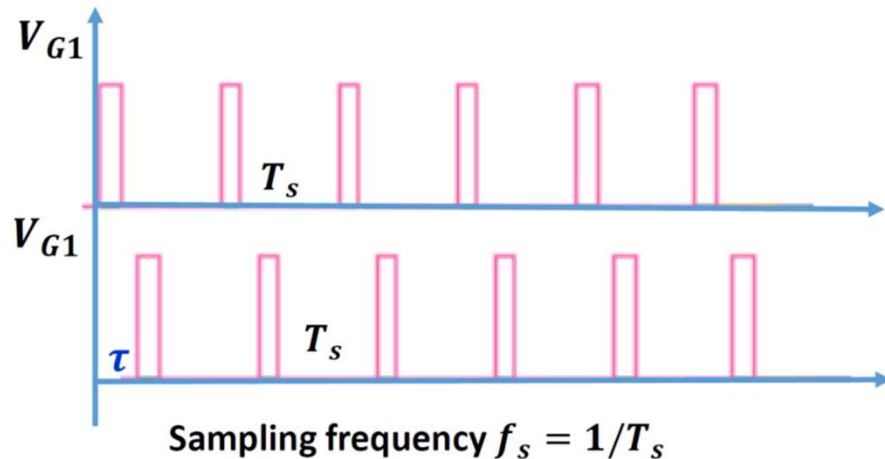


Flat-topped sampling (zero order hold sampling)



- The discharge switch is then closed by a pulse applied to its gate $G2$ at $t = \tau$.
- Due to this, the capacitor C is discharged to zero volts.
- The discharge switch is then opened and thus the capacitor has no voltage.
- Hence the output of the sample and hold circuit consists of a sequence of flat topped samples

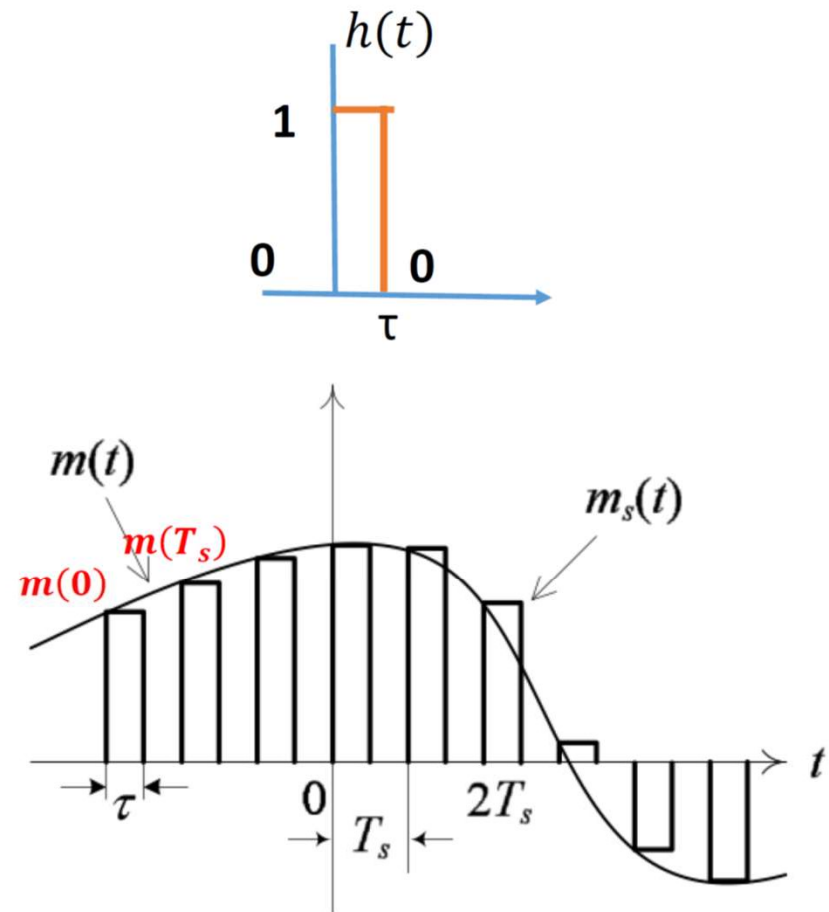
<http://technical123b.blogspot.com/2016/11/pulse-amplitude-modulation-pam.html>



