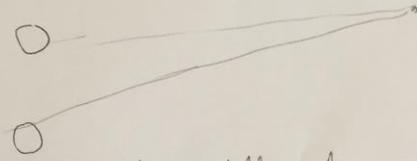
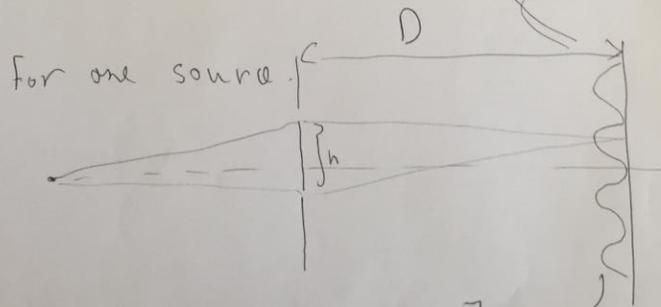
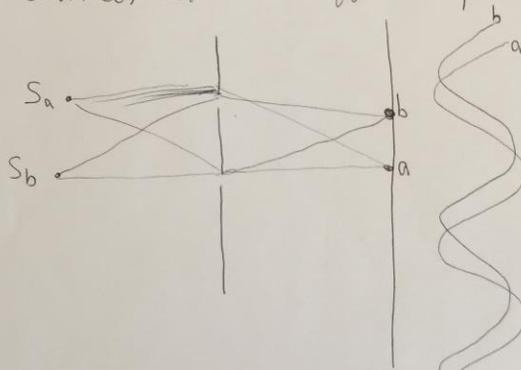


8.5 Young's Two-Slit Setup and Spatial coherence.



Two sources at two different points.



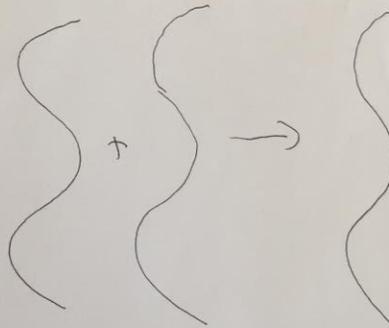
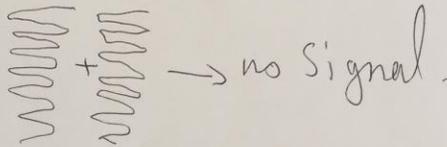
$$I_{\text{tot}}(h) = 2I_0 [1 + \cos(kyh/D)]$$

IF $h \rightarrow$ large, the fringe pattern becomes dense.

(8)



This results in cancellation.



There is interference

9.1 The Eikonal Equation

①

Assume light with one frequency isotropic medium; real refractive index.

From wave equation:

$$\nabla^2 \vec{E}(\vec{r}, t) + \frac{[n(\vec{r})]^2 \omega^2}{c^2} \vec{E}(\vec{r}, t) = 0$$

Note: $n(\vec{r})$ depends on position

By analogy let the trial solution be

$$\vec{E}(\vec{r}, t) = \vec{E}_0(\vec{r}) e^{i[k_{vac} R(\vec{r}) - \omega t]}$$

$$k_{vac} = \frac{\omega}{c} = \frac{2\pi}{\lambda_{vac}}$$

Subbing the solution we get

$$\frac{1}{k_{vac}^2} \nabla^2 \left[\vec{E}_0(\vec{r}) e^{i k_{vac} R(\vec{r})} \right] + [n(\vec{r})]^2 \vec{E}_0(\vec{r}) e^{i k_{vac} R(\vec{r})} = 0$$