Flat-topped sampling: modeling

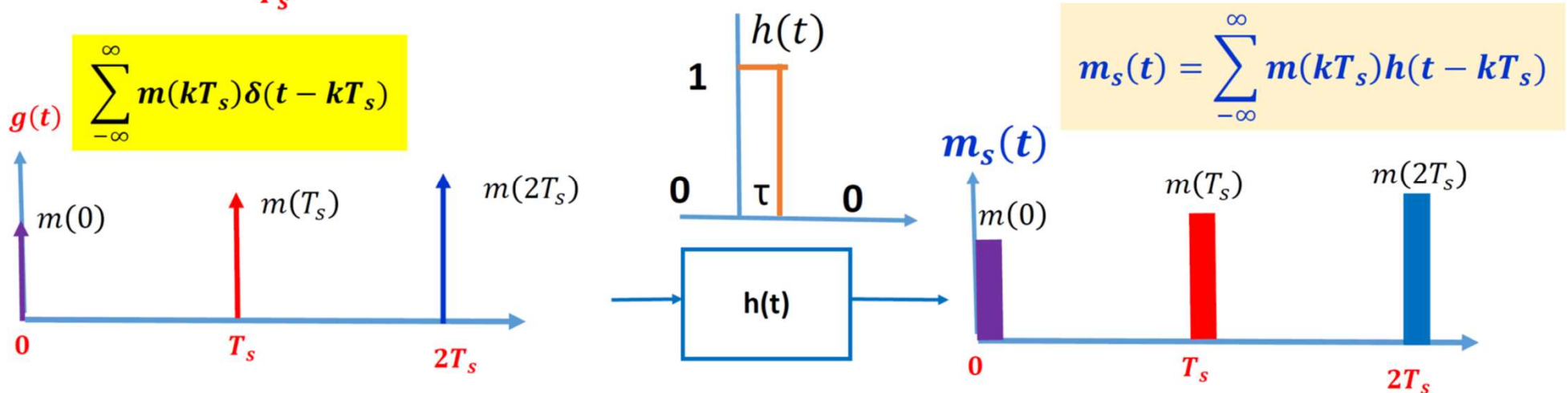
- Let $h(t)$ be a basic unit amplitude pulse defined as:
- $h(t) = \begin{cases} 1 & 0 < t < \tau, \\ 0 & \text{otherwise} \end{cases}$
- In flat-topped sampling, the sampler generates a sequence of equally spaced rectangular pulses whose amplitudes are proportional to the message signal $m(t)$ at the sampling times $m(kT_s)$.
- The sampled signal is represented as

$$m_s(t) = \sum_{-\infty}^{\infty} m(kT_s)h(t - kT_s)$$



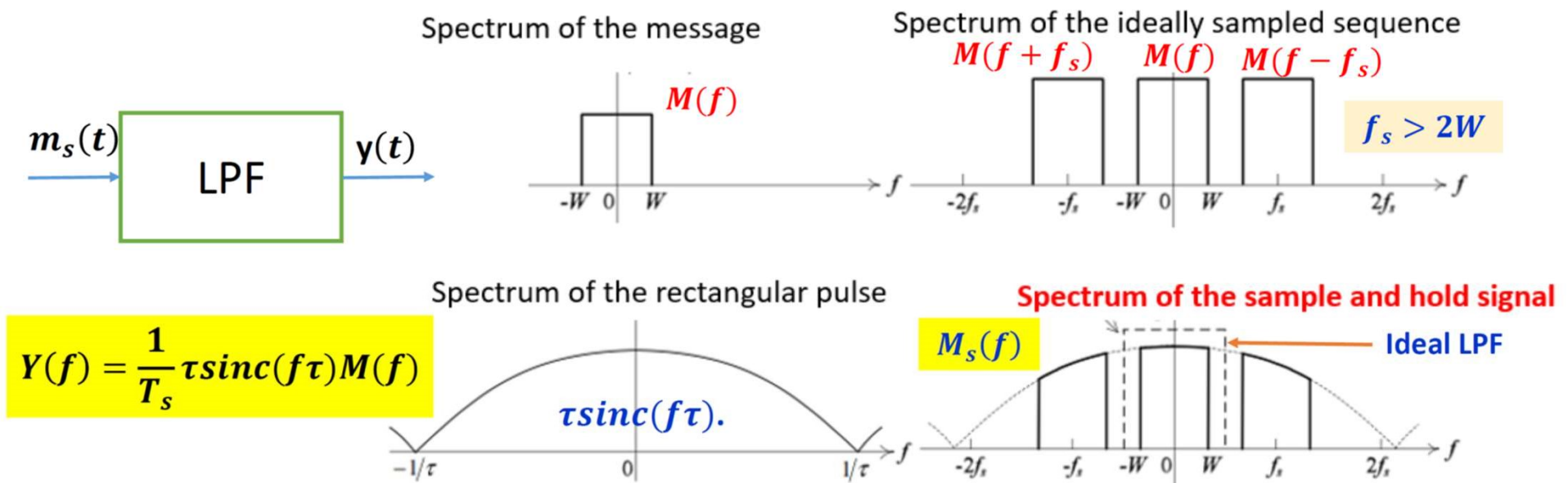
Flat-topped sampling: modeling

- The sampled signal is represented as $m_s(t) = \sum_{-\infty}^{\infty} m(kT_s)h(t - kT_s)$
- Using the identity, $\delta(t - kT_s) * h(t) = h(t - kT_s)$
- Multiplying both sides by $m(kT_s)$ we get, $m(kT_s)\delta(t - kT_s) * h(t) = m(kT_s)h(t - kT_s)$
- Therefore, $m_s(t)$ can be expressed as: $m_s(t) = h(t) * \sum_{-\infty}^{\infty} m(kT_s)\delta(t - kT_s)$
- Taking the Fourier transform, and recognizing that the second term corresponds to an ideally sampled sequence, we get
- $M_s(f) = H(f) \frac{1}{T_s} \sum_{-\infty}^{\infty} M(f - kf_s)$; where $H(f) = \tau \text{sinc}(f\tau)$.



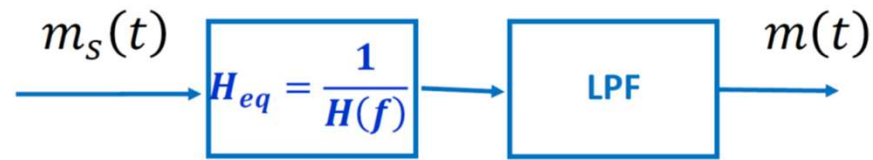
Flat-topped sampling: spectrum and message recovery

- $M_s(f) = H(f) \frac{1}{T_s} \sum_{-\infty}^{\infty} M(f - kf_s)$; $H(f) = \tau \text{sinc}(f\tau)$
- Here, we observe that the spectrum of the flat-topped sampled signal corresponds to the spectrum of the ideally sampled signal multiplied by the Fourier transform of the rectangular pulse $\tau \text{sinc}(f\tau)$.
- When $m_s(t)$ is passed through a low pass filter with bandwidth W , the output is $y(t)$



Flat-topped sampling: equalization

- The LPF filter output is $Y(f) = \frac{1}{T_s} \tau \text{sinc}(f\tau) M(f)$.
- Note that $Y(f) \neq kM(f) \Rightarrow \text{Distortion}$.
- The distortion is due to the finite width τ of the sampling pulse.
- When the message B.W $W \ll 1/\tau$, the distortion is negligible. As τ increases, the distortion becomes more pronounced.
- Even though the signal is sampled at a rate $f_s > 2W$, a distortion is observed.
- A distortion-free signal can be obtained by using an equalizing filter whose transfer function is the reciprocal of the Fourier transform of the unit pulse