In very short λ limit, we get

$$(9.7) \quad \nabla R(\vec{r}) = n(\vec{r}) \hat{S}(\vec{r})$$

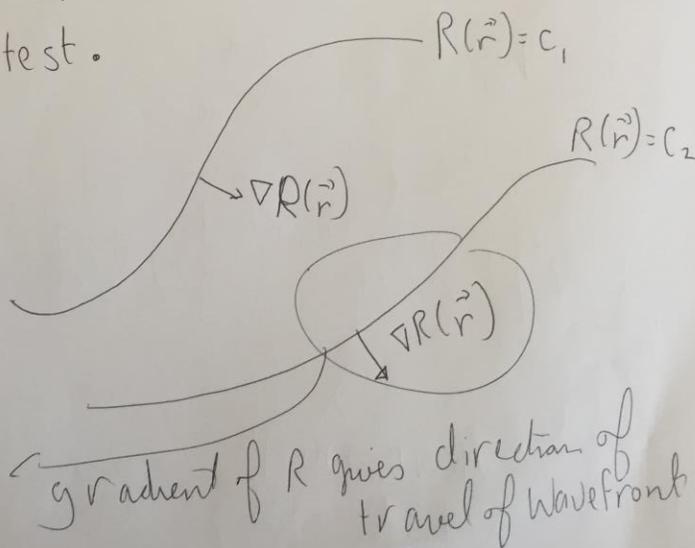
\hat{S} = unit vector in direction of $\nabla R(\vec{r})$ ⁽²⁾
= direction normal to wavefront surfaces.

$$\nabla R(\vec{r}) = n(\vec{r}) \hat{S}(\vec{r}) \quad [\text{Eikonal equation}]$$

What is $R(\vec{r})$? Real Scalar function

$R(\vec{r}) = \text{constant} = \text{Wavefront}$.

This wavefront travels in direction for which $R(\vec{r})$ changes the fastest.



Example 9.1

$$\text{Let } n(y) = n_0 \sqrt{1 + y^2/h^2}$$

Verify that $R(x, y) = n_0(x \pm y^2/2h)$ is a solution to the eikonal equation.

$$\nabla R = n_0 \left(\hat{x} \pm \frac{y}{h} \hat{y} \right)$$

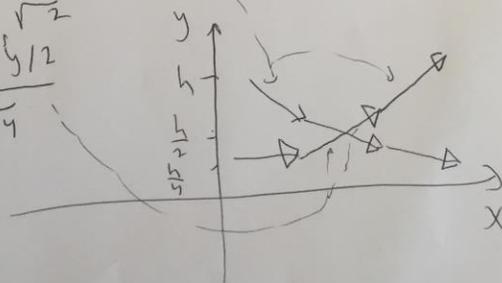
$$\nabla R \cdot \nabla R = n_0^2 \left(1 + \frac{y^2}{h^2} \right) = [n(y)]^2$$

The direction of light propagation is

$$\hat{S}(y) = \frac{\nabla R}{|\nabla R|} = \frac{\hat{x} \pm \hat{y} \frac{y}{h}}{\sqrt{1 + y^2/h^2}}$$

$$\hat{S}(h) = \frac{\hat{x} \pm \hat{y}}{\sqrt{2}}$$

$$\hat{S}(h/2) = \frac{\hat{x} \pm \hat{y}/2}{\sqrt{5/4}}$$



9.2 Fermat's Principle

(4)

Used to find path of rays.

∴  follows a path that takes least time.

$$\text{OPL} \Big|_A^B = \min \left\{ \int_A^B n dl \right\}$$

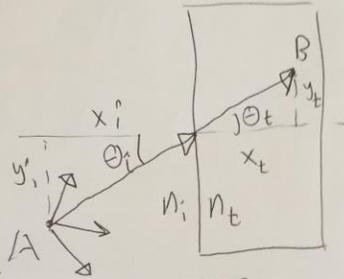
$$\Delta t \Big|_A^B = \int_A^B \frac{dl}{v(\vec{r})} = \int_A^B \frac{dl}{c/n(\vec{r})} = \frac{\text{OPL} \Big|_A^B}{c}$$

∴ To find correct path of light,
we minimize the OPL.