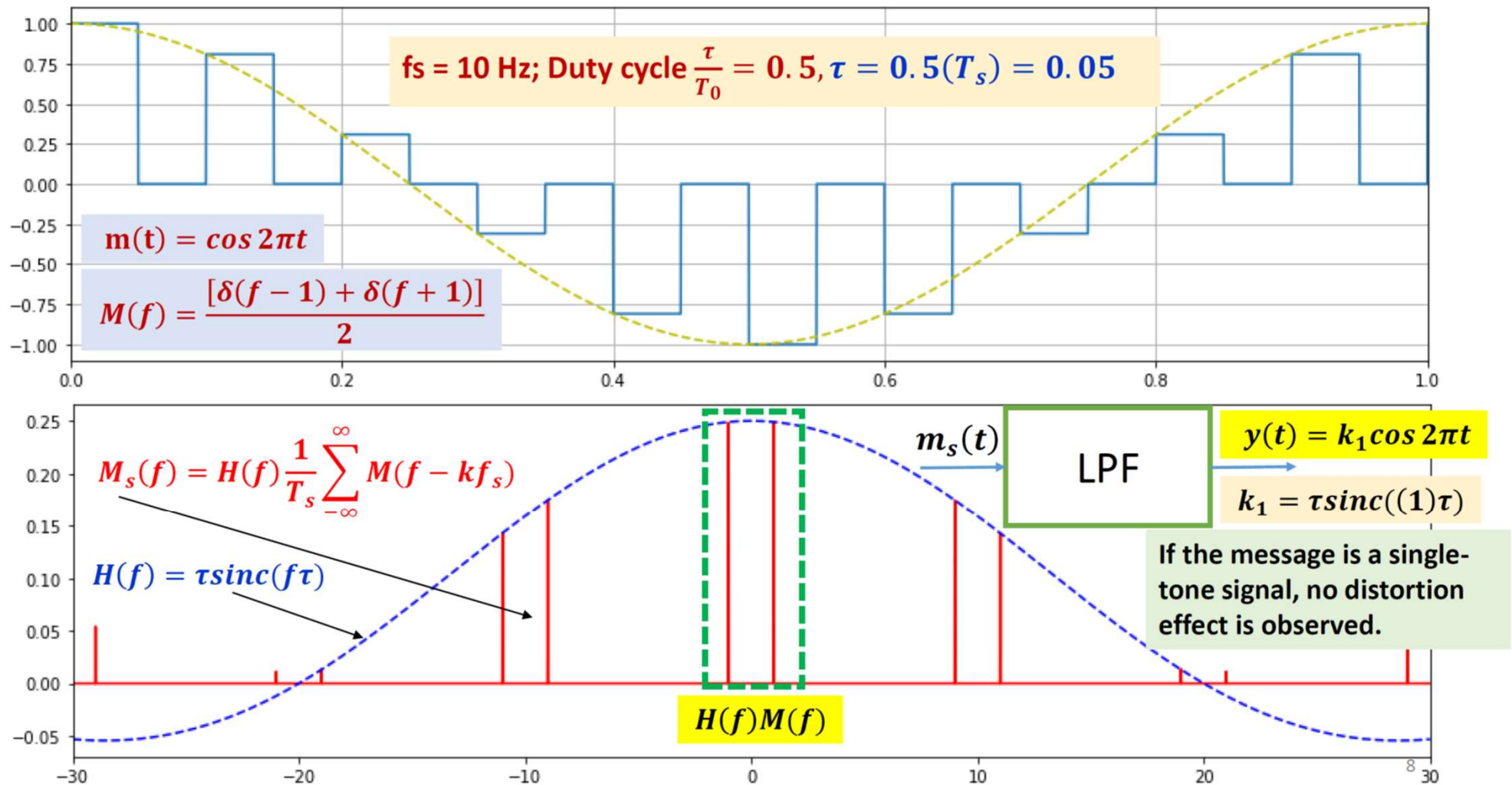


Equalization implemented at the receiver

Here,

- $f_s > 2W$
- $H(f) = A\tau \text{sinc}(f\tau)$

Flat-topped sampling: single tone example

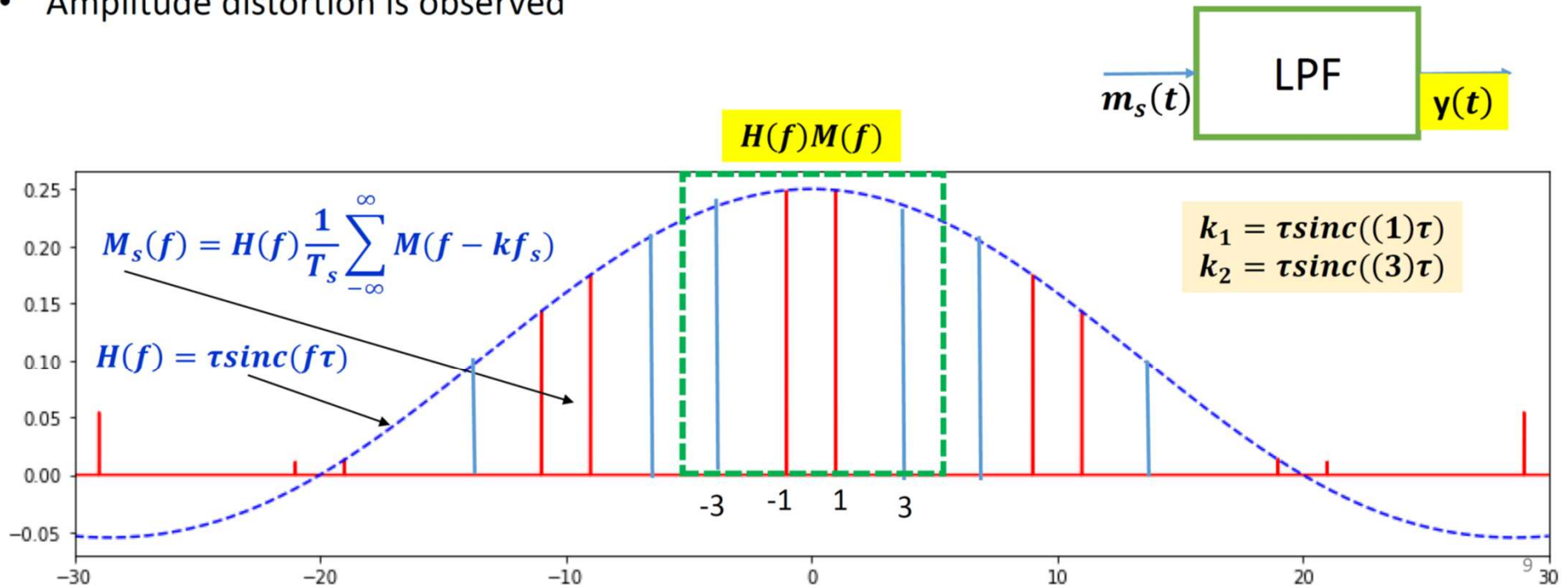


Flat-topped sampling: multi-tone example

Example: Repeat the previous example with $f_s = 10$ Hz; Duty cycle $\frac{\tau}{T_0} = 0.5, \tau = 0.5(T_s) = 0.05$