Example 9.2

(5)

Derive Snell's law using Fermat's principle.



$$OPL = n_i \sqrt{x_i^2 + y_i^2} + n_t \sqrt{x_t^2 + y_t^2}$$

This should be minimized.

$$x_i, x_t = \text{fixed.}$$

$$y_{tot} = y_i + y_t = \text{constant.}$$

$$OPL = n_i \sqrt{x_i^2 + y_i^2} + n_t \sqrt{x_t^2 + (y_{tot} - y_i)^2}$$

only variable is y_i

$$\frac{d(OPL)}{dy_i} = n_i \frac{y_i}{\sqrt{x_i^2 + y_i^2}} + n_t \frac{-(y_{tot} - y_i)}{\sqrt{x_t^2 + (y_{tot} - y_i)^2}} = 0$$

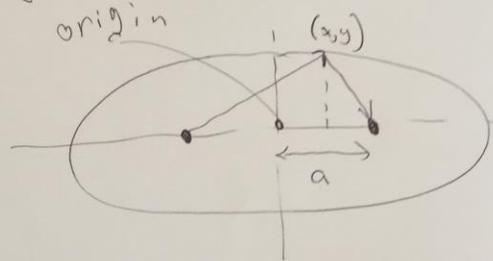
$$\sin \theta_i = \frac{y_i}{\sqrt{x_i^2 + y_i^2}} \quad ; \quad \sin \theta_t = \frac{y_t}{\sqrt{x_t^2 + y_t^2}} \quad (6)$$

$$n_i \sin \theta_i - n_t \sin \theta_t = 0$$

$$n_i \sin \theta_i = n_t \sin \theta_t$$

Example 9.3 Derive equation of curvature⁽⁷⁾

for a reflective surface that causes all rays leaving one point to image to another. (In 2D).



$$\sqrt{(x+a)^2 + y^2} + \sqrt{(x-a)^2 + y^2} = b$$

[after some algebra] [

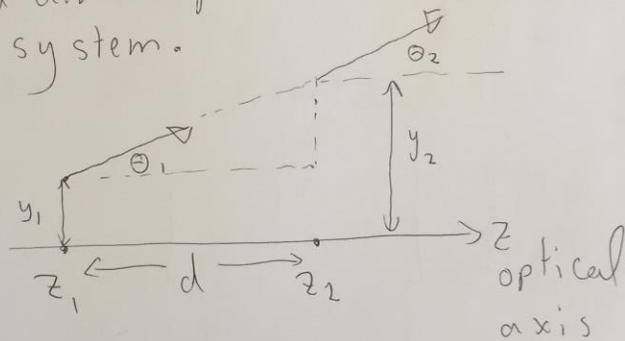
we get

$$\frac{x^2}{\left(\frac{b^2}{4}\right)} + \frac{y^2}{\left(\frac{b^2}{4} - a^2\right)} = 1 ; \text{ ellipse.}$$

9.3 Paraxial Rays and ABCD matrices (8)

- Ray Optics: Describe light as rays and not waves.
Good approximation if $\lambda \ll$ features.

- Paraxial Approximation: rays near and almost parallel to optical axis of system.



$$\sin \theta \approx \theta$$

$$\tan \theta \approx \theta$$

let n be uniform everywhere.

$$\theta_2 = \theta_1$$

$$y_2 = y_1 + d \tan \theta_1 = y_1 + \theta_1 d$$

$$\therefore \begin{bmatrix} y_2 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} 1 & d \\ 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ \theta_1 \end{bmatrix} \quad (9)$$

↑
ABCD matrix for propagation through a distance d .

Example 9.4 let $d = a + b$
show that applying ABCD matrix for \underline{d} , or for \underline{a} then b , gives same result.

$$\begin{bmatrix} y_{\text{mid}} \\ \theta_{\text{mid}} \end{bmatrix} = \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ \theta_1 \end{bmatrix}$$

$$\begin{bmatrix} y_2 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} \begin{bmatrix} y_{\text{mid}} \\ \theta_{\text{mid}} \end{bmatrix}$$

$$\therefore \begin{bmatrix} y_2 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ \theta_1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & a+b \\ 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ \theta_1 \end{bmatrix} \quad \checkmark$$