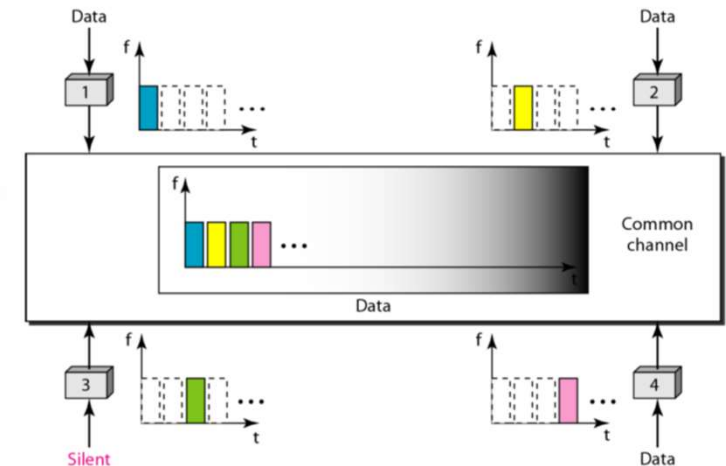
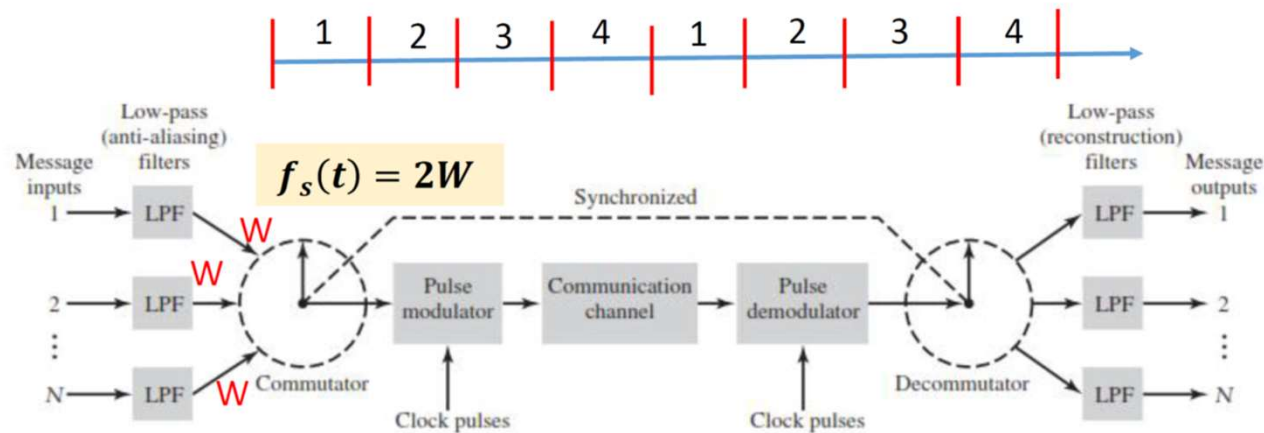
Now, let, $m(t) = \cos 2\pi t + \cos 2\pi 3t$. $M(f) = \frac{[\delta(f-1)+\delta(f+1)]}{2} + \frac{[\delta(f-3)+\delta(f+3)]}{2}$

- The spectrum of the sampled signal is as shown in the figure below.
- The output of the LPF is $y(t) = k_1 \cos 2\pi t + k_2 \cos 2\pi 3t \neq km(t)$
- Amplitude distortion is observed



Time Division Multiplexing (TDM)

- **Time Division Multiplexing (TDM)**: A technique which allows multiple users to use the same channel by assigning each user a portion of the transmission time without interfering with other users.
- Let N be the number of sources. The time axis is divided into N slots and each slot is allocated to a source.
- Each source transmits only during its slot, avoiding the possibility of a collision.
- When a user transmits during its slot, it utilizes the entire B.W. of the channel and this B.W. will be made available to the next user during the succeeding time slot.
- The collection of the N slots is called a **cycle**.
- TDMA requires some form of synchronization.
- The number of signal samples transmitted per second should be larger than the Nyquist rate.



Time Division Multiplexing: Example

$$m_1(t) = \cos 2\pi t \quad m_2(t) = \sin 2\pi t \quad f_s(t) = 30 \quad f_{m1} = f_{m2} = 1$$

